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A GENERALIZED NONLINEAR ITERATIVE ALGORITHM FOR THE EXPLICIT MIDPOINT RULE OF NONEXPANSIVE SEMIGROUP

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ABSTRACT. In this paper, we introduce a new iterative midpoint rule for finding a solution of fixed point problem for a nonexpansive semigroup in real Hilbert spaces. We establish a strong convergence theorem for the sequences generated by our proposed iterative scheme. Furthermore, we provide application to Fredholm integral equations. A numerical example is presented to illustrate the convergence result. Our results improve and extend the corresponding results in the literature.

1. INTRODUCTION

Let \mathbb{R} denote the set of all real numbers, H be a real Hilbert space with inner product $\langle .,. \rangle$ and norm $\|.\|$ and C be a nonempty closed convex subset of H. A mapping $T: C \to C$ is said to be contraction if there exists a constant $\alpha \in (0,1)$ such that $\|T(x) - T(y)\| \leq \alpha \|x - y\|$, for all $x, y \in C$. If $\alpha = 1$, T is called nonexpansive on C.

The fixed point problem (FPP) for a nonexpansive mapping T is: To find $x \in C$ such that $x \in Fix(T)$, where Fix(T) is the fixed point set of the nonexpansive mapping T.

The explicit midpoint rule is one of the powerful numerical methods for solving ordinary differential equations and differential algebraic equations. For related works, we refer to [2, 3, 4, 5, 9, 10, 11, 16, 19, 20, 21, 22, 23, 25, 27, 28] and the references cited therein. For instance, consider the initial value problem for the differential equation y'(t) = f(y(t)) with the initial condition $y(0) = y_0$, where fis a continuous function from \mathbb{R}^d to \mathbb{R}^d . The explicit midpoint rule in which a

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sequence $\{y_n\}$ is generated by the following the recurrence relation

$$\frac{1}{h}(y_{n+1} - y_n) = f(\frac{y_{n+1} - y_n}{2}).$$

In 2015, Xu et al. [30] extended and generalized the results of Alghamdi et al. [1] and applied the viscosity method on the midpoint rule for nonexpansive mappings and they gave the generalized viscosity explicit method:

$$x_{n+1} = \alpha_n f(x_n) + \beta_n x_n + (1 - \alpha_n) T(\frac{x_n + x_{n+1}}{2}).$$

In 2016, Rizvi [24] introduced the following iterative method for the explicit midpoint rule of nonexpansive mappings:

$$x_{n+1} = \alpha_n \gamma f(x_n) + (1 - \alpha_n B)T(\frac{x_n + x_{n+1}}{2}).$$

A family $S := \{T(s) : 0 \le s < \infty\}$ of mappings from C into itself is called a nonexpansive semigroup on C if it satisfies the following conditions:

- (1) T(0)x = x for all $x \in C$
- (2) T(s+t) = T(s)T(t) for all $s, t \ge 0$
- (3) $\|T(s)x T(s)y\| \le \|x y\|$ for all $x, y \in C$ and $s \ge 0$
- (4) For all $x \in C, s \to T(s)x$ is continuous.

Plubtieng and Punpaeng [18] introduced and studied the following iterative method to prove a strong convergence theorem for FPP in a real Hilbert space:

$$x_{n+1} = \alpha_n f(x_n) + \beta_n x_n + (1 - \alpha_n - \beta_n) \frac{1}{s_n} \int_0^{s_n} T(s) x_n ds, \qquad \forall n \in \mathbb{N}.$$

where f is a contraction mapping and $\{\alpha_n\}$ and $\{\beta_n\}$ are the sequences in (0,1) and $\{s_n\}$ is a positive real divergent sequence.

Kang et al. [12] considered an iterative algorithm in a Hilbert space as follows:

$$x_{n+1} = \alpha_n \gamma f(x_n) + \beta_n x_n + ((1-\beta_n)I - \alpha_n A) \frac{1}{s_n} \int_0^{s_n} T(s) x_n ds.$$

Under the certain conditions, the sequence $\{x_n\}$ strongly converges to a unique solution of the variational inequality $\langle (\gamma f - A)x^*, x - x^* \rangle \leq 0, \ \forall x \in Fix(T).$

Motivated and inspired by the results mentioned and related literature in [1, 12, 24, 30], we propose an iterative midpoint algorithm based on the viscosity method for finding a common element of the set of solutions of nonexpansive semigroup in Hilbert spaces. Then we prove strong convergence theorems that extend and improve the corresponding results of Rizvi [24], Xu [30], and others. Finally, we give an example and numerical result to illustrate our main result.

The rest of paper is organized as follows. The next section presents some preliminary results. Section 3 is devoted to introduce midpoint algorithm for solving it. The last section presents a numerical example to demonstrate the proposed algorithms.

2. Preliminaries

For each point $x \in H$, there exists a unique nearest point of C, denote by $P_C x$, such that $||x - P_C x|| \leq ||x - y||$ for all $y \in C$. P_C is called the metric projection of H onto C. It is well known that P_C is nonexpansive mapping and is characterized by the following property:

$$\langle x - P_C x, y - P_C y \rangle \le 0 \tag{1}$$

Further, it is well known that every nonexpansive operator $T: H \to H$ satisfies, for all $(x, y) \in H \times H$, inequality

$$\langle (x - T(x)) - (y - T(y)), T(y) - T(x) \rangle \le (\frac{1}{2}) \| (T(x) - x) - (T(y) - y) \|^2,$$
 (2)

and therefore, we get, for all $(x, y) \in H \times Fix(T)$,

$$\langle (x - T(x)), (y - T(y)) \rangle \le (\frac{1}{2}) \| (T(x) - x) \|^2,$$
(3)

see, e.g. [8].

