Commun. Fac. Sci. Univ. Ank. Ser. A1 Math. Stat. Volume 67, Number 1, Pages 248-261 (2018) DOI: 10.1501/Commual_0000000847 ISSN 1303-5991



http://communications.science.ankara.edu.tr/index.php?series=A1

STABILITY CRITERION FOR DIFFERENCE EQUATIONS INVOLVING GENERALIZED DIFFERENCE OPERATOR

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Abstract. In this study, some necessary and sufficient conditions are given for the stability of some class of difference equations including generalized difference operator. For this, Schur-Cohn criteria is used and some examples are given to verify the results obtained.

1. Introduction

Difference equations are the discrete analogues of differential equations and usually describe certain phenomena over the course of time. Difference equations have many applications in variety of disciplines such as economy, mathematical biology, social sciences, physics, etc. Generalized difference equations have special importance in difference equations. In this study some necessary and sufficient conditions are given for the stability of some class of difference equations involving generalized difference operator.

The basic theory of difference equations is based on the difference operator Δ defined as

$$\Delta y(n) = y(n+1) - y(n), \qquad n \in \mathbb{N}$$
(1)

where $\mathbb{N} = \{1, 2, ...\}$.

In [1],[7],[13] authors suggested the definition of Δ as

$$\Delta y(n) = y(n+l) - y(n), \qquad l \in \mathbb{N}. \tag{2}$$

In [14]-[15] authors defined Δ_{α} as

$$\Delta_{\alpha} y(k) = y(k+1) - \alpha y(k) \tag{3}$$

where α is a fixed real constant and $k \in \{n_0, n_0 + 1, ...\}$ and n_0 is a given nonnegative integer.

Received by the editors: July 27, 2016; Accepted: February 02, 2017.

 $2010\ Mathematics\ Subject\ Classification.\quad 39A10,\ 39A30.$

Key words and phrases. Generalized difference operator, Schur Cohn criteria, stability.

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Communications de la Faculté des Sciences de l'Université d'Ankara. Séries A1. Mathematics and Statistics.

Throughout this paper we define the operator $\Delta_{l,a}$ as

$$\Delta_{l,a}y(n) = y(n+l) - ay(n), \qquad n, l \in \mathbb{N}, \ a \in \mathbb{R}. \tag{4}$$

Stability of solutions of linear difference equations requires analysis of root of characteristic equation of difference equations. In [2], [4], [5], [8], [9], [10], [11], [12] authors found some stability results using root analysis. In our study firstly we will consider the asymptotic stability of the zero solution of the difference equation involving generalized difference of the form

$$\Delta_{l,a}^{m}y(n) + r\Delta_{l,a}y(n) + sy(n) = 0 \tag{5}$$

with the initial conditions

$$y(i) = \varphi_i , i = 0, 1, 2, \dots, ml - 1$$
 (6)

where $a, r, s \in \mathbb{R}$, $l, m, n \in \mathbb{N}$. By solution of equation (5) we mean a real sequence y(n) which is defined for $n = 0, 1, 2, \dots, ml - 1$ and reduce equation (5) to an identity over \mathbb{N} . Later we will consider the asymptotic stability of the zero solution of the delay difference equation involving generalized difference of the form

$$\Delta_{l,a}^{m} y(n-l) + r \Delta_{l,a} y(n) + s y(n-l) = 0$$
 (7)

with the initial conditions

$$y(i) = \varphi_i, i = -l, -l + 1, \dots, (m-1)l - 1$$
 (8)

where $a, r, s \in \mathbb{R}$, $l, m, n \in \mathbb{N}$. Similarly by solution of equation (7) we mean a real sequence y(n) which is defined for $n = -l, -l+1, \dots -1, 0, 1 \dots, (m-1)l-1$ and reduce equation (7) to an identity over \mathbb{N} .

Paper is organized as follows: In Section 2 we give some definitions, properties of generalized difference operator and some basic lemmas and theorems. We will give stability results for equations (5) and (7) in section 3. Also we will give illustrative examples which verify the results obtained.

