IKONION JOURNAL OF MATHEMATICS
Year:2019 Volume:1 Issue: 2

# MEASURE OF NONCOMPACTNESS FOR NONLINEAR HILFER FRACTIONAL DIFFERENTIAL EQUATION IN BANACH SPACES 

Abdelatif Boutiara ${ }^{1}$, Maamar Benbachir ${ }^{2, *}$, Kaddour Guerbati ${ }^{1}$<br>${ }^{1}$ Laboratoire de Mathematiques et Sciences appliquees, University of Ghardaia, ALGERIA<br>${ }^{2}$ Departement de Mathematiques, Universite Saad Dahlab Blida1, ALGERIA<br>*E-mail: mbenbachir2001@gmail.com (corresponding author)

( Received: 30.11.2019, Accepted: 02.01.2019, Published Online: 06.01.2020)


#### Abstract

This paper deals with nonlinear fractional differential equation with boundary value problem conditions. We investigate the existence of solutions in Banach spaces with Hilfer derivative. To obtain such result we apply Mönch's fixed point theorem and the technique of measures of noncompactness. At the end an example is given.

Keywords: Fractional differential equation; Hilfer fractional derivative; Kuratowski measures of noncompactness; Mönch fixed point theorems; Banach space.


MSC 2010: 26A33; 34B25; 34B15.

## 1 Introduction

In recent years, several papers have been devoted to the study of the existence of solutions for fractional differential equations, among others we refer the readers to the following references: Agarwal et al. [5, 4], Abbas et al. [3, 2], Sandeep et al. [32], Furati et al.[20], Benchohra et al. [17, 18], Gu et al. [21]. Moreover, it has been proved that differential models involving derivatives of fractional order arise in many engineering and scientific disciplines as the mathematical modeling of systems and processes in many fields, for instance, about physics, control theory, rheology, chemistry, and so on (see the monograph of Kilbas and al. [25], Hilfer and al. [22, 23], and Samko and al. [30]).

In this paper we focus on the existence of solutions of the following boundary value problem for a nonlinear fractional differential equation,

$$
\begin{equation*}
D_{a^{+}}^{\alpha, \beta} y(t)=f(t, y(t)), t \in J:=[0, T] . \tag{1.1}
\end{equation*}
$$

with the fractional boundary conditions

$$
\begin{align*}
& I^{1-\gamma} y(0)=y_{0}, I^{3-\gamma-2 \beta} y^{\prime}(0)=y_{1} \\
& I^{1-\gamma} y(\eta)=\lambda\left(I^{1-\gamma} y(T)\right), \gamma=\alpha+\beta-\alpha \beta \tag{1.2}
\end{align*}
$$

where $D_{0^{+}}^{\alpha, \beta}$ is the Hilfer fractional derivative, $0<\alpha<1,0 \leq \beta \leq 1,0<\lambda<1,0<\eta<T$ and let $E$ be a Banach space space with norm $\|\|, f:. J \times E \times E \times E \times E \rightarrow E$ is given continuous function and satisfying some assumptions that will be specified later. We will use the technique of measures of noncompactness. which is often used in several branches of nonlinear analysis. Especially, that technique turns out to be a very useful tool in existence for several types of integral equations; details
are found in Akhmerov et al. [7], Alvàrez [8], Banas̀ et al. [10, 11, 12, 13, 14, 15, 16], Benchohra et al. [17, 18], Mönch [27], Szufla [31].

The main idea used here is that on the Banach space $E$, we can not use Ascoli-Arzela theorem to prove the compactness of the operator, so we use the technique of measure of nocompactness to conclude.

Recently, considerable attention has been given to the existence of solutions of initial and boundary value problems for fractional differential equations with Hilfer fractional derivative [2, 3, 19], and other problems with Hilfer-Hadamard fractional derivative; see [1, 2, 33, 34]. Many existence results were established by the use of technics of nonlinear analysis such as Banach fixed point theorem, Schaefer's fixed point theorem, Lerayâ-Schauder nonlinear alternative, etc ..., and the technique of measures of noncompactness, see $[4,5,6,18,15,16]$.

In 2008, Benchohra et al. [17], considered the existence of solutions of an initial value problem for a nonlinear fractional differential equation

$$
\begin{cases}D^{r} y(t)=f(t, y), & \text { for each } t \in J=[0, T], 1<r<2  \tag{1.3}\\ y(0)=y_{0}, y^{\prime}(0)=y_{1}, & \end{cases}
$$

where $D^{r}$ is the Caputo fractional derivative, $f: J \times E \rightarrow E$ is a given function, and E is a Banach space. They obtained results for solutions by using Mönch's fixed point theorem and the technique of measures of noncompactness.

In 2018, S. Abbas et al. [2], studied the existence of solutions for the following coupled system of Hilfer fractional differential equations

$$
\left\{\begin{array}{l}
D_{0}^{\alpha_{1}, \beta_{1}} u(t)=f_{1}(t, u(t), v(t)), \quad t \in J=[0, T]  \tag{1.4}\\
D_{0}^{\alpha_{2}, \beta_{2}} v(t)=f_{2}(t, u(t), v(t)),
\end{array}\right.
$$

with the following initial conditions

$$
\left\{\begin{array}{l}
I_{0}^{1-\gamma_{1}} u(0)=\phi_{1}  \tag{1.5}\\
I_{0}^{1-\gamma_{2}} v(0)=\phi_{2}
\end{array}\right.
$$

where $T>0, \alpha_{i} \in(0,1), \beta_{i} \in[0,1], \gamma_{i}=\alpha_{i}+\beta_{i}-\alpha_{i} \beta_{i}, \phi_{i} \in E, f_{i}: I \times E \times E \rightarrow E ; i=1,2$, are given functions, $E$ is a real (or complex) Banach space with a norm $\|\cdot\|, I_{0}^{1 \gamma_{i}}$ is the left- sided mixed Riemann-Liouville integral of order $1-\gamma_{i}$, and $D_{0}^{\alpha_{i}, \beta_{i}}$ is the generalized Riemann-Liouville derivative (Hilfer) operator of order $\alpha_{i}$ and type $\beta_{i}: i=1,2$. They obtained results for solutions by using the technique of measure of noncompactness and the fixed point theory.

In 2018, D.Vivek et al. [34], studied the existence, uniqueness and stability analysis of Hilfer-Hadamard type fractional neutral pantograph equations with boundary conditions of the form

$$
\begin{cases}D_{1^{+}}^{\alpha, \beta} x(t)=f\left(t, x(t), x(\lambda t), D_{1^{+}}^{\alpha, \beta} x(\lambda t)\right), & t \in J=[0, T]  \tag{1.6}\\ I_{1^{+}}^{1-\gamma} x(1)=a, I_{1^{+}}^{1-\gamma} x(T)=b, & \gamma=\alpha+\beta-\alpha \beta\end{cases}
$$

where $D_{1^{+}}^{\alpha, \beta}$ is the Hilfer-Hadamard fractional derivative, $0<\alpha<1,0 \leq \beta \leq 1,0<\lambda<1$. Let $E$ be a Banach space, $f: J \times E \times E \times E \rightarrow E$ is a given continuous function. They obtained results for solutions by using Schaefer's fixed point theorem.

The principal goal of this paper is to prove the existence of solutions for the problem (1.1)-(1.2) using Mönch's fixed point theorem and its related Kuratowski measure of noncompactness.