It is also known that H satisfies Opial's condition [17], i.e., for any sequence $\{x_n\}$ with $x_n \rightharpoonup x$, the inequality

$$\liminf_{n \to \infty} \|x_n - x\| < \liminf_{n \to \infty} \|x_n - y\|$$
(4)

holds for every $y \in H$ with $y \neq x$.

Lemma 1. [6] The following inequality holds in real space H:

$$||x+y||^2 \le ||x||^2 + 2\langle y, x+y \rangle, \qquad \forall x, y \in H.$$

Definition 2. A mapping $M : C \to H$ is said to be monotone, if

$$\langle Mx - My, x - y \rangle \ge 0, \qquad \forall x, y \in C.$$

M is called α -inverse-strongly-monotone if there exist a positive real number α such that

$$\langle Mx - My, x - y \rangle \ge \alpha \|Mx - My\|^2, \quad \forall x, y \in C.$$

Definition 3. A mapping $B : H \to H$ is said to be strongly positive linear bounded operator, if there exists a constant $\bar{\gamma} > 0$ such that $\langle Bx, x \rangle \geq \bar{\gamma} ||x||^2$, $\forall x \in H$.

Lemma 4. [15] Assume that B is a strong positive linear bounded self adjoint operator on a Hilbert space H with coefficient $\bar{\gamma} > 0$ and $0 < \rho \leq ||B||^{-1}$. Then $||I - \rho B|| \leq 1 - \rho \bar{\gamma}$.

Lemma 5. [26] Let C be a nonempty bounded closed convex subset of a Hilbert space H and let $S = \{T(s) : 0 \le s < \infty\}$ be a nonexpansive semigroup on C. For each $x \in C$ and t > 0. Then, for any $0 \le h < \infty$,

$$\lim_{t \to \infty} \sup_{x \in C} \|\frac{1}{t} \int_0^t T(s) x ds - T(h) (\frac{1}{t} \int_0^t T(s) x ds)\| = 0.$$

Lemma 6. [29] Let $\{a_n\}$ be a sequence of nonnegative real numbers such that $a_{n+1} \leq (1 - \alpha_n)a_n + \delta_n$, $n \geq 0$ where α_n is a sequence in (0, 1) and δ_n is a sequence in \mathbb{R} such that

(*i*) $\Sigma_{n=1}^{\infty} \alpha_n = \infty$; (*ii*) $\limsup_{n \to \infty} \frac{\delta_n}{\alpha_n} \le 0$ or $\Sigma_{n=1}^{\infty} \delta_n < \infty$. Then $\lim_{n \to \infty} a_n = 0$.

3. Nonlinear midpoint algorithm

In this section, we prove a strong convergence theorem based on the explicit iterative for fixed point of nonexpansive semigroup. We firstly present the following unified algorithm.

Let $S = \{T(s) : s \in [0, +\infty)\}$ be a nonexpansive semigroup on C such that $Fix(S) \neq \emptyset$. Also $f : C \to H$ be a α -contraction mapping and B, D be strongly positive bounded linear self adjoint operators on H with coefficients $\bar{\gamma}_1, \bar{\gamma}_2 > 0$ such that $0 < \gamma < \frac{\bar{\gamma}_1}{\alpha} < \gamma + \frac{1}{\alpha}, \bar{\gamma}_1 \leq ||B|| \leq 1$ and $||D|| = \bar{\gamma}_2 \leq 1$.

Algorithm 7. For given $x_0 \in C$ arbitrary, let the sequence $\{x_n\}$ be generated by:

$$x_{n+1} = \alpha_n \gamma f(x_n) + \beta_n D x_n + ((1 - \epsilon_n)I - \beta_n D - \alpha_n B) \frac{1}{s_n} \int_0^{s_n} T(s) (\frac{x_n + x_{n+1}}{2}) ds.$$
(5)

where $\{\alpha_n\}$, $\{\beta_n\}$, $\{\epsilon_n\}$ are the sequence in (0,1) such that $\epsilon_n \leq \alpha_n$ and $\{s_n\} \subset [s,\infty)$ with s > 0 satisfying conditions:

(C1)

$$\lim_{n \to \infty} \alpha_n = \lim_{n \to \infty} \beta_n = \lim_{n \to \infty} \epsilon_n = 0, \ \Sigma_{n=1}^{\infty} \alpha_n = \Sigma_{n=1}^{\infty} \beta_n = \infty;$$

(C2)

$$\sum_{n=1}^{\infty} |\alpha_n - \alpha_{n-1}| < \infty \quad or \quad \lim_{n \to \infty} \frac{\alpha_{n+1}}{\alpha_n} = 1;$$
$$\sum_{n=1}^{\infty} |\beta_n - \beta_{n-1}| < \infty \quad or \quad \lim_{n \to \infty} \frac{\beta_{n+1}}{\beta_n} = 1;$$
$$\sum_{n=1}^{\infty} |\epsilon_n - \epsilon_{n-1}| < \infty \quad or \quad \lim_{n \to \infty} \frac{\epsilon_{n+1}}{\epsilon_n} = 1;$$

(C3)

$$\lim_{n \to \infty} s_n = \infty, \ \sup_{n \in \mathbb{N}} |s_{n+1} - s_n| \ is \ bounded.$$

Lemma 8. For any $0 < \gamma < \frac{\bar{\gamma}_1}{\alpha} < \gamma + \frac{1}{\alpha}$, there exists a unique fixed point for sequence $\{x_n\}$.