2. Some definitions, auxiliary Lemmas and Theorems

In this section we will give some definitions, auxiliary lemmas and theorems which we use throughout this study. For each positive integer m, we define the iterates $\Delta_{l,a}^m$ by

$$\Delta_{l,a}^m y(n) = \Delta_{l,a} \left(\Delta_{l,a}^{m-1} y(n) \right).$$

Basic property of the operator $\Delta_{l,a}$ is shown below.

Lemma 1. For each positive integer m

$$\Delta_{l,a}^{m} y(n) = \sum_{i=0}^{m} (-1)^{i} {m \choose i} a^{i} y \left(n + (m-i) \, l \right). \tag{9}$$

Definition 1. Let I be some intervals of real numbers and consider the difference equation

$$x_{n+1} = F(x_n, x_{n-1}, ..., x_{n-k})$$
(10)

where F is a function that maps some set I^{k+1} into I. Then a point \bar{x} is called an equilibrium point of equation (10) if

$$x_n = \bar{x} \text{ for all } n \geq -k.$$

[3].

Definition 2. Let \bar{x} be an equilibrium point of equation (10).

(a) An equilibrium point \bar{x} of equation (10) is called locally stable, if for every $\varepsilon > 0$, there exists $\delta > 0$ such that if $\{x_n\}_{n=-k}^{\infty}$ is a solution of equation (10) with

$$|x_{-k} - \bar{x}| + |x_{-k+1} - \bar{x}| + \dots + |x_0 - \bar{x}| < \delta,$$

then

$$|x_n - \bar{x}| < \varepsilon$$
, for all $n \ge 0$.

(b) An equilibrium point \bar{x} of equation (10) is called locally asymptotically stable, if \bar{x} is locally stable, and if, in addition, there exists $\gamma > 0$ such that if $\{x_n\}_{n=-k}^{\infty}$ is a solution of equation (10) with

$$|x_{-k} - \bar{x}| + |x_{-k+1} - \bar{x}| + \dots + |x_0 - \bar{x}| < \gamma,$$

then

$$\lim_{n \to \infty} x_n = \bar{x}.$$

(c) An equilibrium point \bar{x} of equation (10) is called global attractor if, for every solution $\{x_n\}_{n=-k}^{\infty}$ of equation (10) we have

$$\lim_{n \to \infty} x_n = \bar{x}$$

- (d) An equilibrium point \bar{x} of equation (10) is called globally asymptotically stable if \bar{x} is locally stable, and \bar{x} is also a global attractor of equation (10).
- (e)An equilibrium point \bar{x} of equation (10) is called unstable if it is not stable [3].

Consider the linear difference equation

$$x_{n+1} = a_0 x_n + a_1 x_{n-1} + \dots + a_k x_{n-k}$$
(11)

where $a_i \in \mathbb{R}$, $i = 0, 1, ..., k, k \in \mathbb{N}$.

As is customary, a zero solution of (11) is said to be asymptotically stable iff all zeros of the corresponding characteristic equation are in the unit disk. Otherwise the zero solution is called unstable.

As it is well known, the asymptotic stability of the zero solution of the linear difference equation is determined by the location of the roots of the associated characteristic equation

$$\lambda^{k+1} - \sum_{i=0}^{k} a_i \lambda^{k-i} = 0.$$

Thus, for each particular choice of the coefficients a_i , i = 0, ..., k, one can use the so called Schur-Cohn criterion. However, with this method, it is very difficult to get explicit conditions for a general form of (11) depending on the coefficients. This kind of explicit conditions are of special importance in the applications, where the coefficients are meaningful parameters of the model [10].

Definition 3 (Inners of a matrix). The inners of a matrix are the matrix itself and all the matrices obtained by omitting successively the first and the last rows and the first and the last columns [6].

