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RESEARCH ARTICLE

# Trace formula for finite groups and the Macdonald correspondence for $GL_n(\mathbb{F}_q)^*$

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#### ABSTRACT

Let *G* be a finite group. The trace formula for *G*, which is the trivial case of the Arthur trace formula, is well known with many applications. In this note, we further consider a subgroup  $\Gamma$  of *G* and a representation  $\rho : \Gamma \to \operatorname{GL}(V_{\rho})$  of  $\Gamma$  on a finite dimensional  $\mathbb{C}$ -vector space  $V_{\rho}$ , and compute the trace  $\operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f))$  of the operator  $\operatorname{Ind}_{\Gamma}^{G}(\rho)(f) : \operatorname{Ind}_{\Gamma}^{G}(V_{\rho}) \to \operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$ for any function  $f : G \to \mathbb{C}$  in two different ways. The expressions for  $\operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f))$  denoted by  $J(\rho, f)$  and  $I(\rho, f)$  are the spectral side and the geometric side of the trace formula for  $\operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f))$ , respectively. The identity  $J(\rho, f) = \operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f)) = I(\rho, f)$  is a generalization of the trace formula for the finite group *G*. This theory is then applied to the "automorphic side" of the Macdonald correspondence for  $\operatorname{GL}_{n}(\mathbb{F}_{q})$ ; namely, to the "automorphic side" of the local 0-dimensional Langlands correspondence for  $\operatorname{GL}(n)$ , where new identities are obtained for the  $\epsilon$ -factors of representations of  $\operatorname{GL}_{n}(\mathbb{F}_{q})$ .

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#### 1. INTRODUCTION

This short note which is the revised version of our colloquium talk notes that we delivered at Selçuk University, Konya in 2022, concerns the trivial case of the Arthur trace formula, namely the trace formula for finite groups. Let *G* be a finite group. The trace formula for *G* is an identity involving characters of the finite group *G*, and although simple, this formula is of central importance with deep applications in the theory of linear representations of *G* over  $\mathbb{C}$ . For instance, using the trace formula for *G*, it is well known that major theorems like the Frobenius reciprocity law (Example 6.1) and the Plancherel formula (Example 6.2) for *G* follow directly.

In this note, we further consider a subgroup  $\Gamma$  of *G* and a representation

$$\rho: \Gamma \to \operatorname{GL}(V_{\rho})$$

of  $\Gamma$  on a finite dimensional vector space  $V_{\rho}$  over  $\mathbb{C}$ , and for any function  $f : G \to \mathbb{C}$ , we compute the trace  $\operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f))$  of the operator

$$\operatorname{Ind}_{\Gamma}^{G}\rho(f): \operatorname{Ind}_{\Gamma}^{G}(V_{\rho}) \to \operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$$

which is defined by

$$(\mathsf{Ind}_{\Gamma}^G(\rho)(f))(\varphi) = \sum_{g \in G} f(g)[\mathsf{Ind}_{\Gamma}^G(\rho)(g)](\varphi), \ ^{\forall}\varphi \in \mathsf{Ind}_{\Gamma}^G(V_{\rho})$$

in two different ways. The first expression for  $\operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f))$  denoted by  $J(\rho, f)$  involves multiplicities of irreducible representations appearing in  $\operatorname{Ind}_{\Gamma}^{G}(\rho)$  and called the spectral side of the trace formula for  $\operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f))$ . The second expression  $I(\rho, f)$  for  $\operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f))$ , which is called the geometric side of the trace formula for  $\operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f))$ , is

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constructed by the conjugacy classes of  $\Gamma$  and G. The identity (Theorem 3.1 and Theorem 5.1)

$$J(\rho, f) = \operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f)) = I(\rho, f)$$

that we derive and call the trace formula for *G* with respect to the subgroup  $\Gamma$  and  $\rho : \Gamma \to GL(V_{\rho})$  in this note, is a generalization of the well known trace formula for the finite group *G* which corresponds to the case  $\Gamma = \langle 1 \rangle$  and  $\rho = \mathbb{1}_{\langle 1 \rangle} : \langle 1 \rangle \to GL(\mathbb{C})$ . In the remainder of this work, that is in Section 7, we apply this theory to the "automorphic side" of the Macdonald correspondence for  $GL_n(\mathbb{F}_q)$ ; namely, to the "automorphic side" of the local 0-dimensional Langlands correspondence for GL(n), where new identities are obtained for the  $\epsilon$ -factors of representations of  $GL_n(\mathbb{F}_q)$ .

The main references that we follow closely in this work are Terras Terras (1999) and Yang Yang (2006). However, we will deal with the trace formula for finite groups in full generality. The trace formula stated and proved in this note should be considered "folklore", videlicet, well-known to researchers in the area, and seems only treated recently in the M.Sc. thesis of Chasek Chasek (2023) and in a note of Lee Lee (2022). Therefore, the only contribution of this note is the last section on the Macdonald correspondence for  $GL_n(\mathbb{F}_q)$ , where the main references that we follow are Macdonald (1980); Piatetski-Shapiro (1983); Silberger and Zink (2008); Ye and Zelingher (2021)

# 2. THE REPRESENTATION $\mathsf{IND}_{\Gamma}^{G}(\rho)$ OF G ON $\mathsf{IND}_{\Gamma}^{G}(V_{\rho})$ OVER $\mathbb{C}$ INDUCED FROM $\rho : \Gamma \to \mathsf{GL}(V_{\rho})$ UP TO G

To fix the very basic notation, let *G* be a finite group,  $\Gamma$  a fixed subgroup of *G* of index  $(G : \Gamma) = \iota$ , and  $\rho : \Gamma \to GL(V_{\rho})$ a representation of  $\Gamma$  on a *d*-dimensional vector space  $V_{\rho}$  over  $\mathbb{C}$  whose character is denoted by  $\chi_{\rho} : \Gamma \to \mathbb{C}$  as usual. Set  $\chi_{\rho}(1) = d_{\rho}$  the dimension dim<sub> $\mathbb{C}</sub>(V_{\rho})$  of  $V_{\rho}$  called the degree of  $\rho : \Gamma \to GL(V_{\rho})$ ). Introduce further the map</sub>

$$\widetilde{\rho}: G \to \left\langle \operatorname{GL}(V_{\rho}) \cup \{\mathbf{0}: V_{\rho} \to \{\mathbf{0}_{V_{\rho}}\} \right\} \right\rangle$$

by defining

$$\widetilde{\rho}(x) = \begin{cases} \rho(x), & x \in \Gamma; \\ \mathbf{0}, & x \in G - \Gamma, \end{cases} \quad \forall x \in G.$$