Proof. As a matter of fact, for fixed $x \in C$, we can define the sequence $\{P_n : H \to H\}$ as follows:

$$P_n(x) := \alpha_n \gamma f(x) + \beta_n Dx + ((1 - \epsilon_n)I - \beta_n D - \alpha_n B) \frac{1}{s_n} \int_0^{s_n} T(s)x \, ds, \, \forall x \in H.$$

We may assume without loss of generality that $\alpha_n \leq (1 - \epsilon_n - \beta_n ||D||) ||B||^{-1}$. Since ${\cal B}$ and ${\cal D}$ are linear bounded self adjoint operators, we have

 $||B|| = \sup\{|\langle Bx, x\rangle| : x \in H, ||x|| = 1\},\$ $||D|| = \sup\{|\langle Dx, x\rangle| : x \in H, ||x|| = 1\}$

and observe that

$$\langle ((1-\epsilon_n)I - \beta_n D - \alpha_n B)x, x \rangle = (1-\epsilon_n) \langle x, x \rangle - \beta_n \langle Dx, x \rangle - \alpha_n \langle Bx, x \rangle \\ \geq 1-\epsilon_n - \beta_n \|D\| - \alpha_n \|B\| \ge 0.$$

Therefore, $(1 - \epsilon_n)I - \beta_n D - \alpha_n B$ is positive. Then, by strong positivity of B and D, we get

$$\begin{aligned} \|(1-\epsilon_n)I - \beta_n D - \alpha_n B\| &= \sup\{\langle ((1-\epsilon_n)I - \beta_n D - \alpha_n B)x, x\rangle : x \in H, \|x\| = 1\} \\ &= \sup\{(1-\epsilon_n)\langle x, x\rangle - \beta_n\langle Dx, x\rangle \\ &- \alpha_n\langle Bx, x\rangle : x \in H, \|x\| = 1\} \\ &\leq 1 - \epsilon_n - \beta_n \bar{\gamma}_2 - \alpha_n \bar{\gamma}_1 \\ &\leq 1 - \beta_n \bar{\gamma}_2 - \alpha_n \bar{\gamma}_1. \end{aligned}$$

$$(6)$$

For any $x, y \in C$

$$\begin{aligned} \|P_n x - P_n y\| &\leq \alpha_n \gamma \|f(x) - f(y)\| + \beta_n \|D\| \|x - y\| \\ &+ \|(1 - \epsilon_n)I - \beta_n D - \alpha_n B\| \frac{1}{s_n} \int_0^{s_n} \|T(s)x - T(s)y\| ds \\ &\leq \alpha_n \gamma \alpha \|x - y\| + \beta_n \bar{\gamma}_2 \|x - y\| + (1 - \beta_n \bar{\gamma}_2 - \alpha_n \gamma_1) \|x - y\| \\ &= (1 - (\gamma_1 - \gamma \alpha) \alpha_n) \|x - y\|. \end{aligned}$$

Therefore, Banach contraction principle guarantees that P_n has a unique fixed point in H, and so the iteration (5) is well defined.

Lemma 9. Let $p \in Fix(S)$. Then the sequence $\{x_n\}$ generated by Algorithm 7 is bounded.

Proof. Let $p \in Fix(S)$, we obtain

$$\begin{split} \|x_{n+1} - p\| &= \|\alpha_n \gamma f(x_n) + \beta_n D x_n \\ &+ ((1 - \epsilon_n)I - \beta_n D - \alpha_n B) \frac{1}{s_n} \int_0^{s_n} T(s) (\frac{x_n + x_{n+1}}{2}) ds - p\| \\ &\leq \alpha_n \|\gamma f(x_n) - Bp\| + \beta_n \|D x_n - Dp\| + \epsilon_n \|p\| \\ &+ \|((1 - \epsilon_n)I - \beta_n D - \alpha_n B)\|\| \frac{1}{s_n} \int_0^{s_n} T(s) (\frac{x_n + x_{n+1}}{2}) - T(s)p\| ds \\ &\leq \alpha_n (\|\gamma f(x_n) - \gamma f(p)\| + \|\gamma f(p) - Bp\|) + \beta_n \|D x_n - Dp\| + \epsilon_n \|p\| \\ &+ (1 - \beta_n \bar{\gamma}_2 - \alpha_n \bar{\gamma}_1)\| \frac{x_n + x_{n+1}}{2} - p\| \\ &\leq \alpha_n \gamma \alpha \|x_n - p\| + \alpha_n \|\gamma f(p) - Bp\| + \beta_n \bar{\gamma}_2 \|x_n - p\| + \alpha_n \|p\| \\ &+ \frac{(1 - \beta_n \bar{\gamma}_2 - \alpha_n \bar{\gamma}_1)}{2} (\|x_n - p\| + \|x_{n+1} - p\|). \end{split}$$

which implies that

$$\frac{1 + \beta_n \bar{\gamma}_2 + \alpha_n \bar{\gamma}_1}{2} \|x_{n+1} - p\| \leq (\alpha_n \gamma \alpha + \frac{1 + \beta_n \bar{\gamma}_2 - \alpha_n \bar{\gamma}_1}{2}) \|x_n - p\| + \alpha_n (\|\gamma f(p) - Bp\| + \|p\|).$$

