

ON DOUGLAS SPACES WITH VANISHING $\bar{\mathbf{E}}$ -CURVATURE

A. TAYEBI AND E. PEYGHAN

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ABSTRACT. In this paper, we prove that every compact Douglas space is a Berwald space, when the mean Berwald curvature is covariantly constant along all horizontal directions on the slit tangent bundle.

1. INTRODUCTION

There are two well-known projective invariants of Finsler metrics namely, Douglas curvature [8] and Weyl curvature [18]. The Douglas curvature is a non-Riemannian projective invariant constructed from the Berwald curvature. The notion of Douglas curvature was proposed by Bácsó and Matsumoto as a generalization of Berwald curvature [4][11].

On the other hand, there are several important non-Riemannian quantities such as the Cartan torsion \mathbf{C} , the Berwald curvature \mathbf{B} , the mean Berwald curvature \mathbf{E} and the Landsberg curvature \mathbf{L} , etc [16]. They all vanish for Riemannian metrics, hence they are said to be non-Riemannian.

The study shows that the above mentioned non-Riemannian quantities are closely related to the Douglas metrics, namely Bácsó-Matsumoto proved that every Douglas metric with vanishing Landsberg curvature is a Berwald metric [3]. Is there any other interesting non-Riemannian quantity with such property? In [12], Shen find a new non-Riemannian quantity for Finsler metrics that is closely related to the \mathbf{E} -curvature and call it $\bar{\mathbf{E}}$ -curvature. Recall that $\bar{\mathbf{E}}$ is obtained from the mean Berwald curvature by the covariant horizontal differentiation along geodesics.

In this paper, we prove that every compact Douglas space with vanishing $\bar{\mathbf{E}}$ -curvature is a Berwald space. More precisely, we prove the following.

Theorem 1.1. *Let (M, F) be a complete Douglas space with bounded Cartan torsion. Suppose that $\bar{\mathbf{E}}$ -curvature of F is vanishing. Then F reduces to a Berwald metric. In particular, every compact Douglas space with $\bar{\mathbf{E}} = 0$ is a Berwald space.*

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The completeness in Theorem 1.1, can not be dropped. Consider following Finsler metric on the unit ball $\mathbb{B}^n \subset \mathbb{R}^n$,

$$F(y) := \frac{\sqrt{|y|^2 - (|x|^2|y|^2 - \langle x, y \rangle^2)} + \langle x, y \rangle}{1 - |x|^2}, \quad y \in T_x \mathbb{B}^n = \mathbb{R}^n$$

where $|\cdot|$ and $\langle \cdot, \cdot \rangle$ denote the Euclidean norm and inner product in \mathbb{R}^n , respectively. F is called the Funk metric which is a Randers metric on \mathbb{B}^n . One can show that F is positively complete on \mathbb{B}^n [7]. Funk metric is a Douglas metric and satisfies $\bar{\mathbf{E}} = 0$ while $\mathbf{B} \neq 0$.

There are many connections in Finsler geometry [6][14][15]. Throughout this paper, we use the Berwald connection on Finsler manifolds. The h - and v - covariant derivatives of a Finsler tensor field are denoted by “ $|$ ” and “ \cdot ” respectively.

2. PRELIMINARIES

Let M be a n -dimensional C^∞ manifold. Denote by $T_x M$ the tangent space at $x \in M$, by $TM = \cup_{x \in M} T_x M$ the tangent bundle of M and by $TM_0 = TM \setminus \{0\}$ the slit tangent bundle. A Finsler metric on M is a function $F : TM \rightarrow [0, \infty)$ which has the following properties:

- (i) F is C^∞ on TM_0 ,
- (ii) F is positively 1-homogeneous on the fibers of TM ,
- (iii) for each $y \in T_x M$, the following quadratic form g_y on $T_x M$ is positive definite,

$$g_y(u, v) := \frac{1}{2} \frac{\partial^2}{\partial s \partial t} [F^2(y + su + tv)]|_{s,t=0}, \quad u, v \in T_x M.$$

Let $x \in M$ and $F_x := F|_{T_x M}$. To measure the non-Euclidean feature of F_x , define $\mathbf{C}_y : T_x M \otimes T_x M \otimes T_x M \rightarrow \mathbb{R}$ by

$$\mathbf{C}_y(u, v, w) := \frac{1}{2} \frac{d}{dt} [g_{y+tw}(u, v)]|_{t=0}, \quad u, v, w \in T_x M.$$

The family $\mathbf{C} := \{\mathbf{C}_y\}_{y \in TM_0}$ is called the Cartan torsion. It is well known that $\mathbf{C} = \mathbf{0}$ if and only if F is Riemannian.