The inners of the following matrix A are shown below.

$$A = \begin{bmatrix} b_{11} & b_{12} & b_{13} & b_{14} & b_{15} \\ b_{21} & b_{22} & b_{23} & b_{24} & b_{25} \\ b_{31} & b_{32} & b_{33} & b_{34} & b_{35} \\ b_{41} & b_{42} & b_{43} & b_{44} & b_{45} \\ b_{51} & b_{52} & b_{53} & b_{54} & b_{55} \end{bmatrix}, \begin{bmatrix} b_{22} & b_{23} & b_{24} \\ b_{32} & b_{33} & b_{34} \\ b_{42} & b_{43} & b_{44} \end{bmatrix}, [b_{33}]$$

Definition 4. A matrix is said to be innerwise if the determinants of all of its inners are positive [6].

Consider the linear homogeneous difference equation with constant coefficient

$$y(n+k) + p_1 y(n+k-1) + p_2 y(n+k-2) + \dots + p_k y(n) = 0$$
 (12)

where p_1, p_2, \dots, p_k are real numbers. Then the zero solution of (12) is asymptotically stable iff $|\lambda| < 1$ for all characteristic roots λ of (12), that is for every zero λ of the characteristic polynomial

$$p(\lambda) = \lambda^k + p_1 \lambda^{k-1} + p_2 \lambda^{k-2} + \dots + p_k.$$
(13)

Now the following theorem gives a necessary and sufficient conditions for the zeros of the polynomial (13) lie inside the unit disk $|\lambda| < 1$ [6, sec 5.1, page 246].

Theorem 1 (Schur-Cohn Criterion). The zeros of the characteristic polynomial (7) lie inside the unit disk if and only if the following hold:

$$p(1)>0 \ , \ (-1)^k p(-1)>0$$
 and $(k-1)\times (k-1) \ matrices$

$$A_{k-1}^{\pm} = \begin{bmatrix} 1 & 0 & \cdots & 0 & 0 \\ p_1 & 1 & \cdots & 0 & 0 \\ \vdots & & & & \vdots \\ p_{k-3} & p_{k-4} & \cdots & 1 & 0 \\ p_{k-2} & p_{k-3} & \cdots & p_1 & 1 \end{bmatrix} \pm \begin{bmatrix} 0 & 0 & \cdots & 0 & p_k \\ 0 & 0 & \cdots & p_k & p_{k-1} \\ \vdots & \vdots & & & \vdots \\ 0 & p_k & \cdots & & p_3 \\ p_k & p_{k-1} & \cdots & p_3 & p_2 \end{bmatrix}$$
(14)

are innervise [6].

In [6] using the Schur-Cohn Criterion (Theorem 1), necessary and sufficient conditions are given on the coefficients p_i such that the zero solution of (12) is asymptotically stable. Some compact necessary and sufficient conditions for the zero solutions of (12) to be asymptotically stable are available for lower order difference equations. Hence conditions for second and third order difference equations are given below.

For the second order difference equation

$$x(n+2) + p_1 x(n+1) + p_2 x(n) = 0 (15)$$

the characteristic polynomial is

$$p(\lambda) = \lambda^2 + p_1 \lambda + p_2.$$

The characteristic roots are inside the unit disk if and only if

$$p(1) = 1 + p_1 + p_2 > 0, (16)$$

$$p(-1) = 1 - p_1 + p_2 > 0 (17)$$

and

$$A_1^{\pm} = 1 \pm p_2 > 0. \tag{18}$$

It follows from (16) and (17) that $1 + p_2 > |p_1|$ and $1 + p_2 > 0$. Now (18) reduces to $1 - p_2 > 0$. Hence zero solution of (15) is asymptotically stable if and only if

$$|p_1| < 1 + p_2 < 2. (19)$$

For the third order difference equation

$$x(n+3) + p_1x(n+2) + p_2x(n+1) + p_3x(n) = 0$$
(20)

the characteristic polynomial is

$$p(\lambda) = \lambda^3 + p_1 \lambda^2 + p_2 \lambda + p_3 = 0.$$

The Schur-Cohn criterion are

$$1 + p_1 + p_2 + p_3 > 0, (21)$$

$$(-1)^{3} \left[-1 + p_1 - p_2 + p_3 \right] = 1 - p_1 + p_2 - p_3 > 0 \tag{22}$$

and

$$|A_2^+| = \left| \begin{bmatrix} 1 & 0 \\ p_1 & 1 \end{bmatrix} + \begin{bmatrix} 0 & p_3 \\ p_3 & p_2 \end{bmatrix} \right| = \left| \begin{array}{cc} 1 & p_3 \\ p_1 + p_3 & 1 + p_2 \end{array} \right| > 0.$$
 (23)