## 2 Preliminaires

In what follows we introduce definitions, notations, and preliminary facts which are used in the sequel.
For more details, we refer to $[4,5,7,9,11,19,20,21,22,23,24,25,26,31,32]$.
Denote by $C(J, E)$ the Banach space of continuous functions $y: J \rightarrow E$, with the usual supremum norm

$$
\|y\|_{\infty}=\sup \{\|y(t)\|, t \in J\}
$$

Let $L^{1}(J, E)$ be the Banach space of measurable functions $y: J \rightarrow E$ which are Bochner integrable, equipped with the norm

$$
\|y\|_{L^{1}}=\int_{J} y(t) d t
$$

$A C^{1}(J, E)$ denotes the space of functions $y: J \rightarrow E$, whose first derivative is absolutely continuous.
Definition 2.1. [20] Let $J=[0, T]$ be a finite interval and $\gamma$ as a real such that $0 \leq \gamma<1$. We introduce the weighted space $C_{1-\gamma}(J, E)$ of continuous functions $f$ on $(0, T]$ as

$$
C_{1-\gamma}(J, E)=\left\{f:(0, T] \rightarrow E:(t-a)^{1-\gamma} f(t) \in C(J, E)\right\}
$$

In the space $C_{1-\gamma}(J, E)$, we define the norm

$$
\|f\|_{C_{1-\gamma}}=\left\|(t-a)^{1-\gamma} f(t)\right\|_{C}, C_{0}(J, E)=C(J, E) .
$$

Definition 2.2. [20] Let $0<\alpha<1,0 \leq \beta \leq 1$, the weighted space $C_{1-\gamma}^{\alpha, \beta}(J, E)$ is defined by

$$
C_{1-\gamma}^{\alpha, \beta}(J, E)=\left\{f:(0, T] \rightarrow \mathbb{R}: D_{0^{+}}^{\alpha, \beta} f \in C_{1-\gamma}(J, E)\right\}, \gamma=\alpha+\beta-\alpha \beta
$$

and

$$
C_{1-\gamma}^{1}(J, E)=\left\{f:(0, T] \rightarrow \mathbb{R}: f^{\prime} \in C_{1-\gamma}(J, E)\right\}, \gamma=\alpha+\beta-\alpha \beta
$$

with the norm

$$
\begin{equation*}
\|f\|_{C_{1-\gamma}^{1}}=\|f\|_{C}+\left\|f^{\prime}\right\|_{C_{1-\gamma}} . \tag{2.1}
\end{equation*}
$$

One have, see [20], $D_{0^{+}}^{\alpha, \beta} f=I_{0^{+}}^{\beta(1-\alpha)} D_{0^{+}}^{\gamma} f$ and $C_{1-\gamma}^{\gamma}(J, E) \subset C_{1-\gamma}^{\alpha, \beta}(J, E), \gamma=\alpha+\beta-\alpha \beta, 0<\alpha<$ $1,0 \leq \beta \leq 1$. Moreover, $C_{1-\gamma}(J, E)$ is complete metric space of all continuous functions mapping $J$ into $E$ with the metric $d$ defined by

$$
d\left(y_{1}, y_{2}\right)=\left\|y_{1}-y_{2}\right\|_{C_{1-\gamma}(J, E)}:=\max _{t \in J}\left|(t-a)^{1-\gamma}\left[y_{1}(t)-y_{2}(t)\right]\right|
$$

for details see [20].
Notation 2.3. For a given set $V$ of functions $v: J \rightarrow E$, let us denote by

$$
V(t)=\{v(t): v \in V\}, t \in J,
$$

and

$$
V(J)=\{v(t): v \in V, t \in J\} .
$$

Now let us recall some fundamental facts of the notion of Kuratowski measure of noncompactness.
Definion 2.4. ( $[7,11]$ ). Let $E$ be a Banach space and $\Omega_{E}$ the bounded subsets of $E$. The Kuratowski measure of noncompactness is the map $\mu: \Omega_{E} \rightarrow[0, \infty]$ defined by

$$
\mu(B)=\inf \left\{\epsilon>0: B \subseteq \cup_{i=1}^{n} B_{i} \text { and } \operatorname{diam}\left(B_{i}\right) \leq \epsilon\right\} ; \text { here } B \in \Omega_{E} .
$$

This measure of noncompactness satisfies some important properties [7, 11]:
(a) $\mu(B)=0 \Leftrightarrow \bar{B}$ is compact ( $B$ is relatively compact).
(b) $\mu(B)=\mu(\bar{B})$.
(c) $A \subset B \Rightarrow \mu(A) \leq \mu(B)$.
(d) $\mu(A+B) \leq \mu(A)+\mu(B)$
(e) $\mu(c B)=|c| \mu(B) ; c \in \mathbb{R}$.
(f) $\mu(\operatorname{conv} B)=\mu(B)$.

Now, we give some results and properties of fractional calculus. Definition 2.5. [26] Let $(0, T]$ and $f:(0, \infty) \rightarrow \mathbb{R}$ is a real valued continuous function. The Riemann-Liouville fractional integral of a function $f$ of order $\alpha \in \mathbb{R}^{+}$is denoted as $I_{0^{+}}^{\alpha} f$ and defined by

$$
\begin{equation*}
I_{0^{+}}^{\alpha} f(t)=\frac{1}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1} f(s) d s, t>0 \tag{2.2}
\end{equation*}
$$

where $\Gamma(\alpha)$ is the Euler's Gamma function.
Definion 2.6. [25] Let $(0, T]$ and $f:(0, \infty) \rightarrow \mathbb{R}$ is a real valued continuous function. The Riemann-Liouville fractional derivative of a function $f$ of order $\alpha \in \mathbb{R}_{0}^{+}=[0,+\infty)$ is denoted as $D_{0^{+}}^{\alpha} f$ and defined by

$$
\begin{equation*}
D_{0^{+}}^{\alpha} f(t)=\frac{1}{\Gamma(n-\alpha)} \frac{d^{n}}{d t^{n}} \int_{0}^{t}(t-s)^{n-\alpha-1} f(s) d s \tag{2.3}
\end{equation*}
$$

where $n=[\alpha]+1$, and $[\alpha]$ means the integral part of $\alpha$, provided the right hand side is pointwise defined on $(0, \infty)$.

Definion 2.7. [25] The Caputo fractional derivative of function $f$ with order $\alpha>0, n-1<\alpha<$ $n, n \in \mathbb{N}$ is defined by

$$
\begin{equation*}
{ }^{C} D_{0^{+}}^{\alpha} f(t)=\frac{1}{\Gamma(n-\alpha)} \int_{0}^{t}(t-s)^{n-\alpha-1} f^{(n)}(s) d s, t>0 \tag{2.4}
\end{equation*}
$$

In [22], R. Hilfer studied applications of a generalized fractional operator having the Riemann-Liouville and Caputo derivatives as specific cases (see also [23, 24]).

Definion 2.8. [22] The Hilfer fractional derivative $D_{0^{+}}^{\alpha, \beta}$ of order $\alpha(n-1<\alpha<n)$ and type $\beta$ $(0 \leq \beta \leq 1)$ is defined by

$$
\begin{equation*}
D_{0^{+}}^{\alpha, \beta}=I_{0^{+}}^{\beta(n-\alpha)} D^{n} I_{0^{+}}^{(1-\beta)(n-\alpha)} f(t) \tag{2.5}
\end{equation*}
$$

where $I_{0^{+}}^{\alpha}$ and $D_{0^{+}}^{\alpha}$ are Riemann-Liouville fractional integral and derivative defined by 2.2 and 2.3 , respectively.