Given a Finsler manifold (M, F) , then a global vector field \mathbf{G} is induced by F on TM_0 , which in a standard coordinate (x^i, y^i) for TM_0 is given by

$$\mathbf{G} = y^i \frac{\partial}{\partial x^i} - 2G^i(x, y) \frac{\partial}{\partial y^i},$$

where $G^i(y)$ are local functions on TM given by

$$G^i := \frac{1}{4} g^{il} \left\{ \frac{\partial^2 [F^2]}{\partial x^k \partial y^l} y^k - \frac{\partial [F^2]}{\partial x^l} \right\}, \quad y \in T_x M.$$

\mathbf{G} is called the associated spray to (M, F) . The projection of an integral curve of \mathbf{G} is called a geodesic in M . In local coordinates, a curve $c(t)$ is a geodesic if and only if its coordinates $(c^i(t))$ satisfy $\ddot{c}^i + 2G^i(\dot{c}) = 0$.

For a tangent vector $y \in T_x M_0$, define $\mathbf{B}_y : T_x M \otimes T_x M \otimes T_x M \rightarrow T_x M$ and $\mathbf{E}_y : T_x M \otimes T_x M \rightarrow \mathbb{R}$ by

$$\mathbf{B}_y(u, v, w) := B^i{}_{jkl}(y) u^j v^k w^l \frac{\partial}{\partial x^i} \Big|_x, \quad \mathbf{E}_y(u, v) := E_{jk}(y) u^j v^k,$$

where

$$B^i_{jkl}(y) := \frac{\partial^3 G^i}{\partial y^j \partial y^k \partial y^l}(y), \quad E_{jk}(y) := \frac{1}{2} B^m_{jkm}(y),$$

$u = u^i \frac{\partial}{\partial x^i}|_x$, $v = v^i \frac{\partial}{\partial x^i}|_x$ and $w = w^i \frac{\partial}{\partial x^i}|_x$. \mathbf{B} and \mathbf{E} are called the Berwald curvature and mean Berwald curvature, respectively. A Finsler metric is called a Berwald metric and mean Berwald metric if $\mathbf{B} = 0$ or $\mathbf{E} = 0$, respectively [12].

For a tangent vector $y \in T_x M_0$, define $\bar{\mathbf{E}}_y : T_x M \otimes T_x M \otimes T_x M \rightarrow \mathbb{R}$ by $\bar{\mathbf{E}}_y(u, v, w) := \bar{E}_{jkl}(y) u^i v^j w^k$, where

$$\bar{E}_{ijk} := E_{ij|k}.$$

From a Bianchi identity, we have

$$B^i_{jml|k} - B^i_{jkm|l} = R^i_{jkl,m},$$

where R^i_{jkl} is the Riemannian curvature of Berwald connection [13][17]. By putting $i = m$ in the above relation, we get

$$\bar{E}_{jlk} - \bar{E}_{jkl} = 2R^m_{jkl,m}.$$

Then \bar{E}_{ijk} is not totally symmetric in all three of its indices. It is easy to see that if $\bar{\mathbf{E}}$ -curvature is vanishing, then \mathbf{E} -curvature is covariantly constant along all horizontal directions on the slit tangent bundle TM_0 .