Thus

$$1 + p_2 - p_1 p_3 - p_3^2 > 0 (24)$$

and

$$|A_2^-| = \left| \begin{bmatrix} 1 & 0 \\ p_1 & 1 \end{bmatrix} - \begin{bmatrix} 0 & p_3 \\ p_3 & p_2 \end{bmatrix} \right| = \left| \begin{array}{cc} 1 & p_3 \\ p_1 - p_3 & 1 - p_2 \end{array} \right| > 0.$$
 (25)

Hence

$$1 - p_2 + p_1 p_3 - p_3^2 > 0. (26)$$

Using (21), (22), (24), (26) a necessary and sufficient condition for the zero solution of (20) to be asymptotically stable is concluded as

$$|p_1 + p_3| < 1 + p_2 \text{ and } |p_2 - p_1 p_3| < 1 - p_3^2$$
 [6]. (27)

3. Main Results

In this section we will give some stability results for the difference equation (5) with initial conditions (6), the difference equation (7) with initial conditions (8) and illustrative examples. For this we will use Schur-Cohn criterion .

Theorem 2. Consider the difference equation (5) with initial conditions (6). Then the following statements are equivalent.

- (a) The zero solution of (5) is asymptotically stable.
- (b) Followings hold;

$$\sum_{i=0}^{m-2} (-1)^i \binom{m}{i} a^i + (-1)^{m-1} m a^{m-1} + r + (-1)^m a^m - ar + s > 0, \tag{28}$$

$$\sum_{i=0}^{m-2} {m \choose i} a^i + (-1)^{m+1} \left[(-1)^{m-1} m a^{m-1} + r \right] +$$

$$(-1)^m \left[(-1)^m a^m - ar + s \right] > 0,$$
(29)

$$A_{m-1}^{\pm} = \begin{bmatrix} 1 & 0 & \dots & 0 & 0 \\ -\binom{m}{1}a & 1 & 0 & \dots & 0 \\ \binom{m}{2}a^2 & -\binom{m}{1}a & 1 & 0 \dots & 0 \\ \vdots & & & & & & \\ (-1)^{m-2}\binom{m}{m-2}a^{m-2} & (-1)^{m-3}\binom{m}{m-3}a^{m-3} & \dots & 1 \end{bmatrix} \pm \\ \begin{bmatrix} 0 & 0 & \dots & 0 & (-1)^m a^m - ar + s \\ 0 & \dots & 0 & (-1)^m a^m - ar + s & (-1)^{m-1}a^{m-1} + r \\ \vdots & & & & & \\ (-1)^m a^m - ar + s & (-1)^{m-1}a^{m-1} + r & \dots & & & \\ \binom{m}{2}a^2 & \end{bmatrix}$$

matrices are innerwise. Here entries of A_{m-1}^{\pm} is formed by the coefficients of p(t) where

$$p(t) = \sum_{i=0}^{m-2} (-1)^i \binom{m}{i} a^i t^{m-i} + \left((-1)^{m-1} m a^{m-1} + r \right) t + (-1)^m a^m - ar + s.$$

Proof. $(a) \Longrightarrow (b)$. Suppose that zero solution of (5) is asymptotically stable. Since (5) is a linear difference equation with constant coefficients then the roots of the corresponding characteristic equation must be in the unit disk. Using Lemma 1 we reduce (5) to

$$\sum_{i=0}^{m} (-1)^{i} {m \choose i} a^{i} y \left(n + (m-i) l \right) + ry(n+l) - ary(n) + sy(n) = 0.$$
 (31)