Remark 2.9. (See [19]) Hilfer fractional derivative interpolates between the R-L (2.3, if $\beta=0$ ) and Caputo (2.4, if $\beta=1$ ) fractional derivatives since

$$
D_{0^{+}}^{\alpha, \beta}=\left\{\begin{array}{l}
D I^{1-\alpha}=D_{0^{+}}^{\alpha}, \beta=0, \quad I^{1-\alpha} D=^{C} D_{0^{+}}^{\alpha}, \beta=1, \\
I^{1-\alpha} D=C^{C} D_{0^{+}}^{\alpha}, \beta=1,
\end{array}\right.
$$

Lemma 2.10. Let $0<\alpha<1,0 \leq \beta \leq 1, \gamma=\alpha+\beta-\alpha \beta$, and $f \in L^{1}(J, E)$.
The operator $D_{0^{+}}^{\alpha, \beta}$ can be written as

$$
\begin{aligned}
D_{0^{+}}^{\alpha, \beta} f(t) & =\left(I_{0^{+}}^{\beta(1-\alpha)} \frac{d}{d t} I_{0^{+}}^{(1-\gamma)} f\right)(t) \\
& =I_{0^{+}}^{\beta(1-\alpha)} D^{\gamma} f(t), \quad t \in J
\end{aligned}
$$

Moreover, the parameter $\gamma$ satisfies

$$
0<\gamma \leq 1, \gamma \geq \alpha, \gamma>\beta, 1-\gamma<1-\beta(1-\alpha) .
$$

Lemma 2.11. Let $0<\alpha<1,0 \leq \beta \leq 1, \gamma=\alpha+\beta-\alpha \beta$, If $D_{0^{+}}^{\beta(1-\alpha)} f$ exists and in $L^{1}(J, E)$, then

$$
D_{0^{+}}^{\alpha, \beta} I_{0^{+}}^{\alpha} f(t)=I_{0^{+}}^{\beta(1-\alpha)} D_{0^{+}}^{\beta(1-\alpha)} f(t) \text {, for a.e. } t \in J
$$

Furthermore, if $f \in C_{1-\gamma}(J, E)$ and $I_{0^{+}}^{1-\beta(1-\alpha)} f \in C_{1-\gamma}^{1}(J, E)$, then

$$
D_{0^{+}}^{\alpha, \beta} I_{0^{+}}^{\alpha} f(t)=f(t) \text {, for a.e. } t \in J .
$$

Lemma 2.12. Let $0<\alpha<1,0 \leq \beta \leq 1, \gamma=\alpha+\beta-\alpha \beta$, and $f \in L^{1}(J, E)$. If $D_{0^{+}}^{\gamma} f$ exists and in $L^{1}(J, E)$, then

$$
\begin{aligned}
I_{0^{+}}^{\alpha} D_{0^{+}}^{\alpha, \beta} f(t) & =I_{0^{+}}^{\gamma} D_{0^{+}}^{\gamma} f(t) \\
& =f(t)-\frac{I_{0^{+}}^{1-\gamma} f\left(0^{+}\right)}{\Gamma(\gamma)} t^{\gamma-1}, \quad t \in J .
\end{aligned}
$$

Lemma 2.13. [25] For $t>a$, we have

$$
\begin{align*}
I_{0^{+}}^{\alpha}(t-a)^{\beta-1}(t) & =\frac{\Gamma(\beta)}{\Gamma(\beta-\alpha)}(t-a)^{\beta+\alpha-1}  \tag{2.6}\\
D_{0^{+}}^{\alpha}(t-a)^{\beta-1}(t) & =\frac{\Gamma(\beta)}{\Gamma(\beta-\alpha)}(t-a)^{\beta-\alpha-1},
\end{align*}
$$

Lemma 2.14. Let $\alpha>0,0 \leq \beta \leq 1$, so the homogeneous differential equation with Hilfer fractional order

$$
\begin{equation*}
D_{0+}^{\alpha, \beta} h(t)=0 \tag{2.7}
\end{equation*}
$$

has a solution

$$
h(t)=c_{0} t^{\gamma-1}+c_{1} t^{\gamma+2 \beta-2}+c_{2} t^{\gamma+2(2 \beta)-3}+\ldots+c_{n} t^{\gamma+n(2 \beta)-(n+1)} .
$$

Definion 2.15. A map $f: J \times E \rightarrow E$ is said to be Caratheodory if
(i) $t \mapsto f(t, u)$ is measurable for each $u \in E$;
(ii) $u \mapsto F(t, u)$ is continuous for almost all $t \in J$.

The following theorems will play a major role in our analysis.
Theorem 2.16. ([5, 32]). Let $D$ be a bounded, closed and convex subset of a Banach space such that $0 \in D$, and let $N$ be a continuous mapping of $D$ into itself. If the implication $V=\overline{\operatorname{conv}} N(V)$ or $V=N(V) \cup 0 \Rightarrow \mu(V)=0$ holds for every subset $V$ of $D$, then $N$ has a fixed point.

Lemma 2.17. ([32]). Let $D$ be a bounded, closed and convex subset of the Banach space $C(J, E)$, $G$ a continuous function on $J \times J$ and $f$ a function from $J \times E \longrightarrow E$ which satisfies the Caratheodory conditions, and suppose there exists $p \in L^{1}\left(J, \mathbb{R}^{+}\right)$such that, for each $t \in J$ and each bounded set $B \subset E$, we have

$$
\lim _{h \rightarrow 0^{+}} \mu\left(f\left(J_{t, h} \times B\right)\right) \leq p(t) \mu(B) ; \text { here } J_{t, h}=[t-h, t] \cap J .
$$

If $V$ is an equicontinuous subset of $D$, then

$$
\mu\left(\left\{\int_{J} G(s, t) f(s, y(s)) d s: y \in V\right\}\right) \leq \int_{J}\|G(t, s)\| p(s) \mu(V(s)) d s
$$

## 3 Main results

First of all, we define what we mean by a solution of the BVP (1.1)-(1.2).
Definition 3.1. A function $y \in C_{1-\gamma}(J, E)$ is said to be a solution of the problem (1.1)- (1.2) if $y$ satisfies the equation $D_{a^{+}}^{\alpha, \beta} y(t)=f(t, y(t))$ on $J$, and the conditions $I^{1-\gamma} y(0)=y_{0}, I^{3-\gamma-2 \beta} y^{\prime}(0)=y_{1}$, and $I^{1-\gamma} y(\eta)=\lambda\left(I^{1-\gamma} y(T)\right)$.

Lemma 3.2. Let $f: J \times E \times E \times E \times E \rightarrow E$ be a function such that $f \in C_{1-\gamma}(J, E)$ for any $y \in C_{1-\gamma}(J, E)$. A function $y \in C_{1-\gamma}^{\gamma}(J, E)$ is a solution of the integral equation

$$
\begin{align*}
y(t) & =I^{\alpha} f(t, y(t))+\frac{y_{0}}{\Gamma(\gamma)} t^{\gamma-1}+\frac{y_{1}}{\Gamma(\gamma+2 \beta-1)} t^{\gamma+2 \beta-2}+\zeta(\beta, \gamma, \eta, \lambda) \\
& {\left[y_{0}(\lambda-1)+\frac{\lambda T^{2 \beta-1}-\eta^{2 \beta-1}}{\Gamma(2 \beta)} y_{1}+\lambda I^{\alpha-\gamma+1} f(T, y(T))-I^{\alpha-\gamma+1} f(\eta, y(\eta))\right] t^{\gamma+2(2 \beta)-3} } \tag{3.1}
\end{align*}
$$

if and only if $y$ is a solution of the Hilfer fractional BVP

$$
\begin{equation*}
D_{a^{+}}^{\alpha, \beta} y(t)=f(t, y(t)), t \in J:=[0, T] \tag{3.2}
\end{equation*}
$$

with the fractional boundary conditions

$$
\begin{align*}
& I^{1-\gamma} y(0)=y_{0}, \quad I^{3-\gamma-2 \beta} y^{\prime}(0)=y_{1} \\
& I^{1-\gamma} y(\eta)=\lambda\left(I^{1-\gamma} y(T)\right), \gamma=\alpha+\beta-\alpha \beta \tag{3.3}
\end{align*}
$$

Proof. Assume $y$ satisfies (3.1). Then Lemma 2.18 implies that

$$
y(t)=c_{0} t^{\gamma-1}+c_{1} t^{\gamma+2 \beta-2}+c_{2} t^{\gamma+2(2 \beta)-3}+\frac{1}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1} f(s, y(s)) d s
$$

for some constants $c_{0}, c_{1}, c_{2} \in \mathbb{R}$.
From (3.3), by Lemma 2.16 (2.6), we have