Then

$$\begin{aligned} \|x_{n+1} - p\| &\leq (1 - \frac{2(\bar{\gamma}_1 - \gamma\alpha)\alpha_n}{1 + \beta_n \bar{\gamma}_2 + \alpha_n \bar{\gamma}_1}) \|x_n - p\| + \frac{2\alpha_n(\bar{\gamma}_1 - \gamma\alpha)}{1 + \beta_n \bar{\gamma}_2 + \alpha_n \bar{\gamma}_1} \frac{\|\gamma f(p) - Bp\| + \|p\|}{\bar{\gamma}_1 - \gamma\alpha} \\ &\leq \max\{\|x_n - p\|, \frac{\|\gamma f(p) - Bp\| + \|p\|}{\bar{\gamma}_1 - \gamma\alpha}\} \\ &\vdots \\ &\leq \max\{\|x_0 - p\|, \frac{\|\gamma f(p) - Bp\| + \|p\|}{\bar{\gamma}_1 - \gamma\alpha}\}. \end{aligned}$$
(7)

Hence $\{x_n\}$ is bounded.

Now, set $t_n := \frac{1}{s_n} \int_0^{s_n} T(s)(\frac{x_n + x_{n+1}}{2}) ds$. Then $\{t_n\}$ and $\{f(x_n)\}$ are bounded.

Lemma 10. The following properties are satisfying for the Algorithm 7 P1. $\lim_{n\to\infty} ||x_{n+1} - x_n|| = 0.$ P2. $\lim_{n\to\infty} ||x_n - t_n|| = 0.$ P3. $\lim_{n\to\infty} ||T(s)t_n - t_n|| = 0.$

Lemma 11. In order to prove P1, one can write

$$\begin{split} \|t_{n+1} - t_n\| &= \|\frac{1}{s_{n+1}} \int_0^{s_{n+1}} T(s) (\frac{x_{n+1} + x_{n+2}}{2}) ds - \frac{1}{s_n} \int_0^{s_n} T(s) (\frac{x_n + x_{n+1}}{2}) ds \| \\ &= \|\frac{1}{s_{n+1}} \int_0^{s_{n+1}} (T(s) (\frac{x_{n+1} + x_{n+2}}{2}) - T(s) (\frac{x_n + x_{n+1}}{2})) ds \\ &+ (\frac{1}{s_{n+1}} - \frac{1}{s_n}) \int_0^{s_n} T(s) (\frac{x_n + x_{n+1}}{2}) ds \\ &+ \frac{1}{s_{n+1}} \int_{s_n}^{s_{n+1}} T(s) (\frac{x_{n+1} + x_{n+2}}{2}) - T(s) (\frac{x_n + x_{n+1}}{2})) ds \\ &= \|\frac{1}{s_{n+1}} \int_0^{s_{n+1}} (T(s) (\frac{x_n + x_{n+1}}{2}) - T(s) (\frac{x_n + x_{n+1}}{2})) ds \\ &+ (\frac{1}{s_{n+1}} - \frac{1}{s_n}) \int_0^{s_n} (T(s) (\frac{x_n + x_{n+1}}{2}) - T(s)p) ds \\ &+ \frac{1}{s_{n+1}} \int_{s_n}^{s_{n+1}} (T(s) (\frac{x_n + x_{n+1}}{2}) - T(s)p) ds \| \\ &\leq \|\frac{x_{n+1} + x_{n+2}}{2} - \frac{x_n + x_{n+1}}{2}\| + \frac{|s_{n+1} - s_n|s_n}{s_{n+1}s_n}\|\frac{x_n + x_{n+1}}{2} - p\| \end{split}$$

$$+\frac{|s_{n+1}-s_n|}{s_{n+1}} \|\frac{x_n+x_{n+1}}{2}-p\|\frac{1}{2}(\|x_{n+1}-x_n\|+\|x_{n+2}-x_{n+1}\|)$$

$$\leq +\frac{|s_{n+1}-s_n|}{s_{n+1}}(\|x_n-p\|+\|x_{n+1}-p\|).$$
(8)

Next, we show that the sequence $\{x_n\}$ is asymptotically regular, i.e., $\lim_{n\to\infty} ||x_{n+2} - x_{n+1}|| = 0$. By (8) we estimate that

Therefore

$$\begin{split} \|x_{n+2} - x_{n+1}\| &\leq (1 - \frac{2(\beta_{n+1}\bar{\gamma}_2 + (\bar{\gamma}_1 - \alpha\gamma)\alpha_{n+1})}{1 + \alpha_{n+1}\bar{\gamma}_1 + \beta_{n+1}\bar{\gamma}_2}) \|x_{n+1} - x_n\| \\ &+ (\frac{1 - \beta_{n+1}\bar{\gamma}_2 - \alpha_{n+1}\bar{\gamma}_1}{1 + \alpha_{n+1}\bar{\gamma}_1 + \beta_{n+1}\bar{\gamma}_2}) (\frac{2|s_{n+1} - s_n|}{s_{n+1}}) (\|x_n - p\| + \|x_{n+1} - p\|) \\ &+ \frac{2}{1 + \alpha_{n+1}\bar{\gamma}_1 + \beta_{n+1}\bar{\gamma}_2} |\epsilon_{n+1} - \epsilon_n| \|t_n\| + \frac{2M}{1 + \alpha_{n+1}\bar{\gamma}_1 + \beta_{n+1}\bar{\gamma}_2} |\alpha_n - \alpha_{n+1}| \\ &+ \frac{2N}{1 + \alpha_{n+1}\bar{\gamma}_1 + \beta_{n+1}\bar{\gamma}_2} |\beta_n - \beta_{n+1}|. \end{split}$$

Lemma 6 and (C1)-(C2) implies

$$\lim_{n \to \infty} \|x_{n+1} - x_n\| = 0.$$
(9)