Rearranging (31) we get

$$\sum_{i=0}^{m-2} (-1)^{i} {m \choose i} a^{i} y \left(n + (m-i) l\right) + \left((-1)^{m-1} m a^{m-1} + r \right) y \left(n + l\right) +$$

$$((-1)^m a^m - ar + s) y(n) = 0. (32)$$

The characteristic equation of (32) is

$$\sum_{i=0}^{m-2} (-1)^i \binom{m}{i} a^i \lambda^{(m-i)l} + \left((-1)^{m-1} m a^{m-1} + r \right) \lambda^l + (-1)^m a^m - ar + s = 0.$$
 (33)

Getting $\lambda^l = t$ in (33)we obtain

$$\sum_{i=0}^{m-2} (-1)^i \binom{m}{i} a^i t^{m-i} + \left((-1)^{m-1} m a^{m-1} + r \right) t + (-1)^m a^m - ar + s = 0.$$
 (34)

In (34)taking

$$p(t) = \sum_{i=0}^{m-2} (-1)^i \binom{m}{i} a^i t^{m-i} + \left((-1)^{m-1} m a^{m-1} + r \right) t + (-1)^m a^m - ar + s, (35)$$

 $p_i = (-1)^i {m \choose i} a^i$ for $0 \le i \le m-2$, $p_{m-1} = ((-1)^{m-1} m a^{m-1} + r)$ and $p_m = (-1)^i {m \choose i} a^i$ $(-1)^m a^m - ar + s$ in view of Theorem 1 following conditions are necessary and sufficient condition for the roots of polynomial in (35) to be inside the unit disk |t| < 1.

$$p(1) = \sum_{i=0}^{m-2} (-1)^{i} \binom{m}{i} a^{i} + (-1)^{m-1} m a^{m-1} + r + (-1)^{m} a^{m} - ar + s > 0,$$

$$(-1)^{m} p(-1) = (-1)^{m} \sum_{i=0}^{m-2} (-1)^{i} \binom{m}{i} a^{i} (-1)^{m-i} + (-1)^{m} \left[(-1)^{m-1} m a^{m-1} + r \right] (-1) +$$

$$(-1)^{m} \left[(-1)^{m} a^{m} - ar + s \right]$$

$$= \sum_{i=0}^{m-2} \binom{m}{i} a^{i} + (-1)^{m+1} \left[(-1)^{m-1} m a^{m-1} + r \right] + (-1)^{m} \left[(-1)^{m} a^{m} - ar + s \right] > 0,$$

and the matrices A_{m-1}^{\pm} whose entries are formed the coefficients of p(t) must be innerwise where

 $(b) \Longrightarrow (a)$. If (28), (29) and (30) hold then for characteristic polynomial of (5), conditions of Schur-Cohn criteria are satisfied. So roots of characteristic polynomial be inside the unit disk. Hence the zero solution of (5) is asymptotically stable. \square

Corollary 1. Consider the difference equation involving generalized difference

$$\Delta_{l,a}^2 y(n) + r \Delta_{l,a} y(n) + s y(n) = 0$$
(36)

with the initial conditions

$$y(i) = \varphi_i, i = 0, 1, 2, \dots, 2l - 1$$
 (37)

where $a, r, s \in \mathbb{R}$, $l, n \in \mathbb{N}$. Then the following statements are equivalent.

- (a) The zero solution of (36) is asymptotically stable.
- (b) $|r-2a| < a^2 ar + s + 1 < 2$ holds.

Proof. $(a) \Longrightarrow (b)$. Suppose that the zero solution of (36) is asymptotically stable. For m=2 equation (5) reduces to equation (36) which is equivalent to

$$y(n+2l) + (r-2a)y(n+l) + (a^2 - ar + s)y(n) = 0.$$
(38)

In view of Theorem 2 and (19), the roots of the characteristic polynomial of (38) be inside the unit disk $|\lambda| < 1$ if and only if

$$|r - 2a| < a^2 - ar + s + 1 < 2 (39)$$

holds. Hence (b) is satisfied.