Recall that Piatetski-Shapiro (1983); Serre (1972), the  $\mathbb{C}[G]$ -module  $\operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  induced from the  $\mathbb{C}[\Gamma]$ -module  $V_{\rho}$  is defined by

$$\operatorname{Ind}_{\Gamma}^{G}(V_{\rho}) := \{ \varphi : G \to V_{\rho} \mid \varphi(\gamma x) = \rho(\gamma)(\varphi(x)), \forall x \in G, \forall \gamma \in \Gamma \},\$$

which defines a representation

$$\operatorname{Ind}_{\Gamma}^{G}(\rho): G \to \operatorname{GL}(\operatorname{Ind}_{\Gamma}^{G}(V_{\rho}))$$

of the finite group G on the induced  $\mathbb{C}$ -linear space  $\mathsf{Ind}_{\Gamma}^{G}(V_{\rho})$  by

$$[\mathsf{Ind}_{\Gamma}^{G}(\rho)(g)](\varphi)(x) = \varphi(xg), \ ^{\forall}g \in G, \ ^{\forall}\varphi \in \mathsf{Ind}_{\Gamma}^{G}V_{\rho}, \ ^{\forall}x \in G,$$

called the representation induced from  $\rho : \Gamma \to GL(V_{\rho})$  up to G.

Recall that  $\operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  is an inner product space under the inner product

$$\langle \bullet \mid \bullet \rangle : \operatorname{Ind}_{\Gamma}^{G}(V_{\rho}) \times \operatorname{Ind}_{\Gamma}^{G}(V_{\rho}) \to \mathbb{C}$$

on  $\operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  defined by

$$\langle \varphi_1 \mid \varphi_2 \rangle := \sum_{i=1}^{\iota} {}^{\mathsf{H}} [\varphi_2(g_i)]_{\mathcal{B}_{V_{\rho}}} [\varphi_1(g_i)]_{\mathcal{B}_{V_{\rho}}}, \ {}^{\forall} \varphi_1, \varphi_2 \in \mathsf{Ind}_{\Gamma}^G(V_{\rho}),$$

which neither depends on a choice of a complete set of representatives  $\mathcal{R}_{\Gamma \setminus G} = \{g_1, \dots, g_t\} \subset G$  of the coset space  $\Gamma \setminus G$ nor a choice of an ordered basis  $\mathcal{B}_{V_\rho} = \{v_1, \dots, v_d\}$  of  $V_\rho$  over  $\mathbb{C}$  (in particular, nor a choice of an ordered orthonormal basis  $\mathcal{N}_{V_\rho} = \{e_1, \dots, e_d\}$  of  $V_\rho$  over  $\mathbb{C}$ ), and

$$\mathcal{N}_{\mathrm{Ind}_{\Gamma}^{G}(V_{\rho})} \coloneqq \{\varphi_{ij}\}_{\substack{i=1,\cdots, \iota\\ j=1,\cdots, d}}$$

is an orthonormal basis of  $\operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  over  $\mathbb{C}$ , where for  $i = 1, \dots, \iota$  and  $j = 1, \dots, d$ 

$$\varphi_{ij}: G \to V_{\rho}$$

is defined by

$$\varphi_{ij}(x) = \widetilde{\rho}(xg_i^{-1})e_j, \ ^{\forall}x \in G.$$

The  $(G : \Gamma)$ dim $(V_{\rho}) = \iota d$ -dimensional representation  $\operatorname{Ind}_{\Gamma}^{G}(\rho)$  of G on  $\operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  over  $\mathbb{C}$  decomposes into the direct sum

$$\operatorname{Ind}_{\Gamma}^{G}(\rho) = \bigoplus_{\pi_{o} \in [\pi] \in \Pi(G)} m(\pi_{o}, \operatorname{Ind}_{\Gamma}^{G}(\rho))\pi_{o}$$
(1)

of non-isomorphic irreducible representations  $\pi_o$  of G over  $\mathbb{C}$  with  $m(\pi_o, \mathsf{Ind}_{\Gamma}^G(\rho)) \in \mathbb{N}_0 = \mathbb{N} \cup \{0\}$ , where  $\Pi(G)$  denotes the set of all isomorphism classes  $[\pi]$  of irreducible representations  $\pi$  of G over  $\mathbb{C}$ .

#### **3.** THE TRACE FORMULA FOR *G* WITH RESPECT TO THE SUBGROUP $\Gamma$ AND $\rho : \Gamma \rightarrow GL(V_{\rho})$

Let  $r : G \to GL(V_r)$  be a representation of the finite group *G* on a *d*-dimensional vector space  $V_r$  over  $\mathbb{C}$ . For any function  $f : G \to \mathbb{C}$ , there exists a  $\mathbb{C}$ -linear operator

$$\mathbf{r}(f): V_{\mathsf{r}} \to V_{\mathsf{r}}$$

on  $V_r$  defined by

$$(\mathbf{r}(f))(v) = \sum_{g \in G} f(g)\mathbf{r}(g)(v), \ ^{\forall} v \in V_{\mathbf{r}}.$$

We can compute the trace  $Tr(\mathbf{r}(f))$  of the operator  $\mathbf{r}(f) : V_r \to V_r$  on  $V_r$ .