The quantity $\mathbf{H}_y = H_{ij} dx^i \otimes dx^j$ is defined as the covariant derivative of \mathbf{E} along geodesics [1][10]. More precisely

$$H_{ij} := E_{ij|m} y^m = \bar{E}_{ijm} y^m.$$

Define $\mathbf{D}_y : T_x M \otimes T_x M \otimes T_x M \rightarrow T_x M$ by $\mathbf{D}_y(u, v, w) := D^i_{jkl}(y) u^i v^j w^k \frac{\partial}{\partial x^i}|_x$ where

$$D^i_{jkl} := B^i_{jkl} - \frac{2}{n+1} \{E_{jk} \delta_l^i + E_{jl} \delta_k^i + E_{kl} \delta_j^i + E_{jk,l} y^i\}.$$

We call $\mathbf{D} := \{\mathbf{D}_y\}_{y \in TM_0}$ the Douglas curvature [8]. A Finsler metric with $\mathbf{D} = 0$ is called a Douglas metric [9]. It is remarkable that, the notion of Douglas metrics was proposed by Bácsó-Matsumoto as a generalization of Berwald metrics (see [4] and [5]).

Define $\mathbf{L}_y : T_x M \otimes T_x M \otimes T_x M \rightarrow \mathbb{R}$ by $\mathbf{L}_y(u, v, w) := L_{ijk}(y) u^i v^j w^k$ where $L_{ijk} := C_{ijk|s} y^s$. The family $\mathbf{L} := \{\mathbf{L}_y\}_{y \in TM_0}$ is called the Landsberg curvature [17]. F is called a Landsberg metric if $\mathbf{L} = \mathbf{0}$. Every Berwald metric is a Landsberg metric.

Theorem 2.1. ([2][3]) For a Douglas metric F on a manifold M , if $\mathbf{L} = \mathbf{0}$, then $\mathbf{B} = \mathbf{0}$.

3. PROOF OF THEOREM 1.1

To prove the Theorem 1.1, we need the following:

Lemma 3.1.

$$(3.1) \quad E_{jk,l|m} y^m = H_{jk,l} - \bar{E}_{jkl}.$$

Proof. The following Ricci identity for E_{ij} is hold:

$$(3.2) \quad E_{ij,l|k} - E_{ij|k,l} = E_{pj}B_{ikl}^p + E_{ip}B_{jkl}^p.$$

It follows from (3.2) that

$$(3.3) \quad E_{jk,l|m}y^m = E_{jk|m,l}y^m = [E_{jk|m}y^m]_{,l} - E_{jk|l}.$$

This yields the (3.1). \square

Proposition 3.1. *Let (M, F) be a Douglas space. Suppose that F satisfies $\bar{\mathbf{E}} = 0$. Then for any geodesic $c(t)$ and any parallel vector field $U(t)$ along c , the following functions*

$$(3.4) \quad \mathbf{C}(t) = \mathbf{C}_c(U(t), U(t), U(t)),$$

satisfying in the following equation

$$(3.5) \quad \mathbf{C}(t) = \mathbf{L}(0)t + \mathbf{C}(0).$$

Proof.

$$(3.6) \quad D^i_{jkl} = B^i_{jkl} - \frac{2}{n+1} \{E_{jk}\delta^i_l + E_{kl}\delta^i_j + E_{lj}\delta^i_k + E_{jk,ly^i}\}.$$

Then

$$(3.7) \quad D^i_{jkl|m}y^m = B^i_{jkl|m}y^m - \frac{2}{n+1} \{H_{jk}\delta^i_l + H_{kl}\delta^i_j + H_{lj}\delta^i_k + E_{jk,ly^i}y^i\}.$$

By Lemma 3.1, we get

$$(3.8) \quad B^i_{jkl|m}y^m = \frac{2}{n+1} \{H_{jk}\delta^i_l + H_{kl}\delta^i_j + H_{lj}\delta^i_k + H_{jk,ly^i} - \bar{E}_{jkl}y^i\}.$$