(b) \implies (a). If $|r-2a| < a^2 - ar + s + 1 < 2$ holds then for characteristic polynomial of (36), conditions of Schur-Cohn criteria are satisfied. So roots of characteristic polynomial be inside the unit disk. Hence the zero solution of (36) is asymptotically stable.

Example 1. Consider the generalized difference equation of the form

$$\Delta_{4,1/2}^2 y(n) + 11/6\Delta_{4,1/2} y(n) + 5/6y(n) = 0 \tag{40}$$

where l = 4, a = 1/2, r = 11/6, s = 5/6. For m = 2 all the conditions of Theorem 2 are satisfied. Hence the zero solution of equation (40) is asymptotically stable.

Corollary 2. Consider the difference equation involving generalized difference

$$\Delta_{l,a}^3 y(n) + r \Delta_{l,a} y(n) + s y(n) = 0 \tag{41}$$

with the initial conditions

$$y(i) = \varphi_i \text{ for } i = 0, 1, 2, \dots, 3l - 1$$
 (42)

where $a, r, s \in \mathbb{R}$, $n, l \in \mathbb{N}$. Then the following statements are equivalent.

- (a) The zero solution of (41) is asymptotically stable. (b) $\left|-3a+s-ar-a^3\right|<1+3a^2+r$ and $\left|3a^2+r+3as-3a^2r-3a^4\right|<1 (s-ar-a^3)^2$ hold.

Proof. $(a) \Longrightarrow (b)$. Suppose that the zero solution of (41) is asymptotically stable. For m=3 equation (5) reduces to equation (41) which is equivalent to

$$y(n+3l) - 3ay(n+2l) + (3a^2 + r)y(n+l) + (s - ar - a^3)y(n) = 0.$$
 (43)

In view of Theorem 2 and (27), the roots of the characteristic polynomial of (43) be inside the unit disk $|\lambda| < 1$ if and only if

$$\left| -3a + s - ar - a^{3} \right| < 1 + 3a^{2} + r \tag{44}$$

and

$$\left|3a^2 + r + 3as - 3a^2r - 3a^4\right| < 1 - \left(s - ar - a^3\right)^2 \tag{45}$$

hold. Hence (b) is satisfied.

$$(b) \Longrightarrow (a)$$
. Proof is same as in proof of Corollary 1.

Example 2. Consider the generalized difference equation of the form

$$\Delta_{3,1/3}^3 y(n) - 1/36 \Delta_{3,1/3} y(n) = 0, \tag{46}$$

where l = 3, a = 1/3, r = -1/36, s = 0. For m = 3 all the conditions of Theorem 2 are satisfied. Hence the zero solution of equation (46) is asymptotically stable.

Theorem 3. Consider the delay difference equation(7) with initial conditions (8). Then the following statements are equivalent.

- (a) The zero solution of (7) is asymptotically stable.
- (b) Followings hold;

$$p(1) = \sum_{i=0}^{m-3} (-1)^i \binom{m}{i} a^i + (-1)^{m-2} \binom{m}{2} a^{m-2} + r + (-1)^m m a^{m-1}$$

$$-ar + (-1)^m a^m + s > 0, (47)$$

$$(-1)^m p(-1) = \sum_{i=0}^{m-3} {m \choose i} a^i + (-1)^m \left[(-1)^{m-2} {m \choose 2} a^{m-2} + r \right] +$$

$$(-1)^{m+1} \left[(-1)^m m a^{m-1} - ar \right] + a^m + (-1)^m s > 0, \tag{48}$$

$$A_{m-1}^{\pm} = \begin{bmatrix} 1 & 0 & \dots & 0 & 0 \\ -\binom{n}{1}a & 1 & 0 & \dots & 0 \\ \binom{m}{2}a^2 & -\binom{m}{1}a & 1 & 0 \dots & 0 \\ \vdots & & & & & & \\ (-1)^{m-2}\binom{m}{m-2}a^{m-2} + r & (-1)^{m-3}\binom{m}{m-3}a^{m-3} & \dots & 1 \end{bmatrix} \pm \begin{bmatrix} 0 & 0 & \dots & 0 & (-1)^m a^m + s \\ 0 & \dots & 0 & (-1)^m a^m + s & (-1)^{m-1} ma^{m-1} - ar \\ \vdots & & & & & \\ 0 & & (-1)^m a^m + s & & & \\ (-1)^m a^m + s & (-1)^{m-1} ma^{m-1} - ar & \dots & & & \\ \begin{pmatrix} m \\ 2 \end{pmatrix} a^2 \end{bmatrix}$$