In this note, in particular, we are interested in computing the trace  $\operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f))$  of the linear operator  $\operatorname{Ind}_{\Gamma}^{G}(\rho)(f)$ :  $\operatorname{Ind}_{\Gamma}^{G}(V_{\rho}) \to \operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  on  $\operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$ . Observe that, the operator

$$\operatorname{Ind}_{\Gamma}^{G}(\rho)(f) : \operatorname{Ind}_{\Gamma}^{G}(V_{\rho}) \to \operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$$

on the  $\mathbb{C}$ -linear space  $\mathsf{Ind}_{\Gamma}^{G}(V_{\rho})$  given by

$$(\mathsf{Ind}_{\Gamma}^{G}(\rho)(f))(\varphi) = \sum_{g \in G} f(g)[\mathsf{Ind}_{\Gamma}^{G}(\rho)(g)](\varphi), \ ^{\forall}\varphi \in \mathsf{Ind}_{\Gamma}^{G}(V_{\rho})$$

is defined explicitly by

$$(\mathsf{Ind}_{\Gamma}^{G}(\rho)(f)\varphi)(x) = \sum_{g \in G} f(g)[\mathsf{Ind}_{\Gamma}^{G}(\rho)(g)](\varphi)(x) = \sum_{g \in G} f(g)\varphi(xg), \ ^{\forall}\varphi \in \mathsf{Ind}_{\Gamma}^{G}(V_{\rho}), \ ^{\forall}x \in G.$$

Therefore changing the G-variables  $xg \rightsquigarrow y$  and partitioning G as  $G = \bigsqcup_{i=1}^{l} \Gamma g_i$ , the equalities

$$(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f)\varphi)(x) = \sum_{y \in G} f(x^{-1}y)\varphi(y)$$
$$= \sum_{i=1}^{\iota} \sum_{\gamma \in \Gamma} f(x^{-1}\gamma g_{i})\varphi(\gamma g_{i}) \qquad \forall \varphi \in \operatorname{Ind}_{\Gamma}^{G}(V_{\rho}), \ \forall x \in G,$$
$$= \sum_{i=1}^{\iota} \sum_{\gamma \in \Gamma} f(x^{-1}\gamma g_{i})\rho(\gamma)(\varphi(g_{i}))$$

follow immediately. Define now an  $\mathsf{End}_{\mathbb{C}}(V_{\rho})$ -valued function

$$K_f: G \times G \to \mathsf{End}_{\mathbb{C}}(V_\rho)$$

on  $G \times G$  by

$$K_f(x, y) = \sum_{\gamma \in \Gamma} f(x^{-1}\gamma y)\rho(\gamma), \quad \forall x, y \in G.$$

The operator  $\operatorname{Ind}_{\Gamma}^{G}(\rho)(f) : \operatorname{Ind}_{\Gamma}^{G}(V_{\rho}) \to \operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  on  $\operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  is then an "integral operator" on  $\operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  with "kernel"  $K_{f}: G \times G \to \operatorname{End}_{\mathbb{C}}(V_{\rho})$ , given by

$$(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f)\varphi)(x) = \sum_{i=1}^{l} K_{f}(x, g_{i})(\varphi(g_{i})), \qquad {}^{\forall}\varphi \in \operatorname{Ind}_{\Gamma}^{G}(V_{\rho}), \; {}^{\forall}x \in G.$$
(3)

The trace formula for G with respect to the subgroup  $\Gamma$  and  $\rho : \Gamma \to \operatorname{GL}(V_{\rho})$  is an identity that computes the trace  $\operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f))$  of the operator  $\operatorname{Ind}_{\Gamma}^{G}(\rho)(f) : \operatorname{Ind}_{\Gamma}^{G}(V_{\rho}) \to \operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  on  $\operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  in two different ways:

"Spectral side" =  $\operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f))$  = "Geometric side".

More precisely, the trace formula for the finite group G with respect to the subgroup  $\Gamma$  and  $\rho : \Gamma \to GL(V_{\rho})$  states the following:

**Theorem 3.1.** (Trace formula for finite groups – Version 1) For any function  $f : G \to \mathbb{C}$ , the trace  $\operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f))$  of the operator

$$\operatorname{Ind}_{\Gamma}^{G}(\rho)(f) : \operatorname{Ind}_{\Gamma}^{G}(V_{\rho}) \to \operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$$

on the  $\mathbb{C}$ -linear space  $\operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  satisfies the identity

$$J(\rho, f) = \sum_{\pi_o \in [\pi] \in \Pi(G)} m(\pi_o, \mathsf{Ind}_{\Gamma}^G(\rho)) \operatorname{Tr}(\pi_o(f)) = \operatorname{Tr}(\mathsf{Ind}_{\Gamma}^G(\rho)(f)) = \sum_{\gamma \in \{\Gamma\}} \chi_\rho(\gamma) \frac{|G_\gamma|}{|\Gamma_\gamma|} \sum_{t \in G_\gamma \setminus G} f(t^{-1}\gamma t) = I(\rho, f),$$

$$\tag{4}$$

where

 $- \{\Gamma\} = a \text{ set consisting of all representatives for the conjugacy classes in } \Gamma;$ 

- $-\Gamma_{\gamma} = \{\delta \in \Gamma \mid \delta^{-1}\gamma\delta = \gamma\} \text{ for } \gamma \in \{\Gamma\}; \\ -G_{\gamma} = \{g \in G \mid g^{-1}\gamma g = \gamma\} \text{ for } \gamma \in \{\Gamma\}.$

Here,  $J(\rho, f)$  and  $I(\rho, f)$  are called the spectral side and the geometric side of the trace formula for the finite group G with respect to the subgroup  $\Gamma$  and  $\rho : \Gamma \to GL(V_{\rho})$ , respectively.

In the next section we sketch a proof of this theorem.