From assumption, we have

$$(3.9) \quad B^i_{jkl|m}y^m = 0.$$

Contracting with y_i yields

$$(3.10) \quad L_{jkl|m}y^m = 0.$$

Let

$$(3.11) \quad \mathbf{L}(t) = \mathbf{L}_c(U(t), U(t), U(t)).$$

From the definition of \mathbf{L}_y , we have

$$(3.12) \quad \mathbf{L}(t) = \mathbf{C}'(t).$$

By (3.10) we get

$$(3.13) \quad \mathbf{L}'(t) = 0.$$

The equation (3.13) implies that

$$(3.14) \quad \mathbf{L}(t) = \mathbf{L}(0).$$

Then we get the equation (3.5). \square

Remark 3.1. Let (M, F) be a Finsler space and $c : [a, b] \rightarrow M$ be a geodesic. For a parallel vector field $V(t)$ along c ,

$$(3.15) \quad g_c(V(t), V(t)) = \text{constant}.$$

Proof of Theorem 1.1: Take an arbitrary unit vector $y \in T_x M$ and an arbitrary vector $v \in T_x M$. Let $c(t)$ be the geodesic with $\dot{c}(0) = y$ and $V(t)$ the parallel vector field along c with $V(0) = v$. Define $\mathbf{C}(t)$ and $\mathbf{L}(t)$ as in (3.4) and (3.11), respectively. Then

$$(3.16) \quad \mathbf{C}(t) = t \mathbf{L}(0) + \mathbf{C}(0).$$

Suppose that \mathbf{C}_y is bounded, i.e., there is a constant $N < \infty$ such that

$$(3.17) \quad \|\mathbf{C}\|_x := \sup_{y \in T_x M_0} \sup_{v \in T_x M} \frac{\mathbf{C}_y(v, v, v)}{[g_y(v, v)]^{\frac{3}{2}}} \leq N.$$

By (3.15), we know that

$$T := g_{\dot{c}}(V(t), V(t)) = \text{constant}.$$

is positive constant. Thus

$$(3.18) \quad |\mathbf{C}(t)| \leq NT^{\frac{3}{2}} < \infty,$$

and $\mathbf{C}(t)$ is a bounded function on $[0, \infty)$. This implies

$$(3.19) \quad \mathbf{L}_y(v, v, v) = \mathbf{L}(0) = 0.$$

Therefore $\mathbf{L} = 0$ and by the Theorem 2.1, F is a Berwald metric. \square

Corollary 3.1. *Let (M, F) be a compact Douglas manifold. Then $\mathbf{L} = 0$ if and only if $\bar{\mathbf{E}} = 0$.*

Proof. If $\mathbf{D} = \mathbf{L} = 0$, then by Theorem 2.1 $\mathbf{B} = 0$ which implies that $\bar{\mathbf{E}} = 0$. Conversely let F be a compact Douglas metric with $\bar{\mathbf{E}} = 0$. By Theorem 1.1, $\mathbf{B} = 0$ and then $\mathbf{L} = 0$. \square

Corollary 3.2. *Let (M, F) be a complete Finsler space with Randers metric $F = \alpha + \beta$ such that α is a Riemannian metric and β is a close 1-form on M . Suppose that F satisfies $\bar{\mathbf{E}} = 0$. Then F is a Berwald metric.*

Proof. It is known that for a Randers metric $F = \alpha + \beta$ the Cartan tensor is bounded [12]. In fact

$$\|\mathbf{C}\| \leq \frac{3}{\sqrt{2}}.$$

Bácsó-Matsumoto showed that the Randers metric $F = \alpha + \beta$ is a Douglas metric if and only if β is a closed form [4]. Then by Theorem 1.1, we obtain the corollary. \square

Corollary 3.3. *For any complete submanifold M in a Minkowski space (V, F) , if the induced metric \bar{F} satisfies $\bar{\mathbf{E}} = 0$, then \bar{F} is a Berwald metric.*

Proof. For a submanifold M in a Minkowski space (V, F) , the Cartan tensor is bounded [12]. Then by Theorem 1.1, \bar{F} is a Berwald metric. \square

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FACULTY OF SCIENCE, DEPARTMENT OF MATHEMATICS, UNIVERSITY OF QOM, QOM. IRAN
E-mail address: akbar.tayebi@gmail.com

DEPARTMENT OF MATHEMATICS, FACULTY OF SCIENCE, ARAK UNIVERSITY, ARAK 38156-8-8349, IRAN
E-mail address: epeyghan@gmail.com