And similarly, we have

$$\lim_{n \to \infty} \|x_{n+2} - x_{n+1}\| = 0.$$
(10)

Also by (8), (9),(10) and (C3) we have $\lim_{n\to\infty} ||t_{n+1} - t_n|| = 0$. In order to prove P2, one can write

$$\begin{aligned} \|x_n - t_n\| &\leq \|x_{n+1} - x_n\| \\ &+ \|\alpha_n \gamma f(x_n) + \beta_n D x_n + ((1 - \epsilon_n) I - \beta_n D - \alpha_n B) t_n - t_n\| \\ &\leq \|x_n - x_{n+1}\| + \alpha_n \|\gamma f(x_n) - B t_n\| + \beta_n \bar{\gamma}_2 \|x_n - t_n\| + \epsilon_n \|t_n\|. \end{aligned}$$

Then

$$(1 - \beta_n \bar{\gamma}_2) \|x_n - t_n\| \le \|x_n - x_{n+1}\| + \alpha_n \|\gamma f(x_n) - Bt_n\| + \epsilon_n \|t_n\|.$$

By (C1) and (9), we obtain

$$\lim_{n \to \infty} \|x_n - t_n\| = 0.$$
(11)

 $\lim_{n \to \infty} \|x_n - t_n\| = 0.$ In order to prove P3, set $K := \{ w \in C : \|w - p\| \le \|x_0 - p\| + \frac{1}{\bar{\gamma}_1 - \gamma \alpha} (\|\gamma f(p) - Bp\| + \|p\|) \}.$ Then K is a nonempty bounded closed convex subset of C which is T(s)invariant for each $s \in [0, +\infty)$ and contains $\{x_n\}$. So, without loss of generality, we may assume that $S := \{T(s) : s \in [0, +\infty)\}$ is a nonexpansive semigroup on K.

$$\begin{aligned} \|T(s)x_n - x_n\| &= \|T(s)x_n - T(s)\frac{1}{s_n}\int_0^{s_n} T(s)(\frac{x_n + x_{n+1}}{2})ds \\ &+ T(s)\frac{1}{s_n}\int_0^{s_n} T(s)(\frac{x_n + x_{n+1}}{2})ds \\ &- \frac{1}{s_n}\int_0^{s_n} T(s)(\frac{x_n + x_{n+1}}{2})ds + \frac{1}{s_n}\int_0^{s_n} T(s)(\frac{x_n + x_{n+1}}{2})ds - x_n \\ &\leq \|T(s)x_n - T(s)\frac{1}{s_n}\int_0^{s_n} T(s)(\frac{x_n + x_{n+1}}{2})ds \| \end{aligned}$$

$$\begin{split} + \|T(s)\frac{1}{s_n} \int_0^{s_n} T(s)(\frac{x_n + x_{n+1}}{2})ds &- \frac{1}{s_n} \int_0^{s_n} T(s)(\frac{x_n + x_{n+1}}{2})ds \| \\ + \|\frac{1}{s_n} \int_0^{s_n} T(s)(\frac{x_n + x_{n+1}}{2})ds - x_n\| \\ \leq & \|x_n - \frac{1}{s_n} \int_0^{s_n} T(s)(\frac{x_n + x_{n+1}}{2})ds \| \\ & + \|T(s)\frac{1}{s_n} \int_0^{s_n} T(s)(\frac{x_n + x_{n+1}}{2})ds - \frac{1}{s_n} \int_0^{s_n} T(s)(\frac{x_n + x_{n+1}}{2})ds \| \\ & + \|\frac{1}{s_n} \int_0^{s_n} T(s)(\frac{x_n + x_{n+1}}{2})ds - x_n\| \\ & = & 2\|\frac{1}{s_n} \int_0^{s_n} T(s)(\frac{x_n + x_{n+1}}{2})ds - x_n\| \\ & + \|T(s)\frac{1}{s_n} \int_0^{s_n} T(s)(\frac{x_n + x_{n+1}}{2})ds - \frac{1}{s_n} \int_0^{s_n} T(s)(\frac{x_n + x_{n+1}}{2})ds \| \end{split}$$

Since $\frac{x_n+x_{n+1}}{2} \in C$, from (11) and Lemma 5, we obtain $\lim_{n\to\infty} ||T(s)x_n-x_n|| = 0$. Therefore

$$||T(s)t_n - t_n|| \leq ||T(s)t_n - T(s)x_n|| + ||T(s)x_n - x_n|| + ||x_n - t_n||$$

$$\leq ||t_n - x_n|| + ||T(s)x_n - x_n|| + ||x_n - t_n||.$$

Then we have $\lim_{n\to\infty} ||T(s)t_n - t_n|| = 0.$

4. Convergence algorithm

Theorem 12. The Algorithm (5) converges strongly $z \in Fix(S)$, which is a unique solution of the variational inequality $\langle (\gamma f - B)z, y - z \rangle \leq 0$, for all $y \in Fix(S)$.

Proof. Let
$$q = P_{Fix(S)}$$
. We get
 $\|q(I - B + \gamma f)(x) - q(I - B + \gamma f)(y)\| \leq \|(I - B + \gamma f)(x) - (I - B + \gamma f)(y)\|$
 $\leq \|I - B\| \|x - y\| + \gamma \|f(x) - f(y)\|$
 $\leq (1 - \bar{\gamma}_1) \|x - y\| + \gamma \alpha \|x - y\|$
 $= (1 - (\bar{\gamma}_1 - \gamma \alpha)) \|x - y\|.$

Then $q(I - B + \gamma f)$ is a contraction mapping from H into itself. Therefore by Banach contraction principle, there exists $z \in H$ such that $z = q(I - B + \gamma f)z = P_{Fix(S)}(I - B + \gamma f)z$.