#### 4. PROOF OF THE TRACE FORMULA FOR G WITH RESPECT TO THE SUBGROUP $\Gamma$ AND $\rho: \Gamma \to \mathrm{GL}(V_{\rho})$

To establish the spectral side  $J(\rho, f)$  of the trace formula for G with respect to the subgroup  $\Gamma$  and  $\rho: \Gamma \to GL(V_{\rho})$ , observe that the irreducible decomposition

$$\mathsf{Ind}_{\Gamma}^G(\rho) = \bigoplus_{\pi_o \in [\pi] \in \Pi(G)} m(\pi_o, \mathsf{Ind}_{\Gamma}^G(\rho)) \pi_o$$

of the representation  $\operatorname{Ind}_{\Gamma}^{G}(\rho)$  of the finite group G on the vector space  $\operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  over  $\mathbb{C}$  induced from  $\rho: \Gamma \to \operatorname{GL}(V_{\rho})$ up to G, stated in (1) yields, for any function  $f: G \to \mathbb{C}$ , the decomposition

$$\mathsf{Ind}_{\Gamma}^G(\rho)(f) = \bigoplus_{\pi_o \in [\pi] \in \Pi(G)} m(\pi_o, \mathsf{Ind}_{\Gamma}^G(\rho)) \pi_o(f)$$

of the operator  $\operatorname{Ind}_{\Gamma}^{G}(\rho)(f) : \operatorname{Ind}_{\Gamma}^{G}(V_{\rho}) \to \operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  on  $\operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$ . Therefore, the trace  $\operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f))$  of  $\operatorname{Ind}_{\Gamma}^{G}(\rho)(f) : \operatorname{Ind}_{\Gamma}^{G}(V_{\rho}) \to \operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  is given by

$$\operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f)) = \operatorname{Tr}\left(\bigoplus_{\pi_{o} \in [\pi] \in \Pi(G)} m(\pi_{o}, \operatorname{Ind}_{\Gamma}^{G}(\rho))\pi_{o}(f)\right) = \sum_{\pi_{o} \in [\pi] \in \Pi(G)} m(\pi_{o}, \operatorname{Ind}_{\Gamma}^{G}(\rho))\operatorname{Tr}(\pi_{o}(f)) = J(\rho, f),$$

which is the spectral side of the formula stated in (4).

For the geometric side  $I(\rho, f)$  of the trace formula for G with respect to the subgroup  $\Gamma$  and  $\rho: \Gamma \to GL(V_{\rho})$ , recall that, by (3), the operator

$$\mathrm{Ind}_{\Gamma}^{G}(\rho)(f):\mathrm{Ind}_{\Gamma}^{G}(V_{\rho})\rightarrow\mathrm{Ind}_{\Gamma}^{G}(V_{\rho})$$

on the  $\mathbb{C}$ -linear space  $\mathsf{Ind}_{\Gamma}^{G}(V_{\rho})$  has an expression of the form

$$(\mathsf{Ind}_{\Gamma}^{G}(\rho)(f)\varphi)(x) = \sum_{i=1}^{\iota} K_{f}(x, g_{i})(\varphi(g_{i})), \qquad {}^{\forall}\varphi \in \mathsf{Ind}_{\Gamma}^{G}(V_{\rho}), \; {}^{\forall}x \in G$$

On the other hand, the matrix representation  $[\mathsf{Ind}_{\Gamma}^{G}(\rho)(f)]_{\mathcal{N}_{\mathsf{Ind}_{\Gamma}^{G}(V_{\rho})}} \in \mathbb{C}^{\iota d \times \iota d}$  of the operator  $\mathsf{Ind}_{\Gamma}^{G}(\rho)(f) : \mathsf{Ind}_{\Gamma}^{G}(V_{\rho}) \to \mathsf{Ind}_{\Gamma}^{G}(V_{\rho})$  $\operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  on  $\operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  with respect to the "lexicographically" ordered orthonormal basis  $\mathcal{N}_{\operatorname{Ind}_{\Gamma}^{G}(V_{\rho})} = \{\varphi_{ij}\}_{\substack{i=1,\dots,l\\j=1,\dots,d}}$  of  $\operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  is given by

$$[\operatorname{Ind}_{\Gamma}^{G}(\rho)(f)]_{\mathcal{N}_{\operatorname{Ind}_{\Gamma}^{G}(V_{\rho})}} = \begin{bmatrix} \left\langle \operatorname{Ind}_{\Gamma}^{G}(\rho)(f)(\varphi_{11}) \mid \varphi_{11} \right\rangle & \left\langle \operatorname{Ind}_{\Gamma}^{G}(\rho)(f)(\varphi_{12}) \mid \varphi_{11} \right\rangle & \dots & \left\langle \operatorname{Ind}_{\Gamma}^{G}(\rho)(f)(\varphi_{\iota d}) \mid \varphi_{11} \right\rangle \\ \left\langle \operatorname{Ind}_{\Gamma}^{G}(\rho)(f)(\varphi_{11}) \mid \varphi_{12} \right\rangle & \left\langle \operatorname{Ind}_{\Gamma}^{G}(\rho)(f)(\varphi_{12}) \mid \varphi_{12} \right\rangle & \dots & \left\langle \operatorname{Ind}_{\Gamma}^{G}(\rho)(f)(\varphi_{\iota d}) \mid \varphi_{12} \right\rangle \\ \vdots & \vdots & \ddots & \vdots \\ \left\langle \operatorname{Ind}_{\Gamma}^{G}(\rho)(f)(\varphi_{11}) \mid \varphi_{\iota d} \right\rangle & \left\langle \operatorname{Ind}_{\Gamma}^{G}(\rho)(f)(\varphi_{12}) \mid \varphi_{\iota d} \right\rangle & \dots & \left\langle \operatorname{Ind}_{\Gamma}^{G}(\rho)(f)(\varphi_{\iota d}) \mid \varphi_{\iota d} \right\rangle \end{bmatrix}.$$