- $I^{1-\gamma} y(0)=y_{0}$ implies that $c_{0}=\frac{y_{0}}{\Gamma(\gamma)}$
- $I^{3-\gamma-2 \beta} y^{\prime}(0)=y_{1}$ implies that $c_{1}=\frac{y_{1}}{\Gamma(\gamma+2 \beta-1)}$
- $I^{1-\gamma} y(1)=\lambda\left(I^{1-\gamma} y(T)\right)$ implies that

$$
\begin{align*}
\left(I^{1-\gamma} y\right)(\eta) & =\left(I^{1-\gamma} \frac{y_{0}}{\Gamma(\gamma)} t^{\gamma-1}\right)(\eta)+\left(I^{1-\gamma} \frac{y_{1}}{\Gamma(\gamma)} t^{\gamma+2 \beta-2}\right)(\eta)+c_{2}\left(I^{1-\gamma} t^{\gamma+2(2 \beta)-3}\right)(\eta)+I^{\alpha-\gamma+1} f(\eta, y(\eta)) \\
& =y_{0}+\frac{y_{1}}{\Gamma(2 \beta)} \eta^{2 \beta-1}+c_{2} \frac{\Gamma(\gamma+2(2 \beta)-2)}{\Gamma(4 \beta-1)} \eta^{4 \beta-2}+I^{\alpha-\gamma+1} f(\eta, y(\eta)) \\
\left(I^{1-\gamma} y\right)(T) & =\left(I^{1-\gamma} \frac{y_{0}}{\Gamma(\gamma)} t^{\gamma-1}\right)(T)+\left(I^{1-\gamma} \frac{y_{1}}{\Gamma(\gamma+2 \beta-1)} t^{\gamma+2 \beta-2}\right)(T)+c_{2}\left(I^{1-\gamma} t^{\gamma+2(2 \beta)-3}\right)(T)  \tag{T}\\
& +I^{\alpha-\gamma+1} f(T, y(T)) \\
& =y_{0}+\frac{y_{1}}{\Gamma(2 \beta)} T^{2 \beta-1}+c_{2} \frac{\Gamma(\gamma+2(2 \beta)-2)}{\Gamma(4 \beta-1)} T^{4 \beta-2}+I^{\alpha-\gamma+1} f(T, y(T)) \\
\lambda\left(I^{1-\gamma} y\right)(T) & =\lambda y_{0}+\frac{\lambda y_{1}}{\Gamma(2 \beta)} T^{2 \beta-1}+c_{2} \frac{\lambda \Gamma(\gamma+2(2 \beta)-2)}{\Gamma(4 \beta-1)} T^{4 \beta-2}+\lambda I^{\alpha-\gamma+1} f(T, y(T))
\end{align*}
$$

that is,

$$
c_{2}=\zeta(\beta, \gamma, \eta, \lambda)\left[y_{0}(\lambda-1)+\frac{\lambda T^{2 \beta-1}-\eta^{2 \beta-1}}{\Gamma(2 \beta)} y_{1}+\lambda I^{\alpha-\gamma+1} f(T, y(T))-I^{\alpha-\gamma+1} f(\eta, y(\eta))\right]
$$

With

$$
\zeta(\beta, \gamma, \eta, \lambda)=\frac{\Gamma(4 \beta-1)}{\Gamma(\gamma+4 \beta-2)\left(\eta^{4 \beta-2}-\lambda T^{4 \beta-2}\right)}
$$

The following hypotheses will be used in the sequel.
(H1) $f: J \times E \rightarrow E$ satisfies the Caratheodory conditions;
(H2) There exists $p \in L^{1}\left(J, \mathbb{R}^{+}\right) \cap C\left(J, \mathbb{R}^{+}\right)$, such that,

$$
\|f(t, y)\| \leq p(t)\|y\|, \text { for } t \in J \text { and each } y \in E
$$

(H3) For each $t \in J$ and each bounded set $B \subset E$, we have

$$
\lim _{h \rightarrow 0^{+}} \mu\left(f\left(J_{t, h} \times B\right)\right) \leq t^{1-\gamma} p(t) \mu(B) ; \text { here } J_{t, h}=[t-h, t] \cap J .
$$

Theorem 3.3. Assume that conditions (H1)-(H3) hold. Let

$$
p^{*}=\sup _{t \in J} p(t) .
$$

If

$$
\begin{equation*}
p^{*}\left[\frac{T^{\alpha-\gamma+1}}{\Gamma(\alpha+1)}+\frac{|\zeta(\beta, \gamma, \eta, \lambda)|}{\Gamma(\alpha-\gamma+2)}\left[|\lambda| T^{\alpha-\gamma+1}+\eta^{\alpha-\gamma+1}\right] T^{2(2 \beta)-2}\right]<1 \tag{3.4}
\end{equation*}
$$

then the BVP (1.1)-(1.2) has at least one solution.
Proof. We transform the problem (1.1)-(1.2) into a fixed point problem, then we consider the operator $N: C_{1-\gamma}(J, E) \rightarrow C_{1-\gamma}(J, E)$ defined by

$$
\begin{gathered}
N(y)(t)=I^{\alpha} f(t, y(t))+\frac{y_{0}}{\Gamma(\gamma)} t^{\gamma-1}+\frac{y_{1}}{\Gamma(\gamma+2 \beta-1)} t^{\gamma+2 \beta-2}+\zeta(\beta, \gamma, \eta, \lambda) \\
{\left[y_{0}(\lambda-1)+\frac{\lambda T^{2 \beta-1}-\eta^{2 \beta-1}}{\Gamma(2 \beta)} y_{1}+\lambda I^{\alpha-\gamma+1} f(T, y(T))-I^{\alpha-\gamma+1} f(\eta, y(\eta))\right] t^{\gamma+2(2 \beta)-3}}
\end{gathered}
$$

Clearly, the fixed points of the operator $N$ are solutions of the problem (1.1)-(1.2). Let

$$
\begin{equation*}
R \geq \frac{\frac{y_{0}}{\Gamma(\gamma)}+\frac{y_{1} T^{2 \beta-1}}{\Gamma(\gamma+2 \beta-1)}+|\zeta(\beta, \gamma, \eta, \lambda)|\left(\left\|y_{0}\right\||\lambda-1|+\frac{\lambda T^{2 \beta-1}-\eta^{2 \beta-1}}{\Gamma(2 \beta)}\left\|y_{1}\right\|\right)}{1-p^{*}\left(\frac{T^{\alpha-\gamma+1}}{\Gamma(\alpha+1)}-\frac{|\zeta(\beta, \gamma, \eta, \lambda)| T^{4 \beta-2}}{\Gamma(\alpha-\gamma+2)}\left(|\lambda| T^{\alpha-\gamma+1}+\eta^{\alpha-\gamma+1}\right)\right)} \tag{3.5}
\end{equation*}
$$

and consider

$$
D=\left\{y \in C_{1-\gamma}(J, E):\|y\| \leq R\right\} .
$$

The subset $D$ is closed, bounded and convex. We shall show that the assumptions of Theorem 2.4 are satisfied. The proof will be given in three steps.