We show that $\langle (\gamma f - B)z, x_n - z \rangle \leq 0$. To show this inequality, we choose a subsequence $\{t_{n_i}\}$ of $\{t_n\}$ such that

$$\limsup_{n \to \infty} \langle (\gamma f - B)z, t_n - z \rangle = \lim_{i \to \infty} \langle (\gamma f - B)z, t_{n_i} - z \rangle.$$
(12)

Since $\{t_{n_i}\}$ is bounded, there exists a subsequence $\{t_{n_{i_j}}\}$ of $\{t_{n_i}\} \subseteq K$ which converges weakly to some $w \in C$. Without loss of generality, we can assume that

 $t_{n_i} \rightharpoonup w$. Now, we prove that $w \in Fix(S)$. Assume that $w \notin Fix(S)$. Since $t_{n_i} \rightharpoonup w$ and $T(s)w \neq w$, from Opial's conditions (4) and Lemma 10 (P3), we have

$$\begin{split} \liminf_{i \to \infty} \|t_{n_i} - w\| &< \liminf_{i \to \infty} \|t_{n_i} - T(s)w\| \\ &\leq \liminf_{i \to \infty} (\|t_{n_i} - T(s)t_{n_i}\| + \|T(s)t_{n_i} - T(s)w\|) \\ &\leq \liminf_{i \to \infty} \|t_{n_i} - w\|, \end{split}$$

which is a contradiction. Thus, we obtain $w \in Fix(S)$. Now from (1), we have

$$\lim_{n \to \infty} \sup_{n \to \infty} \langle (\gamma f - B)z, x_n - z \rangle = \lim_{n \to \infty} \sup_{n \to \infty} \langle (\gamma f - B)z, t_n - z \rangle \\
\leq \lim_{i \to \infty} \sup_{i \to \infty} \langle (\gamma f - B)z, t_{n_i} - z \rangle \quad (13) \\
= \langle (\gamma f - B)z, w - z \rangle \leq 0.$$

Now we prove that x_n is strongly convergence to z.

$$\begin{split} \|x_{n+1} - z\|^2 &= \alpha_n \langle \gamma f(x_n) - Bz, x_{n+1} - z \rangle + \beta_n \langle Dx_n - Dz, x_{n+1} - z \rangle \\ &-\epsilon_n \langle z, x_{n+1} - z \rangle + \langle ((1 - \epsilon_n)I - \beta_n D - \alpha_n B)(t_n - z), x_{n+1} - z \rangle \\ &\leq \alpha_n (\gamma \langle f(x_n) - f(z), x_{n+1} - z \rangle + \langle \gamma f(z) - Bz, x_{n+1} - z \rangle) \\ &+\beta_n \|D\| \|x_n - z\| \|x_{n+1} - z\| - \epsilon_n \|z\| \|x_{n+1} - z\| \\ &+ \|(1 - \epsilon_n)I - \beta_n D - \alpha_n B\| \|t_n - z\| \|x_{n+1} - z\| \\ &\leq \alpha_n \alpha \gamma \|x_n - z\| \|x_{n+1} - z\| + \alpha_n \langle \gamma f(z) - Bz, x_{n+1} - z \rangle \\ &+ \beta_n \tilde{\gamma}_2 \|x_n - z\| \|x_{n+1} - z\| - \epsilon_n \|z\| \|x_{n+1} - z\| \\ &+ (1 - \beta_n \tilde{\gamma}_2 - \alpha_n \tilde{\gamma}_1) \|\frac{x_n + x_{n+1}}{2} - z\| \|x_{n+1} - z\| \\ &\leq \alpha_n \alpha \gamma \|x_n - z\| \|x_{n+1} - z\| + \alpha_n \langle \gamma f(z) - Bz, x_{n+1} - z \rangle \\ &+ \beta_n \tilde{\gamma}_2 \|x_n - z\| \|x_{n+1} - z\| + \alpha_n \langle \gamma f(z) - Bz, x_{n+1} - z \rangle \\ &+ \beta_n \tilde{\gamma}_2 \|x_n - z\| \|x_{n+1} - z\| + \|x_{n+1} - z\| \|x_{n+1} - z\| \\ &= \frac{1 + \beta_n \tilde{\gamma}_2 - \alpha_n (\tilde{\gamma}_1 - 2\alpha\gamma)}{2} \|x_n - z\| \|x_{n+1} - z\| \\ &= \frac{1 + \beta_n \tilde{\gamma}_2 - \alpha_n (\tilde{\gamma}_1 - 2\alpha\gamma)}{4} (\|x_n - z\|^2 + \|x_{n+1} - z\|^2) \\ &+ \alpha_n \langle \gamma f(z) - Bz, x_{n+1} - z \rangle - \epsilon_n \|z\| \|x_{n+1} - z\| \\ &+ \frac{1 - \beta_n \tilde{\gamma}_2 - \alpha_n (\tilde{\gamma}_1 - 2\alpha\gamma)}{2} \|x_{n+1} - z\|^2 \\ &\leq \frac{1 + \beta_n \tilde{\gamma}_2 - \alpha_n (\tilde{\gamma}_1 - 2\alpha\gamma)}{4} \|x_{n+1} - z\|^2 \end{aligned}$$

$$\begin{aligned} &+ \frac{3 - \beta_n \bar{\gamma}_2 - \alpha_n (3\bar{\gamma}_1 - 2\alpha\gamma)}{4} \|x_{n+1} - z\|^2 \\ &+ \alpha_n \langle \gamma f(z) - Bz, x_{n+1} - z \rangle - \epsilon_n \|z\| \|x_{n+1} - z\| \\ &\leq \frac{1 + \beta_n \bar{\gamma}_2 - \alpha_n (\bar{\gamma}_1 - 2\alpha\gamma)}{4} \|x_n - z\|^2 + \frac{3}{4} \|x_{n+1} - z\|^2 \\ &+ \alpha_n \langle \gamma f(z) - Bz, x_{n+1} - z \rangle - \epsilon_n \|z\| \|x_{n+1} - z\|. \end{aligned}$$