Therefore, the trace  $\operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f))$  of the operator  $\operatorname{Ind}_{\Gamma}^{G}(\rho)(f) : \operatorname{Ind}_{\Gamma}^{G}(V_{\rho}) \to \operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  on  $\operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  is given by

$$\operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f)) = \sum_{(s,t)=(1,1)}^{(\iota,d)} \left\langle \operatorname{Ind}_{\Gamma}^{G}(\rho)(f)(\varphi_{st}) \mid \varphi_{st} \right\rangle,$$

which is in explicit form given by

$$Tr(Ind_{\Gamma}^{G}(\rho)(f)) = \sum_{(s,t)=(1,1)}^{(\iota,d)} \left\langle Ind_{\Gamma}^{G}(\rho)(f)(\varphi_{st}) \mid \varphi_{st} \right\rangle$$

$$= \sum_{(s,t)=(1,1)}^{(\iota,d)} \sum_{i_{o}=1}^{\iota} {}^{H}[\varphi_{st}(g_{i_{o}})]_{N_{V_{\rho}}} [(Ind_{\Gamma}^{G}(\rho)(f)(\varphi_{st}))(g_{i_{o}})]_{N_{V_{\rho}}}$$

$$= \sum_{(s,t)=(1,1)}^{(\iota,d)} \sum_{i_{o}=1}^{\iota} {}^{H}[\varphi_{st}(g_{i_{o}})]_{N_{V_{\rho}}} \left[ \sum_{i=1}^{\iota} K_{f}(g_{i_{o}},g_{i})(\varphi_{st}(g_{i})) \right]_{N_{V_{\rho}}}$$

$$= \sum_{(s,t)=(1,1)}^{(\iota,d)} \sum_{i_{o}=1}^{\iota} {}^{H}[\varphi_{st}(g_{i_{o}})]_{N_{V_{\rho}}} \left[ \sum_{i=1}^{\iota} \sum_{\gamma \in \Gamma} f(g_{i_{o}}^{-1}\gamma g_{i})\rho(\gamma)(\varphi_{st}(g_{i})) \right]_{N_{V_{\rho}}}$$

$$= \sum_{(s,t)=(1,1)}^{(\iota,d)} \sum_{i_{o}=1}^{\iota} \sum_{j_{o}=1}^{d} \overline{\langle \varphi_{st}(g_{i_{o}}) \mid e_{j_{o}} \rangle} \sum_{i=1}^{\iota} \sum_{\gamma \in \Gamma} f(g_{i_{o}}^{-1}\gamma g_{i}) \left\langle \rho(\gamma)(\varphi_{st}(g_{i})) \mid e_{j_{o}} \right\rangle.$$

Note that, for  $s, i_o = 1, \cdots, \iota; t, j_o = 1, \cdots, d$ 

$$\varphi_{st}(g_{i_o}) = \widetilde{\rho}(g_{i_o}g_s^{-1})e_t = \begin{cases} \rho(g_{i_o}g_s^{-1})e_t = e_t, & \Gamma g_{i_o} = \Gamma g_s \Leftrightarrow i_o = s; \\ 0_{V_\rho}, & \Gamma g_{i_o} \neq \Gamma g_s \Leftrightarrow i_o \neq s \end{cases}$$

and

$$\left\langle \varphi_{st}(g_{i_o}) \mid e_{j_o} \right\rangle = \begin{cases} 1, & i_o = s \text{ and } j_o = t; \\ 0, & i_o = s \text{ and } j_o \neq t; \\ 0, & i_o \neq s. \end{cases}$$

Also, for  $\gamma \in \Gamma$ ;  $s, i, i_o = 1, \cdots, \iota$ ;  $t, j_o = 1, \cdots, d$ ,

$$\rho(\gamma)(\varphi_{st}(g_i)) = \varphi_{st}(\gamma g_i) = \widetilde{\rho}(\gamma g_i g_s^{-1})e_t = \begin{cases} \rho(\gamma g_i g_s^{-1})e_t = \rho(\gamma)e_t, & \Gamma \gamma g_i = \Gamma g_i = \Gamma g_s \Leftrightarrow i = s; \\ 0_{V_{\rho}}, & \Gamma \gamma g_i = \Gamma g_i \neq \Gamma g_s \Leftrightarrow i \neq s \end{cases}$$

and

$$f(g_{i_o}^{-1}\gamma g_i)\left\langle \rho(\gamma)(\varphi_{st}(g_i)) \mid e_{j_o}\right\rangle = \begin{cases} f(g_{i_o}^{-1}\gamma g_i)\left\langle \rho(\gamma)e_t \mid e_{j_o}\right\rangle, & \Gamma\gamma g_i = \Gamma g_i = \Gamma g_s \Leftrightarrow i = s; \\ 0, & \Gamma\gamma g_i = \Gamma g_i \neq \Gamma g_s \Leftrightarrow i \neq s. \end{cases}$$

Therefore, for a fixed  $s = 1, \dots, \iota$  and a fixed  $t = 1, \dots, d$ ,

$$\begin{split} \left\langle \mathsf{Ind}_{\Gamma}^{G}(\rho)(f)(\varphi_{st}) \mid \varphi_{st} \right\rangle &= \sum_{i_{o}=1}^{\iota} \sum_{j_{o}=1}^{d} \overline{\left\langle \varphi_{st}(g_{i_{o}}) \mid e_{j_{o}} \right\rangle} \sum_{i=1}^{\iota} \sum_{\gamma \in \Gamma} f(g_{i_{o}}^{-1} \gamma g_{i}) \left\langle \rho(\gamma)(\varphi_{st}(g_{i})) \mid e_{j_{o}} \right\rangle \\ &= \sum_{i=1}^{\iota} \sum_{\gamma \in \Gamma} f(g_{s}^{-1} \gamma g_{i}) \left\langle \rho(\gamma)(\varphi_{st}(g_{i})) \mid e_{t} \right\rangle \\ &= \sum_{\gamma \in \Gamma} f(g_{s}^{-1} \gamma g_{s}) \left\langle \rho(\gamma)(\varphi_{st}(g_{s})) \mid e_{t} \right\rangle \\ &= \sum_{\gamma \in \Gamma} f(g_{s}^{-1} \gamma g_{s}) \left\langle \rho(\gamma)e_{t} \mid e_{t} \right\rangle, \end{split}$$

proving that

$$\operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f)) = \sum_{(s,t)=(1,1)}^{(\iota,d)} \left\langle \operatorname{Ind}_{\Gamma}^{G}(\rho)(f)(\varphi_{st}) \mid \varphi_{st} \right\rangle = \sum_{\substack{1 \le s \le t \\ 1 \le t \le d}} \sum_{\gamma \in \Gamma} f(g_{s}^{-1}\gamma g_{s}) \left\langle \rho(\gamma)e_{t} \mid e_{t} \right\rangle.$$
(5)

Introduce:

-  $\{\Gamma\}$  = a set consisting of all representatives  $\gamma$  for the conjugacy classes  $C_{\gamma}^{\Gamma}$  in  $\Gamma$ ;