matrices are innerwise. Here entries of A_{m-1}^{\pm} is formed by the coefficients of p(t) where

$$p(t) = \sum_{i=0}^{m-3} (-1)^i \binom{m}{i} a^i t^{m-i} + \left((-1)^{m-2} \binom{m}{2} a^{m-2} + r \right) t^2 + \left((-1)^m m a^{m-1} - ar \right) t + (-1)^m a^m + s.$$
 (50)

Proof. $(a) \Longrightarrow (b)$. Suppose that the zero solution of (7) is asymptotically stable. Since (7) is a linear difference equation with constant coefficients then the roots of the corresponding characteristic equation must be in the unit disk. Using Lemma 1, we reduce (7) to

$$\sum_{i=0}^{m} (-1)^{i} {m \choose i} a^{i} y \left(n + (m-1-i) l \right) + ry(n+l) - ary(n) + sy(n-l) = 0, \quad (51)$$

rearranging (51) we obtain

$$\sum_{i=0}^{m-3} (-1)^i \binom{m}{i} a^i y \left(n + (m-1-i)l\right) + \left((-1)^{m-2} \binom{m}{2} a^{m-2} + r\right) y \left(n+l\right) + \left((-1)^{m-1} m a^{m-1} - ar\right) y(n) + \left((-1)^m a^m + s\right) y(n-l) = 0.$$
 (52)

The characteristic equation of (52) is

$$\sum_{i=0}^{m-3} (-1)^i \binom{m}{i} a^i \lambda^{(m-i)l} + \left((-1)^{m-2} \binom{m}{2} a^{m-2} + r \right) \lambda^{2l} + \left((-1)^m m a^{m-1} - ar \right) \lambda^l + (-1)^m a^m + s = 0.$$
 (53)

Getting $\lambda^l = t$ we obtain

$$\sum_{i=0}^{m-3} (-1)^i \binom{m}{i} a^i t^{m-i} + \left((-1)^{m-2} \binom{m}{2} a^{m-2} + r \right) t^2 + \left((-1)^m m a^{m-1} - ar \right) t + (-1)^m a^m + s = 0.$$
 (54)

In (54)taking

$$p(t) = \sum_{i=0}^{m-3} (-1)^i \binom{m}{i} a^i t^{m-i} + \left((-1)^{m-2} \binom{m}{2} a^{m-2} + r \right) t^2 + \left((-1)^m m a^{m-1} - ar \right) t + (-1)^m a^m + s, \tag{55}$$

 $p_i = (-1)^i \binom{m}{i} a^i$ for $0 \le i \le m-3$, $p_{m-2} = \left((-1)^{m-2} \binom{m}{2} a^{m-2} + r \right)$, $p_{m-1} = (-1)^m m a^{m-1} - ar$ and $p_m = (-1)^m a^m + s$ in view of Theorem 1 following conditions are necessary and sufficient condition for the roots of polynomial (55) to be inside the unit disk |t| < 1.

$$\begin{split} p(1) &= \sum_{i=0}^{m-3} \left(-1\right)^i \binom{m}{i} a^i + \left(-1\right)^{m-2} \binom{m}{2} a^{m-2} + r + \left(-1\right)^m m a^{m-1} - a r + \left(-1\right)^m a^m + s > 0, \\ &\left(-1\right)^m p(-1) = \sum_{i=0}^{m-3} \binom{m}{i} a^i + \left(-1\right)^m \left[\left(-1\right)^{m-2} \binom{m}{2} a^{m-2} + r \right] + \\ &\left(-1\right)^{m+1} \left[\left(-1\right)^m m a^{m-1} - a r \right] + a^m + \left(-1\right)^m s > 0, \end{split}$$