This implies that

$$4\|x_{n+1} - z\|^2 \leq (1 + \beta_n \bar{\gamma}_2 - \alpha_n (\bar{\gamma}_1 - 2\alpha\gamma))\|x_n - z\|^2 + 3\|x_{n+1} - z\|^2 + 4\alpha_n \langle \gamma f(z) - Bz, x_{n+1} - z \rangle + 4\epsilon_n \|z\| \|x_{n+1} - z\|.$$

Then

$$||x_{n+1} - z||^{2} \leq (1 - (\alpha_{n}(\bar{\gamma}_{1} - 2\alpha\gamma) - \beta_{n}\bar{\gamma}_{2}))||x_{n} - z||^{2} + 4\alpha_{n}\langle\gamma f(z) - Bz, x_{n+1} - z\rangle + 4\epsilon_{n}||z||||x_{n+1} - z|| = (1 - k_{n})||x_{n} - z||^{2} + 4\alpha_{n}l_{n},$$
(14)

where $k_n = \alpha_n(\bar{\gamma}_1 - 2\alpha\gamma) + \beta_n \bar{\gamma}_2$ and $l_n = \langle \gamma f(z) - Bz, x_{n+1} - z \rangle - \|z\| \|x_{n+1} - z\|$. Since $\lim_{n \to \infty} \alpha_n = \lim_{n \to \infty} \beta_n = 0$ and $\sum_{n=0}^{\infty} \alpha_n = \sum_{n=0}^{\infty} \beta_n = \infty$, it is easy to see that $\lim_{n \to \infty} k_n = 0$, $\sum_{n=0}^{\infty} k_n = \infty$ and $\limsup_{n \to \infty} l_n \leq 0$. Hence, from (13) and (14) and Lemma 6, we deduce that $x_n \to z$, where $z = P_{Fix(S)}(I - B + \gamma f)z$. \Box

5. Numerical examples

In this section, we give some examples and numerical results for supporting our main theorem. All the numerical results have been produced in Matlab 2017 on a Linux workstation with a 3.8 GHZ Intel annex processor and 8 Gb of memory

Example 13. Consider a Fredholm integral equation of the following form

$$x(t) = g(t) + \int_0^t F(t, k, x(k)) \quad dk, \qquad t \in [0, 1],$$
(15)

where g is a continuous function on [0,1] and $F: [0,1] \times [0,1] \times R \rightarrow R$ is continuous. Note that if F satisfies the Lipschitz continuity condition, i.e.,

$$|F(t,k,x) - F(t,k,y)| \le |x-y|, \qquad \forall t,k \in [0,1], \quad x,y \in \mathbb{R},$$

then equation (15) has at least one solution in $L^2[0,1]$ (see [13]). Define a mapping $T(s): L^2[0,1] \to L^2[0,1]$ by

$$(T(s)x)(t) = e^{-3s}(g(t) + \int_0^t F(t,k,x(k)) \ dk), \qquad t \in [0,1].$$

It is easy to observe that $S = \{T(s) : s \in [0, +\infty)\}$ is a nonexpansive semigroup. In fact, we have, for $x, y \in L^2[0, 1]$,

$$||T(s)x - T(s)y||^2 = \int_0^1 |(T(s)x)(t) - (T(s)y)(t)|^2 dt$$

$$= \int_{0}^{1} |e^{-3s} \int_{0}^{1} (F(t,k,x(k)) - F(t,k,y(k))) dk|^{2} dt$$

$$\leq \int_{0}^{1} (\int_{0}^{1} |x(k) - y(k)|^{2} dk) dt$$

$$= \int_{0}^{1} |x(k) - y(k)|^{2} dk$$

$$= ||x - y||^{2}.$$

This means that to find the solution of integral equation (15) is reduced to find a fixed point of the nonexpansive semigroup S in $L^2[0,1]$. For any given function $x_0 \in L^2[0,1]$, define a sequence of functions x_n in $L^2[0,1]$ by

$$x_{n+1} = \alpha_n \gamma f(x_n) + \beta_n D x_n + ((1 - \epsilon_n)I - \beta_n D - \alpha_n B) \frac{1}{s_n} \int_0^{s_n} T(s) (\frac{x_n + x_{n+1}}{2}) ds$$

satisfying the conditions of Algorithm 7. Then the sequence $\{x_n\}$ converges strongly in $L^2[0,1]$ to the solution of integral equation (15) which is also a solution of the following variational inequality

$$\langle (\gamma f - B)z, y - z \rangle \le 0, \quad \forall y \in Fix(S).$$

Example 14. Let H = R, the set of all real numbers, with the inner product defined by $\langle x, y \rangle = xy$, $\forall x, y \in R$, and induced usual norm | . |. Let C = [-1,3]; Let $f(x) = \frac{1}{9}x$, $B(x) = \frac{1}{4}x$, D(x) = x and let, for each $x \in C$, $T(s)x = \frac{1}{1+2s}x$. Then there exists a unique sequence $\{x_n\} \subset R$ generated by the iterative scheme