## 1-First we show that $N$ is continuous:

Let $y_{n}$ be a sequence such that $y_{n} \rightarrow y$ in $C_{1-\gamma}(J, E)$. Then for each $t \in J$,

$$
\begin{aligned}
\| t^{1-\gamma}\left(N\left(y_{n}\right)(t)-\right. & N(y)(t))\left\|\leq \frac{t^{1-\gamma}}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1}\right\| f\left(s, y_{n}(s)\right)-f(s, y(s)) \| d s+\frac{|\zeta(\beta, \gamma, \eta, \lambda)| t^{4 \beta-2}}{\Gamma(\alpha-\gamma+1)} \\
& {\left[|\lambda| \int_{0}^{T}(T-s)^{\alpha-\gamma}\left\|f\left(s, y_{n}(s)\right)-f(s, y(s))\right\| d s+\int_{0}^{\eta}(\eta-s)^{\alpha-\gamma}\left\|f\left(s, y_{n}(s)\right)-f(s, y(s))\right\| d s\right] } \\
& \leq\left(\frac{t^{\alpha-\gamma+1}}{\Gamma(\alpha+1)}+\frac{|\zeta(\beta, \gamma, \eta, \lambda)| t^{4 \beta-2}}{\Gamma(\alpha-\gamma+2)}\left(|\lambda| T^{\alpha-\gamma+1}+\eta^{\alpha-\gamma+1}\right)\right)\left\|f\left(s, y_{n}(s)\right)-f(s, y(s))\right\| \\
& \leq\left(\frac{T^{\alpha-\gamma+1}}{\Gamma(\alpha+1)}+\frac{|\zeta(\beta, \gamma, \eta, \lambda)| T^{4 \beta-2}}{\Gamma(\alpha-\gamma+2)}\left(|\lambda| T^{\alpha-\gamma+1}+\eta^{\alpha-\gamma+1}\right)\right)\left\|f\left(s, y_{n}(s)\right)-f(s, y(s))\right\|
\end{aligned}
$$

Since $f$ is of Caratheodory type, then by the Lebesgue dominated convergence theorem we have

$$
\left\|N\left(y_{n}\right)-N(y)\right\|_{\infty} \rightarrow 0 \text { as } n \rightarrow \infty
$$

## 2-Second we show that $N$ maps $D$ into itself:

Take $y \in D$, by (H2), we have, for each $t \in J$ and assume that $N y(t) \neq 0$.

$$
\begin{aligned}
& \left\|t^{1-\gamma} N(y)(t)\right\| \leq \frac{t^{1-\gamma}}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1}\|f(s, y(s))\| d s+\frac{\left\|y_{0}\right\|}{\Gamma(\gamma)}+\frac{\left\|y_{1}\right\|}{\Gamma(\gamma+2 \beta-1)} t^{2 \beta-1} \\
& +|\zeta(\beta, \gamma, \eta, \lambda)|\left[\left\|y_{0}\right\||\lambda-1|+\frac{|\lambda| T^{2 \beta-1}-\eta^{2 \beta-1}}{\Gamma(2 \beta)}\left\|y_{1}\right\|\right] t^{4 \beta-2} \\
& +\frac{|\zeta(\beta, \gamma, \eta, \lambda)| t^{4 \beta-2}}{\Gamma(\alpha-\gamma+1)}\left[|\lambda| \int_{0}^{T}(T-s)^{\alpha-\gamma}\|f(s, y(s))\| d s+\int_{0}^{\eta}(\eta-s)^{\alpha-\gamma}\|f(s, y(s))\| d s\right] \\
& \leq \frac{T^{1-\gamma}}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1} p(s)\|y\| d s+\frac{\left\|y_{0}\right\|}{\Gamma(\gamma)}+\frac{\left\|y_{1}\right\|}{\Gamma(\gamma+2 \beta-1)} T^{2 \beta-1} \\
& +|\zeta(\beta, \gamma, \eta, \lambda)|\left[\left\|y_{0}\right\||\lambda-1|+\frac{|\lambda| T^{2 \beta-1}-\eta^{2 \beta-1}}{\Gamma(2 \beta)}\left\|y_{1}\right\|\right] T^{4 \beta-2} \\
& +\frac{T^{4 \beta-2}}{\Gamma(\alpha-\gamma+1)}|\zeta(\beta, \gamma, \eta, \lambda)|\left[|\lambda| \int_{0}^{T}(T-s)^{\alpha-\gamma} p(s)\|y\| d s+\int_{0}^{1}(1-s)^{\alpha-\gamma} p(s)\|y\| d s\right] \\
& \leq \frac{R T^{1-\gamma}}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1} p(s) d s+\frac{\left\|y_{0}\right\|}{\Gamma(\gamma)}+\frac{\left\|y_{1}\right\|}{\Gamma(\gamma+2 \beta-1)} T^{2 \beta-1} \\
& +|\zeta(\beta, \gamma, \eta, \lambda)|\left[\left\|y_{0}\right\||\lambda-1|+\frac{|\lambda| T^{2 \beta-1}-\eta^{2 \beta-1}}{\Gamma(2 \beta)}\left\|y_{1}\right\|\right] T^{4 \beta-2} \\
& +\frac{R T^{4 \beta-2}}{\Gamma(\alpha-\gamma+1)}|\zeta(\beta, \gamma, \eta, \lambda)|\left[|\lambda| \int_{0}^{T}(T-s)^{\alpha-\gamma} p(s) d s+\int_{0}^{\eta}(\eta-s)^{\alpha-\gamma} p(s) d s\right] \\
& \leq \frac{R p^{*} T^{1-\gamma}}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1} d s+\frac{\left\|y_{0}\right\|}{\Gamma(\gamma)}+\frac{\left\|y_{1}\right\|}{\Gamma(\gamma+2 \beta-1)} T^{2 \beta-1} \\
& +|\zeta(\beta, \gamma, \eta, \lambda)|\left[\left\|y_{0}\right\||\lambda-1|+\frac{|\lambda| T^{2 \beta-1}-\eta^{2 \beta-1}}{\Gamma(2 \beta)}\left\|y_{1}\right\|\right] T^{4 \beta-2} \\
& +\frac{R p^{*} T^{4 \beta-2}}{\Gamma(\alpha-\gamma+1)}|\zeta(\beta, \gamma, \eta, \lambda)|\left[|\lambda| \int_{0}^{T}(T-s)^{\alpha-\gamma} d s+\int_{0}^{\eta}(\eta-s)^{\alpha-\gamma} d s\right] \\
& \leq \frac{R p^{*} T^{\alpha-\gamma+1}}{\Gamma(\alpha+1)}+\frac{\left\|y_{0}\right\|}{\Gamma(\gamma)}+\frac{\left\|y_{1}\right\|}{\Gamma(\gamma+2 \beta-1)} T^{2 \beta-1} \\
& +|\zeta(\beta, \gamma, \eta, \lambda)|\left[\left\|y_{0}\right\||\lambda-1|+\frac{|\lambda| T^{2 \beta-1}-\eta^{2 \beta-1}}{\Gamma(2 \beta)}\left\|y_{1}\right\|\right] T^{4 \beta-2} \\
& +|\zeta(\beta, \gamma, \eta, \lambda)|\left[\frac{|\lambda| R p^{*} T^{\alpha-\gamma+4 \beta-1}}{\Gamma(\alpha-\gamma+2)}+\frac{R p^{*} \eta^{\alpha-\gamma+1} T^{4 \beta-2}}{\Gamma(\alpha-\gamma+2)}\right] \\
& \leq R .
\end{aligned}
$$