 $\begin{array}{l} - \ \Gamma_{\gamma} = \{ \delta \in \Gamma \mid \delta^{-1}\gamma \delta = \gamma \} \ \text{for} \ \gamma \in \{ \Gamma \}; \\ - \ G_{\gamma} = \{ g \in G \mid g^{-1}\gamma g = \gamma \} \ \text{for} \ \gamma \in \{ \Gamma \}. \end{array}$ 

Then the subgroup  $\Gamma$  of *G* decomposes as

$$\Gamma = \bigsqcup_{\gamma \in \{\Gamma\}} C_{\gamma} = \bigsqcup_{\gamma \in \{\Gamma\}} \{ \delta^{-1} \gamma \delta \mid \delta \in \mathcal{R}_{\Gamma_{\gamma} \setminus \Gamma} \},$$

where  $\mathcal{R}_{\Gamma_{\gamma}\setminus\Gamma}$  denotes any fixed complete set of representatives of  $\Gamma_{\gamma}\setminus\Gamma$ . Therefore, for  $s = 1, \dots, \iota$  and  $t = 1, \dots, d$ , the following identities hold

$$\sum_{\gamma \in \Gamma} f(g_s^{-1} \gamma g_s) \langle \rho(\gamma) e_t | e_t \rangle = \sum_{\gamma \in \{\Gamma\}} \sum_{\omega \in C_{\gamma}} f(g_s^{-1} \omega g_s) \langle \rho(\omega) e_t | e_t \rangle$$
$$= \sum_{\gamma \in \{\Gamma\}} \sum_{\delta \in \mathcal{R}_{\Gamma_{\gamma} \setminus \Gamma}} f(g_s^{-1} \delta^{-1} \gamma \delta g_s) \langle \rho(\delta^{-1} \gamma \delta) e_t | e_t \rangle.$$
(6)

Now, substituting eq. (6) into eq. (5),

$$\begin{split} \mathrm{Tr}(\mathrm{Ind}_{\Gamma}^{G}(\rho)(f)) &= \sum_{\substack{1 \leq s \leq \iota \\ 1 \leq t \leq d}} \sum_{\gamma \in \{\Gamma\}} \sum_{\delta \in \mathcal{R}_{\Gamma_{\gamma} \setminus \Gamma}} f(g_{s}^{-1}\delta^{-1}\gamma\delta g_{s}) \left\langle \rho(\delta^{-1}\gamma\delta)e_{t} \mid e_{t} \right\rangle \\ &= \sum_{\gamma \in \{\Gamma\}} \sum_{\delta \in \mathcal{R}_{\Gamma_{\gamma} \setminus \Gamma}} \sum_{\substack{1 \leq s \leq \iota \\ 1 \leq t \leq d}} f(g_{s}^{-1}\delta^{-1}\gamma\delta g_{s}) \left\langle \rho(\delta^{-1}\gamma\delta)e_{t} \mid e_{t} \right\rangle \\ &= \sum_{\gamma \in \{\Gamma\}} \sum_{\delta \in \mathcal{R}_{\Gamma_{\gamma} \setminus \Gamma}} \left( \sum_{\substack{1 \leq s \leq \iota }} f(g_{s}^{-1}\delta^{-1}\gamma\delta g_{s}) \right) \left( \sum_{1 \leq t \leq d} \left\langle \rho(\delta^{-1}\gamma\delta)e_{t} \mid e_{t} \right\rangle \right), \end{split}$$

where for  $\gamma \in \{\Gamma\}$  and  $\delta \in \mathcal{R}_{\Gamma_{\gamma} \setminus \Gamma}$ ,

$$\sum_{1 \le t \le d} \left\langle \rho(\delta^{-1}\gamma\delta) e_t \mid e_t \right\rangle = \operatorname{Tr}\rho(\delta^{-1}\gamma\delta) = \operatorname{Tr}\rho(\gamma) = \chi_\rho(\gamma).$$

Therefore,

$$\mathrm{Tr}(\mathrm{Ind}_{\Gamma}^G(\rho)(f)) = \sum_{\gamma \in \{\Gamma\}} \chi_{\rho}(\gamma) \sum_{\delta \in \mathcal{R}_{\Gamma_{\gamma} \setminus \Gamma}} \sum_{1 \leq s \leq \iota} f(g_s^{-1} \delta^{-1} \gamma \delta g_s).$$

Observe that, for  $\gamma \in \{\Gamma\}$ , the group G has the following subgroups as seen in the Hasse diagram:



Each chain of subgroups

$$\Gamma_{\gamma} \leq \Gamma \leq G$$

and

$$\Gamma_{\gamma} \le G_{\gamma} \le G$$

of G produces different partitions of G into cosets modulo  $\Gamma_{\gamma}$ , as will be discussed in the next two observations.

**Observation 4.1.** For  $\gamma \in \{\Gamma\}$ , the group *G* partitions into cosets modulo  $\Gamma_{\gamma}$  as

$$G = \bigsqcup_{s=1}^{\iota} \bigsqcup_{\delta \in \mathcal{R}_{\Gamma_{\gamma} \setminus \Gamma}} \Gamma_{\gamma} \delta g_s,$$

where  $\mathcal{R}_{\Gamma_{\gamma}\setminus\Gamma} \subset \Gamma$  is any fixed complete set of representatives of the coset space  $\Gamma_{\gamma}\setminus\Gamma$ .

**Proof.** We have already fixed a complete set of representatives  $\mathcal{R}_{\Gamma \setminus G} = \{g_1, \dots, g_t\} \subset G$  of the coset space  $\Gamma \setminus G$ . So, there is a decomposition of the group G into cosets modulo  $\Gamma$  as  $G = \bigsqcup_{s=1}^{t} \Gamma g_s$ .