and the matrices A_{m-1}^{\pm} constructed with the coefficients of p(t) must be innerwise where

$$A_{m-1}^{\pm} = \begin{bmatrix} 1 & 0 & \dots & 0 & 0 \\ -\binom{m}{1}a & 1 & 0 & \dots & 0 \\ \binom{m}{2}a^2 & -\binom{m}{1}a & 1 & 0 \dots & 0 \\ \vdots & & & & & & \\ (-1)^{m-2}\binom{m}{m-2}a^{m-2} + r & (-1)^{m-3}\binom{m}{m-3}a^{m-3} & \dots & 1 \end{bmatrix} \pm \\ \begin{bmatrix} 0 & 0 & \dots & 0 & (-1)^m a^m + s \\ 0 & \dots & 0 & (-1)^m a^m + s & (-1)^{m-1} ma^{m-1} - ar \\ \vdots & & & & & \\ 0 & (-1)^m a^m + s & (-1)^{m-1} ma^{m-1} - ar & \dots & \binom{m}{2}a^2 \end{bmatrix}.$$

Since $|t| = |\lambda^l| < 1$ and l > 0 we can see that $|\lambda| < 1$. Hence (b) is satisfied. $(b) \Longrightarrow (a)$. Proof is same as in proof of theorem 2.

Corollary 3. Consider the generalized difference equation involving generalized

difference

$$\Delta_{l,a}^{2}y(n-l) + r\Delta_{l,a}y(n) + sy(n-l) = 0$$
(56)

with the initial conditions

$$y(i) = \varphi_i, i = -l, -l + 1, \dots, l - 1$$
 (57)

where $a, r, s, \in \mathbb{R}$, $r \neq -1$, $l, n \in \mathbb{N}$. Then the following statements are equivalent.

(a) The zero solution of (56) is asymptotically stable.

(b)
$$\left| a \left(1 + \frac{1}{r+1} \right) \right| < \frac{a^2 + s}{r+1} + 1 < 2 \text{ holds.}$$

Proof. (a) \Longrightarrow (b). Suppose that the zero solution of (56) is asymptotically stable. For m=2 equation (7) reduces to equation (56). Using definition of $\Delta_{a,l}$ (56) reduces to

$$(r+1)y(n+l) + (-ar-2a)y(n) + (a^2+s)y(n-l) = 0, r \neq -1,$$
 (58)

which is equivalent to

$$y(n+l) - a\left(1 + \frac{1}{r+1}\right)y(n) + \left(\frac{a^2 + s}{r+1}\right)y(n-l) = 0.$$
 (59)

In view of Theorem 3 and (19), the roots of the characteristic polynomial of (59) be inside the unit disk $|\lambda| < 1$ if and only if

$$\left| a \left(1 + \frac{1}{r+1} \right) \right| < \frac{a^2 + s}{r+1} + 1 < 2 \tag{60}$$

holds. Hence (b) is satisfied.

$$(b) \Longrightarrow (a)$$
. Proof is same as in proof of Corollary 1.

Example 3. Consider the generalized difference equation of the form

$$\Delta_{5,1/6}^2 y(n-5) - 3/5 \Delta_{5,1/6} y(n) + 1/180 y(n-5) = 0, \tag{61}$$

where l=5, a=1/6, r=-3/5, s=1/180. For m=2 all the conditions of Theorem 3 are satisfied. Hence the zero solution of equation (61) is asymptotically stable.

4. Conclusions

In this paper using Schur-Cohn criterion we investigated the asymptotic stability of difference equations involving generalized difference operator $\Delta_{l,a}$. If the linear difference equation with constant coefficients is lower order then some compact conditions can be given for zeros of corresponding characteristic polynomials to be inside the unit disk. But in the higher order case such conditions are very complicated. In Theorem 2-3 the general case is given. In corollaries although the difference equations are higher order we give some compact necessary and sufficient conditions for asymptotic stability of zero solution.

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