## 3-Finally we show that $N(D)$ is bounded and equicontinuous:

By Step 2, it is obvious that $N(D) \subset C_{1-\gamma}(J, E)$ is bounded. For the equicontinuity of $N(D)$, let $t_{1}, t_{2} \in J, t_{1}<t_{2}$ and $y \in D$, so $t_{2}^{1-\gamma} N y\left(t_{2}\right)-t_{1}^{1-\gamma} N y\left(t_{1}\right) \neq 0$. Then

$$
\left\|t_{2}^{1-\gamma} N y\left(t_{2}\right)-t_{1}^{1-\gamma} N y\left(t_{1}\right)\right\| \leq \frac{1}{\Gamma(\gamma+2 \beta-1)}\left\|y_{1} t_{2}^{2 \beta-1}-y_{1} t_{1}^{2 \beta-1}\right\|+|\zeta(\beta, \gamma, \eta, \lambda)|
$$

$$
\begin{aligned}
& \left\|\left[y_{0}|\lambda-1|+\frac{|\lambda| T^{2 \beta-1}-\eta^{2 \beta-1}}{\Gamma(2 \beta)} y_{1}+|\lambda| I^{\alpha-\gamma+1} f(T, y(T))-I^{\alpha-\gamma+1} f(\eta, y(\eta))\right]\right\| \\
& \left(t_{2}^{2(2 \beta)-2)}-t_{1}^{2(2 \beta)-2)}\right) \\
& +\left\|\frac{t_{2}^{1-\gamma}}{\Gamma(\alpha)} \int_{0}^{t_{2}}\left(t_{2}-s\right)^{\alpha-1} f(s, y(s)) d s-\frac{t_{1}^{1-\gamma}}{\Gamma(\alpha)} \int_{0}^{t_{1}}\left(t_{1}-s\right)^{\alpha-1} f(s, y(s)) d s\right\| \\
& \leq \frac{1}{\Gamma(\gamma+2 \beta-1)}\left\|y_{1}\right\|\left(t_{2}^{2 \beta-1}-t_{1}^{2 \beta-1}\right)+|\zeta(\beta, \gamma, \eta, \lambda)| \\
& {\left[\left\|y_{0}\right\||\lambda-1|+\frac{|\lambda| T^{2 \beta-1}-\eta^{2 \beta-1}}{\Gamma(2 \beta)}\left\|y_{1}\right\|\right]\left(t_{2}^{2(2 \beta)-2)}-t_{1}^{2(2 \beta)-2)}\right)} \\
& +\frac{|\zeta(\beta, \gamma, \eta, \lambda)|}{\Gamma(\alpha-\gamma+1)}\left[|\lambda| \int_{0}^{T}(T-s)^{\alpha-\gamma}\|f(s, y(s))\| d s+\int_{0}^{\eta}(\eta-s)^{\alpha-\gamma}\|f(s, y(s))\| d s\right] \\
& \left(t_{2}^{2(2 \beta)-2)}-t_{1}^{2(2 \beta)-2)}\right) \\
& +\frac{1}{\Gamma(\alpha)}\left[t_{2}^{1-\gamma} \int_{0}^{t_{1}}\left(t_{2}-s\right)^{\alpha-1}\|f(s, y(s))\| d s-t_{1}^{1-\gamma} \int_{0}^{t_{1}}\left(t_{1}-s\right)^{\alpha-1}\|f(s, y(s))\| d s\right. \\
& \left.+t_{2}^{1-\gamma} \int_{t_{1}}^{t_{2}}\left(t_{2}-s\right)^{\alpha-1}\|f(s, y(s))\| d s\right] \\
& \leq \frac{\left\|y_{1}\right\|}{\Gamma(\gamma+2 \beta-1)}\left(t_{2}^{2 \beta-1}-t_{1}^{2 \beta-1}\right)+|\zeta(\beta, \gamma, \eta, \lambda)|
\end{aligned}
$$

$$
\left[\left\|y_{0}\right\||\lambda-1|+\frac{|\lambda| T^{2 \beta-1}-\eta^{2 \beta-1}}{\Gamma(2 \beta)}\left\|y_{1}\right\|+\frac{1}{\Gamma(\alpha-\gamma+1)}\right.
$$

$$
\left.\left[|\lambda| \int_{0}^{T}(T-s)^{\alpha-\gamma} p(s)\|y\| d s+\int_{0}^{\eta}(\eta-s)^{\alpha-\gamma} p(s)\|y\| d s\right]\right]\left(t_{2}^{2(2 \beta)-2)}-t_{1}^{2(2 \beta)-2)}\right)
$$

$$
+\frac{1}{\Gamma(\alpha)}\left[t_{2}^{1-\gamma} \int_{0}^{t_{1}}\left(t_{2}-s\right)^{\alpha-1} p(s)\|y\| d s-t_{1}^{1-\gamma} \int_{0}^{t_{1}}\left(t_{1}-s\right)^{\alpha-1} p(s)\|y\| d s\right.
$$

$$
\left.+t_{2}^{1-\gamma} \int_{t_{1}}^{t_{2}}\left(t_{2}-s\right)^{\alpha-1} p(s)\|y\| d s\right]
$$

$$
\leq \frac{\left\|y_{1}\right\|}{\Gamma(\gamma+2 \beta-1)}\left(t_{2}^{2 \beta-1}-t_{1}^{2 \beta-1}\right)+|\zeta(\beta, \gamma, \eta, \lambda)|
$$

$$
\left[\left\|y_{0}\right\||\lambda-1|+\frac{|\lambda| T^{2 \beta-1}-\eta^{2 \beta-1}}{\Gamma(2 \beta)}\left\|y_{1}\right\|+\frac{R}{\Gamma(\alpha-\gamma+1)}\right.
$$

$$
\left.\left[|\lambda| \int_{0}^{T}(T-s)^{\alpha-\gamma} p(s) d s+\int_{0}^{\eta}(\eta-s)^{\alpha-\gamma} p(s) d s\right]\right]\left(t_{2}^{2(2 \beta)-2)}-t_{1}^{2(2 \beta)-2)}\right)
$$

$$
+\frac{R}{\Gamma(\alpha)}\left[t_{2}^{1-\gamma} \int_{0}^{t_{1}}\left(t_{2}-s\right)^{\alpha-1} p(s) d s-t_{1}^{1-\gamma} \int_{0}^{t_{1}}\left(t_{1}-s\right)^{\alpha-1} p(s) d s\right.
$$

$$
\left.+t_{2}^{1-\gamma} \int_{t_{1}}^{t_{2}}\left(t_{2}-s\right)^{\alpha-1} p(s) d s\right]
$$

$$
\leq \frac{\left\|y_{1}\right\|}{\Gamma(\gamma+2 \beta-1)}\left(t_{2}^{2 \beta-1}-t_{1}^{2 \beta-1}\right)
$$

$$
+|\zeta(\beta, \gamma, \eta, \lambda)|\left[\left\|y_{0}\right\||\lambda-1|+\frac{|\lambda| T^{2 \beta-1}-\eta^{2 \beta-1}}{\Gamma(2 \beta)}\left\|y_{1}\right\|\right.
$$

$$
\left.+\frac{R p^{*}}{\Gamma(\alpha-\gamma+1)}\left[|\lambda| \int_{0}^{T}(T-s)^{\alpha-\gamma} d s+\int_{0}^{\eta}(\eta-s)^{\alpha-\gamma} d s\right]\right]\left(t_{2}^{2(2 \beta)-2)}-t_{1}^{2(2 \beta)-2)}\right)
$$

$$
+\frac{R p^{*}}{\Gamma(\alpha)}\left[t_{2}^{1-\gamma} \int_{0}^{t_{1}}\left(t_{2}-s\right)^{\alpha-1} d s-t_{1}^{1-\gamma} \int_{0}^{t_{1}}\left(t_{1}-s\right)^{\alpha-1} d s+t_{2}^{1-\gamma} \int_{t_{1}}^{t_{2}}\left(t_{2}-s\right)^{\alpha-1} d s\right]
$$

$$
\begin{aligned}
& \leq \frac{\left\|y_{1}\right\|}{\Gamma(\gamma+2 \beta-1)}\left(t_{2}^{2 \beta-1}-t_{1}^{2 \beta-1}\right) \\
& +|\zeta(\beta, \gamma, \eta, \lambda)|\left[\left\|y_{0}\right\||\lambda-1|+\frac{|\lambda| T^{2 \beta-1}-\eta^{2 \beta-1}}{\Gamma(2 \beta)}\left\|y_{1}\right\|+\frac{R p^{*}\left(|\lambda| T^{\alpha-\gamma+1}+\eta^{\alpha-\gamma+1}\right)}{\Gamma(\alpha-\gamma+2)}\right] \\
& \left(t_{2}^{2(2 \beta)-2)}-t_{1}^{2(2 \beta)-2)}\right)+\frac{R p^{*}}{\Gamma(\alpha+1)}\left(t_{2}^{\alpha-\gamma+1}-t_{1}^{\alpha-\gamma+1}\right)
\end{aligned}
$$