There is also the decomposition of the subgroup  $\Gamma$  of G into cosets modulo  $\Gamma_{\gamma}$  as

$$\Gamma = \bigsqcup_{\delta \in \mathcal{R}_{\Gamma_{\gamma} \setminus \Gamma}} \Gamma_{\gamma} \delta.$$

Therefore the group G decomposes into cosets modulo  $\Gamma_{\gamma}$  as:

$$G = \Gamma g_1 \sqcup \cdots \sqcup \Gamma g_\iota = (\bigsqcup_{\delta \in \mathcal{R}_{\Gamma_{\gamma} \setminus \Gamma}} \Gamma_{\gamma} \delta) g_1 \sqcup \cdots \sqcup (\bigsqcup_{\delta \in \mathcal{R}_{\Gamma_{\gamma} \setminus \Gamma}} \Gamma_{\gamma} \delta) g_\iota = \bigsqcup_{s=1}^{\iota} \bigsqcup_{\delta \in \mathcal{R}_{\Gamma_{\gamma} \setminus \Gamma}} \Gamma_{\gamma} \delta g_s.$$

**Observation 4.2.** For  $\gamma \in \{\Gamma\}$ , there is another partitioning of the group G into cosets modulo  $\Gamma_{\gamma}$  given by

$$G = \bigsqcup_{t \in \mathcal{R}_{G_{\gamma} \setminus G}} \bigsqcup_{y \in \mathcal{R}_{\Gamma_{\gamma} \setminus G_{\gamma}}} \Gamma_{\gamma} yt,$$

where  $\mathcal{R}_{G_{\gamma}\setminus G} \subset G$  and  $\mathcal{R}_{\Gamma_{\gamma}\setminus G_{\gamma}} \subset G_{\gamma}$  are any fixed complete set of representatives of the coset spaces  $G_{\gamma}\setminus G$  and  $\Gamma_{\gamma}\setminus G_{\gamma}$ , respectively.

**Proof.** We have already fixed a complete system of representatives  $\mathcal{R}_{G_{\gamma}\setminus G} \subset G$  of the coset space  $G_{\gamma}\setminus G$ . So, there is a decomposition of the group G into cosets modulo  $G_{\gamma}$  as  $G = \bigsqcup_{t \in \mathcal{R}_{G_{\gamma}\setminus G}} G_{\gamma}t$ .

There is also the decomposition of the subgroup  $G_{\gamma}$  of G into cosets modulo  $\Gamma_{\gamma}$  as

$$G_{\gamma} = \bigsqcup_{y \in \mathcal{R}_{\Gamma_{\gamma} \setminus G_{\gamma}}} \Gamma_{\gamma} y.$$

Therefore the group G decomposes into cosets modulo  $\Gamma_{\gamma}$  as:

$$G = \bigsqcup_{t \in \mathcal{R}_{G_{\gamma} \setminus G}} G_{\gamma} t = \bigsqcup_{t \in \mathcal{R}_{G_{\gamma} \setminus G}} \left( \bigsqcup_{y \in \mathcal{R}_{\Gamma_{\gamma} \setminus G_{\gamma}}} \Gamma_{\gamma} y \right) t = \bigsqcup_{t \in \mathcal{R}_{G_{\gamma} \setminus G}} \bigsqcup_{y \in \mathcal{R}_{\Gamma_{\gamma} \setminus G_{\gamma}}} \Gamma_{\gamma} y t.$$

So by Observation 4.1,

$$\operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f)) = \sum_{\gamma \in \{\Gamma\}} \chi_{\rho}(\gamma) \sum_{\delta \in \mathcal{R}_{\Gamma_{\gamma} \setminus \Gamma}} \sum_{1 \le s \le \iota} f(g_{s}^{-1} \delta^{-1} \gamma \delta g_{s})$$
$$= \sum_{\gamma \in \{\Gamma\}} \chi_{\rho}(\gamma) \sum_{x \in \mathcal{R}_{\Gamma_{\gamma} \setminus G}} f(x^{-1} \gamma x),$$

and by Observation 4.2,

$$\begin{aligned} \operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f)) &= \sum_{\gamma \in \{\Gamma\}} \chi_{\rho}(\gamma) \sum_{x \in \mathcal{R}_{\Gamma_{\gamma} \setminus G}} f(x^{-1}\gamma x) \\ &= \sum_{\gamma \in \{\Gamma\}} \chi_{\rho}(\gamma) \sum_{t \in \mathcal{R}_{G_{\gamma} \setminus G}} \sum_{y \in \mathcal{R}_{\Gamma_{\gamma} \setminus G_{\gamma}}} f(t^{-1}y^{-1}\gamma yt) \\ &= \sum_{\gamma \in \{\Gamma\}} \chi_{\rho}(\gamma) \frac{|G_{\gamma}|}{|\Gamma_{\gamma}|} \sum_{t \in \mathcal{R}_{G_{\gamma} \setminus G}} f(t^{-1}\gamma t) = I(\rho, f), \end{aligned}$$

which is the geometric side of the formula stated in (4), completing the proof of Theorem 3.1.

#### 5. TRACE FORMULA FOR G IN "ARTHUR FORM"

Finite groups are (locally) compact groups under the discrete topology. By compactness of *G*, there is a *unique* (left and right invariant) Haar measure  $d\mu_G^{\text{Haar}}$  on *G*, which in this case is nothing but the counting measure  $d\mu_G^{\text{Count}}$  on *G*. The same holds true for the subgroup  $\Gamma$  of *G* as well as the subgroups  $\Gamma_{\gamma}$  and  $G_{\gamma}$  of  $\Gamma$  and *G*, respectively, for  $\gamma \in {\Gamma}$ . So the invariant measures on the coset spaces  $\Gamma_{\gamma} \setminus G_{\gamma}$  and  $G_{\gamma} \setminus G$ , which are defined by the products  $d\mu_{G_{\gamma}}^{\text{Haar}} = d\mu_{\Gamma_{\gamma}}^{\text{Haar}} \times d\mu_{\Gamma_{\gamma} \setminus G_{\gamma}}^{\text{Haar}}$  and  $d\mu_G^{\text{Haar}} = d\mu_{G_{\gamma}}^{\text{Haar}} \times d\mu_{G_{\gamma} \setminus G}^{\text{Haar}}$  for  $\gamma \in {\Gamma}$  are all uniquely defined and are the counting measures on  $\Gamma_{\gamma} \setminus G_{\gamma}$  and  $G_{\gamma} \setminus G$ , respectively.