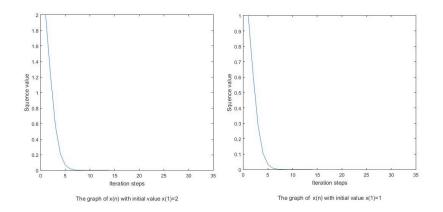
$$x_{n+1} = \left(\frac{1}{9\sqrt{n}} + \frac{1}{2n}\right)x_n$$

$$+\left(\left(1 - \frac{1}{(n+1)^2}\right)I - \frac{1}{2n}D - \frac{1}{\sqrt{n}}B\right)\frac{1}{s_n}\int_0^{s_n}\frac{1}{1+2s}\left(\frac{x_n + x_{n+1}}{2}\right)ds$$
(16)

where $\alpha_n = \frac{1}{\sqrt{n}}$, $\beta_n = \frac{1}{2n}$, $\epsilon_n = \frac{1}{(n+1)^2}$ and $s_n = n$. Then $\{x_n\}$ converges to $\{0\} \in Fix(S)$. f is contraction mapping with constant $\alpha = \frac{1}{6}$ and B, D are strongly positive bounded linear operators with constant $\bar{\gamma}_1 = \frac{1}{5}$ on C. Therefore, we can choose $\gamma = 1$ which satisfies $0 < \gamma < \frac{\bar{\gamma}}{\alpha} < \gamma + \frac{1}{\alpha}$. Furthermore, it is easy to observe that $Fix(S) = \{0\} \neq \emptyset$. After simplification, scheme (16) reduce to

$$x_{n+1} = \frac{\frac{1}{9\sqrt{n}} + \frac{1}{2n} + \frac{1}{4n}\left(1 - \frac{1}{(n+1)^2} - \frac{1}{2n} - \frac{1}{4\sqrt{n}}\right)\ln(1+2n)}{1 - \frac{1}{4n}\left(1 - \frac{1}{(n+1)^2} - \frac{1}{2n} - \frac{1}{4\sqrt{n}}\right)\ln(1+2n)}x_n.$$

Following the proof of Theorem 12, we obtain that $\{x_n\}$ converges strongly to $w = \{0\} \in Fix(S)$.



Let H = R, the set of all real numbers, with the inner product defined by $\langle x, y \rangle = xy$, $\forall x, y \in R$, and induced usual norm | . |. Let C = [0,4]; Let $f(x) = \frac{1}{10}(x-3)$, $B(x) = \frac{1}{3}x$, $D(x) = \frac{1}{2}x$ and let, for each $x \in C$, $T(s)x = e^{-2s}x$. Then there exists a unique sequence $\{x_n\} \subset R$ generated by the iterative scheme

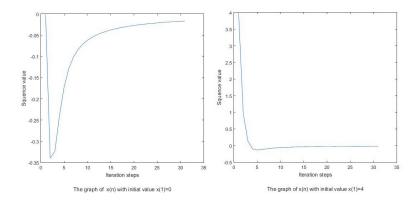
$$x_{n+1} = \frac{3}{20n+5}(x_n-3) + \frac{1}{2\sqrt{n+2}}x_n$$

$$+((1-\frac{1}{n^2})I - \frac{1}{\sqrt{n+2}}D - \frac{3}{4n+1}B)\frac{1}{s_n}\int_0^{s_n} e^{-2s}(\frac{x_n+x_{n+1}}{2})ds$$
(17)

where $\alpha_n = \frac{3}{4n+1}$, $\beta_n = \frac{1}{\sqrt{n+2}}$, $\epsilon_n = \frac{1}{n^2}$ and $s_n = 2n$. Then $\{x_n\}$ converges to $\{0\} \in Fix(S)$. f is contraction mapping with constant $\alpha = \frac{1}{9}$ and B, D are strongly positive bounded linear operators with constant $\bar{\gamma}_1 = \frac{1}{4}$ on C. Therefore, we can choose $\gamma = 2$ which satisfies $0 < \gamma < \frac{\bar{\gamma}}{\alpha} < \gamma + \frac{1}{\alpha}$. Furthermore, it is easy to observe that $Fix(S) = \{0\} \neq \emptyset$. After simplification, scheme (17) reduce to

$$x_{n+1} = \frac{\left(\frac{3}{20n+5} + \frac{1}{2\sqrt{n+2}} - \frac{1}{8n}\left(e^{-4n} - 1\right)\left(1 - \frac{1}{n^2} - \frac{1}{2\sqrt{n+2}} - \frac{1}{4n+1}\right)x_n - \frac{9}{20n+5}}{1 + \frac{1}{8n}\left(e^{-4n} - 1\right)\left(1 - \frac{1}{n^2} - \frac{1}{2\sqrt{n+2}} - \frac{1}{4n+1}\right)}.$$

Following the proof of Theorem 12, we obtain that $\{x_n\}$ converges strongly to $w = \{0\} \in Fix(S)$.



6. CONCULSION

In this paper, we present a viscosity nonlinear midpoint algorithm for solving equilibrium problems in real Hilbert spaces. The methods propose a theoretical generalization of some existing results in the literature and primary numerical experiments also demonstrate the potential applicability of these methods. We establish the algorithm's strong convergence under mild and standard assumptions. This work open the doors for many promising research directions such as obtaining error bound and convergence rate of our algorithms as well as extensions to Banach spaces.

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