As $t_{1} \rightarrow t_{2}$, the right hand side of the above inequality tends to zero.
Hence $N(D) \subset D$.
Now we show that the implication holds:
Let $V \subset D$ such that $V=\overline{\operatorname{conv}}(N(V) \cup\{0\})$.
We have $V(t) \subset \overline{\operatorname{conv}}(N(V) \cup\{0\})$ for all $t \in J . N V(t) \subset N D(t), t \in J$ is bounded and equicontinuous in $E$, the function $t \rightarrow v(t)=\mu(V(t))$ is continuous on $J$.
By assumption (H2), and the properties of the measure $\mu$ we have for each $t \in J$.

$$
\begin{aligned}
& \left.t^{1-\gamma} v(t) \leq \mu\left(t^{1-\gamma} N(V)(t) \cup\{0\}\right)\right) \leq \mu\left(t^{1-\gamma}(N V)(t)\right) \\
& \leq \mu\left[t ^ { 1 - \gamma } \left[I^{\alpha} f(t, y(t))+\frac{y_{0}}{\Gamma(\gamma)} t^{\gamma-1}+\frac{y_{1}}{\Gamma(\gamma)} t^{\gamma+2 \beta-2}+\zeta(\beta, \gamma, \eta, \lambda)\right.\right. \\
& \left.\left.\left(y_{0}(\lambda-1)+\frac{\lambda T^{2 \beta-1}-\eta^{2 \beta-1}}{\Gamma(2 \beta)} y_{1}+\lambda I^{\alpha-\gamma+1} f(T, y(T))-I^{\alpha-\gamma+1} f(\eta, y(\eta))\right) t^{\gamma+2(2 \beta)-3}\right]\right] \\
& \leq \mu\left[\frac{t^{1-\gamma}}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1} f(s, y(s)) d s+\frac{|\zeta(\beta, \gamma, \eta, \lambda)|}{\Gamma(\alpha-\gamma+1)}\right. \\
& \left.\left(|\lambda| \int_{0}^{T}(T-s)^{\alpha-\gamma} f(s, y(s)) d s+\int_{0}^{\eta}(\eta-s)^{\alpha-\gamma} f(s, y(s)) d s\right) t^{2(2 \beta)-2}\right] \\
& \leq\left[\frac{t^{1-\gamma}}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1} \mu(f(s, y(s))) d s+\frac{|\zeta(\beta, \gamma, \eta, \lambda)|}{\Gamma(\alpha-\gamma+1)}\right. \\
& \left.\left(|\lambda| \int_{0}^{T}(T-s)^{\alpha-\gamma} \mu(f(s, y(s))) d s+\int_{0}^{\eta}(\eta-s)^{\alpha-\gamma} \mu(f(s, y(s))) d s\right) t^{2(2 \beta)-2}\right] \\
& \leq\left[\frac{t^{1-\gamma}}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1} p(s) \mu(V(s)) d s+\frac{|\zeta(\beta, \gamma, \eta, \lambda)|}{\Gamma(\alpha-\gamma+1)}\right. \\
& \left.\left(|\lambda| \int_{0}^{T}(T-s)^{\alpha-\gamma} p(s) \mu(V(s)) d s+\int_{0}^{\eta}(\eta-s)^{\alpha-\gamma} p(s) \mu(V(s)) d s\right) t^{2(2 \beta)-2}\right] \\
& \leq\left[\frac{t^{1-\gamma}}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1} p(s) v(s) d s+\frac{|\zeta(\beta, \gamma, \eta, \lambda)|}{\Gamma(\alpha-\gamma+1)}\right. \\
& \left.\left(|\lambda| \int_{0}^{T}(T-s)^{\alpha-\gamma} p(s) v(s) d s+\int_{0}^{\eta}(\eta-s)^{\alpha-\gamma} p(s) v(s) d s\right) t^{2(2 \beta)-2}\right] \\
& \leq\|v\|\left[\frac{t^{1-\gamma}}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1} p(s) d s+\frac{|\zeta(\beta, \gamma, \eta, \lambda)|}{\Gamma(\alpha-\gamma+1)}\right. \\
& \left.\left(|\lambda| \int_{0}^{T}(T-s)^{\alpha-\gamma} p(s) d s+\int_{0}^{\eta}(\eta-s)^{\alpha-\gamma} p(s) d s\right) t^{2(2 \beta)-2}\right] \\
& \leq p^{*}\|v\|\left[\frac{t^{1-\gamma}}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1} d s+\frac{|\zeta(\beta, \gamma, \eta, \lambda)|}{\Gamma(\alpha-\gamma+1)}\left(|\lambda| \int_{0}^{T}(T-s)^{\alpha-\gamma} d s+\int_{0}^{\eta}(\eta-s)^{\alpha-\gamma} d s\right) t^{2(2 \beta)-2}\right] \\
& \leq p^{*}\|v\|\left[\frac{t^{\alpha-\gamma+1}}{\Gamma(\alpha+1)}+\frac{|\zeta(\beta, \gamma, \eta, \lambda)|}{\Gamma(\alpha-\gamma+2)}\left(|\lambda| T^{\alpha-\gamma+1}+\eta^{\alpha-\gamma+1}\right) t^{2(2 \beta)-2}\right]
\end{aligned}
$$

This means that

$$
\|v\| \leq p^{*}\|v\|\left[\frac{T^{\alpha-\gamma+1}}{\Gamma(\alpha+1)}+\frac{|\zeta(\beta, \gamma, \eta, \lambda)|}{\Gamma(\alpha-\gamma+2)}\left(|\lambda| T^{\alpha-\gamma+1}+\eta^{\alpha-\gamma+1}\right) T^{2(2 \beta)-2}\right]
$$

By $p^{*}\left[\frac{T^{\alpha-\gamma+1}}{\Gamma(\alpha+1)}+\frac{|\zeta(\beta, \gamma, \eta, \lambda)|}{\Gamma(\alpha-\gamma+2)}\left[|\lambda| T^{\alpha-\gamma+1}+\eta^{\alpha-\gamma+1}\right] T^{2(2 \beta)-2}\right]<1$ it follows that $\|v\|=0$, that is $v(t)=0$ for each $t \in J$, and then $V(t)$ is relatively compact in $E$. In view of the Ascoli-Arzela theorem, $V$ is relatively compact in $D$. Applying now Theorem 2.16 , we conclude that $N$ has a fixed point which is a solution of the problem (1.1)-(1.2).

## 4 Example

We consider the problem for Hilfer fractional differential equations of the form:

$$
\left\{\begin{array}{l}
D^{\alpha, \beta} y(t)=f(t, y(t)),(t, y) \in([0,1], \mathbb{R})  \tag{4.1}\\
I^{1-\gamma} y(0)=y_{0}, I^{3-\gamma-2 \beta} y^{\prime}(0)=y_{1}, I^{1-\gamma} y(\eta)=\lambda\left(I^{1-\gamma} y(T)\right)
\end{array}\right.
$$

Here

$$
\begin{array}{lll}
\alpha=\frac{1}{2}, & \beta=\frac{1}{2}, & \gamma=\frac{3}{4} \\
\lambda=\frac{1}{2}, & \eta=\frac{1}{4}, & T=1
\end{array}
$$

With

$$
f(t, y t))=\frac{1}{4}+\frac{c t^{2}}{e^{t+4}}|y(t)|, \quad t \in[0,1]
$$

and

$$
c=\frac{e^{3}}{10} \sqrt{\pi}
$$

Clearly, the function f is continuous. For each $y \in E$ and $t \in[0,1]$, we have

$$
\|f(t, y(t))\| \leq \frac{c t^{2}}{e^{t+4}}\|y\|
$$

Hence, the hypothesis (H2) is satisfied with $p^{*}=c e^{-3}$. We shall show that condition 3.4 holds with $T=1$. Indeed,

$$
p^{*}\left[\frac{T^{\alpha-\gamma+1}}{\Gamma(\alpha+1)}+\frac{|\zeta(\beta, \gamma, \eta, \lambda)|}{\Gamma(\alpha-\gamma+2)}\left[|\lambda| T^{\alpha-\gamma+1}+\eta^{\alpha-\gamma+1}\right] T^{2(2 \beta)-2}\right]<1
$$

Simple computations show that all conditions of Theorem 3.1 are satisfied. It follows that the problem 4.1 has a solution defined on $[0, T]$.

## References

[1] S. Abbas, M. Benchohra, M. Bohner, Weak Solutions for Implicit Differential Equations with Hilfer-Hadamard Fractional Derivative, Advances in Dynamical Systems and Applications, Volume 12, Number 1, pp. 1-16 (2017)
[2] S. Abbas, M. Benchohra, J.E. Lazreg, J. J. Nieto, On a coupled system of Hilfer and HilferHadamard fractional defferential equation in Banach spaces, J. Nonlinear Funct. Anal. 2018 (2018), Article ID 12.
[3] S. Abbas, M. Benchohra, J.E. Lazreg, Y. Zhou, A Survey on Hadamard and Hilfer fractional differential equations:analysis and stability, Chaos, Solitons Fractals 102 (2017), 47-71.
[4] R.P. Agarwal, M. Benchohra, D. Seba, On the application of measure of noncompactness to the existence of solutions for fractional differential equations, Results Math. 55:3-4 (2009) 221-230.
[5] R. P. Agarwal, M. Meehan and D. ORegan, Fixed Point Theory and Applications, Cambridge Tracts in Mathematics, 141, Cambridge University Press, Cambridge, 2001.
[6] A. Aghajani, A. M. Tehrani, D. O'Regan, Some New Fixed Point Results via the Concept of Measure of Noncompactness, Filomat 29:6 (2015), 1209-1216.
[7] R. R. Akhmerov, M. I. Kamenskii, A. S. Patapov, A. E. Rodkina and B. N. Sadovskii, Measures of Noncompactness and Condensing Operators, trans. from the Russian by A. Iacob, Birkhauser Verlag, Basel, 1992.
[8] J. C. Alvàrez, Measure of noncompactness and fixed points of nonexpansive condensing mappings in locally convex spaces, Rev. Real. Acad. Cienc. Exact. Fis. Natur. Madrid 79 (1985), 53-66.
[9] J. M. Ayerbee Toledano, T. Dominguez Benavides, G. Lopez Acedo, Measures of Noncompactness in Metric Fixed Point Theory, Operator Theory, Advances and Applications, vol 99, Birkhäuser, Basel, Boston, Berlin, 1997.
[10] J. Banas, Applications of measures of weak noncompactness and some classes of operators in the theory of functional equations in the Lebesgue space, Nonlinear Anal. 30 (1997), 3283-3293.
[11] J. Banas and K. Goebel, Measures of Noncompactness in Banach Spaces, Lecture Notes in Pure and Applied Mathematics, Volume 60, Marcel Dekker, New York, 1980.
[12] J. Banas, M. Jleli, M. Mursaleen, B. Samet,C. Vetro, Advances in Nonlinear Analysis via the Concept of Measure of Noncompactness, Springer Nature Singapore Pte Ltd. 2017.
[13] J. Banas, R. Nalepa, On a measure of noncompactness in the space of functions with tempered increments, J. Math. Anal. Appl. 435 (2016) 1634-1651.
[14] J. Banas and L. Olszowy, Measures of noncompactness related to monotonicity, Comment. Math. 41 (2001), 13-23.
[15] J. Banas and B. Rzepka, An application of a measure of noncompactness in the study of asymptotique stability, Appl. Math. Lett. 16 (2003), 1-6.
[16] J. Banas and K. Sadarangani, On some measures of noncompactness in the space of continuous functions, Nonlinear Anal. 68 (2008), 377-383.
[17] M. Benchohra, J. Henderson, D. Seba, Measure of noncompactness and fractional differential equations in Banach spaces, Commun. Appl. Anal. 12 (2008) 419-428.
[18] M. Benchohra, G.M. N'Guérékata, D. Seba, Measure of noncompactness and nondensely defined semilinear functional differential equations with fractional order, CUBO A Math. J. 12:3 (2010) 33-46.
[19] K. M. Furati, M. D. Kassim and N.e.Tatar, Existence and uniqueness for a problem involving Hilfer fractional derivative, Computers Math. Appl,(2012), 1616-1626.
[20] K. M. Furati, M. D. Kassim, N. Tatar, Non-existence of global solutions for a differential equation involving Hilfer fractional derivative, Electronic Journal of Differential Equations, Vol. 2013 (2013), No. 235, pp. 1-10.
[21] H. Gu, J.J. Trujillo, Existence of mild solution for evolution equation with Hilfer fractional derivative, Appl. Math. Comput. 257 (2015), 344-354.
[22] R. Hilfer, Applications of Fractional Calculus in Physics, World Scientific, Singapore, (2000).
[23] R.Hilfer, Y.Luchko, Z. Tomovski, Operational method for the solution of fractional differential equations with generalized Riemann-Lioville fractional derivative, Fractional calculus and Applications Analysis, 12 (2009), 289-318.
[24] [15] R. Kamocki, C. Obcznnski, On fractional Cauchy-type problems containing Hilfer derivative, Electronic Journal of Qualitative of Differential Equations, 50 (2016), 1-12.
[25] A. A. Kilbas, H. M. Srivastava and J. J. Trujillo, Theory and Applications of Fractional Differential Equations, North-Holland Mathematics Studies 204, Editor: Jan Van Mill, Elsevier, Amsterdam, The Netherlands, (2006).
[26] C. Kou, J. Liu, and Y. Ye, Existence and uniqueness of solutions for the Cachy-type problems of fractional differential equaitions, Discrete Dyn. Nat. Soc., Article ID 142175, (2010), 1-15.
[27] H. Mönch, Boundary value problems for nonlinear ordinary differential equations of second order in Banach spaces, Nonlinear Anal. 4 (1980), 985-999.
[28] H. K. Nashine,R. Arab, R. P Agarwal,M De la Sen, Positive solutions of fractional integral equations by the technique of measure of noncompactness, Journal of Inequalities and Applications(2017) 2017:225 .
[29] H.Rebai,D.Seba, Weak Solutions for Nonlinear Fractional Differential Equation with Fractional Separated Boundary Conditions in Banach Spaces, Filomat 32:3 (2018), 1117-1125.
[30] S.G. Samko, A.A. Kilbas, O.I. Marichev, Fractional Integrals and Derivatives, Theory and Applications, Gordon and Breach, Yverdon 1993.
[31] Sandeep P. Bhairat, Existence and continuation of solutions of Hilfer fractional differential equations, Journal of Mathematical Modeling, Vol. 7, No. 1, 2019, pp. 1-20.
[32] S. Szufla, On the application of measure of noncompactness to existence theorems, Rend. Sem. Mat. Univ. Padova 75 (1986), 1-14.
[33] D. Vivek, K. Kanagarajan, E. M. Elsayed,Nonlocal initial value problems for implicit differential equations with Hilfer-Hadamard fractional derivative, Nonlinear Analysis: Modelling and Control, Vol. 23, No. 3, 341-360.
[34] D. Vivek, K. Kanagarajan,S. Sivasundaram, On the behavior of solutions of Hilfer-Hadamard type fractional neutral pantograph equations with boundary conditions, Communications in Applied Analysis, 22, No. 2 (2018), 211-232.
[35] J.-R. Wang, Y. Zhang, Nonlocal initial value problems for differential equations with Hilfer fractional derivative, Appl. Math. Comput. 266 (2015), 850-859.
[36] M. Yang, Q.-R. Wang, Approximate controllability of Hilfer fractional differential inclusions with nonlocal conditions, Math. Methods Appl. Sci. 40 (2017), 1126-1138.