Therefore, in this setting, for  $\gamma \in \{\Gamma\}$ ,

$$a_{\Gamma}^{G}(\gamma) := \operatorname{vol}(\Gamma_{\gamma} \setminus G_{\gamma}) = \int_{\Gamma_{\gamma} \setminus G_{\gamma}} d\mu_{G_{\gamma}}^{\operatorname{Haar}} = \int_{\Gamma_{\gamma} \setminus G_{\gamma}} d\mu_{G_{\gamma}}^{\operatorname{Count}} = \sum_{y \in \mathcal{R}_{\Gamma_{\gamma} \setminus G_{\gamma}}} 1 = \frac{|G_{\gamma}|}{|\Gamma_{\gamma}|}.$$

Define the orbital integral  $O(\gamma, f)$  of  $f: G \to \mathbb{C}$  over the conjugacy class  $C_{\gamma}^{G}$  of  $\gamma \in {\Gamma}$  in G by

$$O(\gamma, f) := \int_{G_{\gamma} \setminus G} f(t^{-1}\gamma t) \frac{d\mu_{G}^{\text{Haar}}}{d\mu_{G_{\gamma}}^{\text{Haar}}} = \int_{G_{\gamma} \setminus G} f(t^{-1}\gamma t) \frac{d\mu_{G}^{\text{Count}}}{d\mu_{G_{\gamma}}^{\text{Count}}} = \sum_{t \in \mathcal{R}_{G_{\gamma} \setminus G}} f(t^{-1}\gamma t).$$

So, the trace formula for G with respect to the subgroup  $\Gamma$  and  $\rho: \Gamma \to GL(V_{\rho})$  stated in (4) becomes:

**Theorem 5.1. (Trace formula for finite groups – Arthur form)** For any function  $f : G \to \mathbb{C}$ , the trace  $\operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f))$  of the operator

$$\operatorname{Ind}_{\Gamma}^{G}(\rho)(f) : \operatorname{Ind}_{\Gamma}^{G}(V_{\rho}) \to \operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$$

on the  $\mathbb{C}$ -linear space  $\operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  satisfies the identity

$$J(\rho, f) = \sum_{\pi_o \in [\pi] \in \Pi(G)} m(\pi_o, \mathsf{Ind}_{\Gamma}^G(\rho)) \operatorname{Tr}(\pi_o(f)) = \operatorname{Tr}(\mathsf{Ind}_{\Gamma}^G(\rho)(f)) = \sum_{\gamma \in \{\Gamma\}} \chi_\rho(\gamma) a_{\Gamma}^G(\gamma) \mathcal{O}(\gamma, f) = I(\rho, f), \quad (7)$$

where

- { $\Gamma$ } = a set consisting of all representatives for the conjugacy classes in  $\Gamma$ ; -  $\Gamma_{\gamma} = \{\delta \in \Gamma \mid \delta^{-1}\gamma\delta = \gamma\}$  for  $\gamma \in \{\Gamma\}$ ; -  $G_{\gamma} = \{g \in G \mid g^{-1}\gamma g = \gamma\}$  for  $\gamma \in \{\Gamma\}$ .

*Here,*  $J(\rho, f)$  and  $I(\rho, f)$  are the spectral side and the geometric side of the trace formula for the finite group G with respect to the subgroup  $\Gamma$  and  $\rho : \Gamma \to GL(V_{\rho})$ , respectively.

Theorem 5.1 is exactly the trace formula given in Arthur (Arthur 2005, eq (1.3)).

#### 6. TEST FUNCTIONS $F : G \to \mathbb{C}$

Clearly, the operator  $\operatorname{Ind}_{\Gamma}^{G}(\rho)(f) : \operatorname{Ind}_{\Gamma}^{G}(V_{\rho}) \to \operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  on the  $\mathbb{C}$ -linear space  $\operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  depends on the choice of  $f: G \to \mathbb{C}$ . Therefore the trace formula for the finite group G with respect to the subgroup  $\Gamma$  and  $\rho: \Gamma \to \operatorname{GL}(V_{\rho})$ , namely, the spectral side  $J(\rho, f)$  and the geometric side  $I(\rho, f)$  of the formula corresponding to the trace  $\operatorname{Tr}(\operatorname{Ind}_{\Gamma}^{G}(\rho)(f))$  of  $\operatorname{Ind}_{\Gamma}^{G}(\rho)(f) : \operatorname{Ind}_{\Gamma}^{G}(V_{\rho}) \to \operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  depend on the function  $f: G \to \mathbb{C}$  as well. The function  $f: G \to \mathbb{C}$  is called a "test function" of the trace formula for G (with respect to the subgroup  $\Gamma$  and  $\rho: \Gamma \to \operatorname{GL}(V_{\rho})$ ), and choosing  $f: G \to \mathbb{C}$  carefully, the trace identities for the operator  $\operatorname{Ind}_{\Gamma}^{G}(\rho)(f) : \operatorname{Ind}_{\Gamma}^{G}(V_{\rho}) \to \operatorname{Ind}_{\Gamma}^{G}(V_{\rho})$  yield extremely deep results.

The first example is the Frobenius reciprocity law for the finite group G.

**Example 6.1.** (Frobenius reciprocity law for *G*) For any  $\sigma_o \in [\sigma] \in \Pi(G)$ ,

$$\left\langle \mathsf{Ind}_{\Gamma}^{G}(\rho), \sigma_{o} \right\rangle_{G} = \left\langle \rho, \mathsf{Res}_{\Gamma}^{G}(\sigma_{o}) \right\rangle_{\Gamma}$$

**Proof.** For  $\sigma_o \in [\sigma] \in \Pi(G)$ , define a test function  $f_{\sigma_o} : G \to \mathbb{C}$  by  $f_{\sigma_o}(g) = \overline{\chi}_{\sigma_o}(g) = \overline{\chi}_{\sigma_o}(g)$  for  $g \in G$ . The spectral side  $J(\rho, f_{\sigma_o})$  of the trace formula for the operator  $\mathsf{Ind}_{\Gamma}^G(\rho)(f_{\sigma_o}) : \mathsf{Ind}_{\Gamma}^G(V_{\rho}) \to \mathsf{Ind}_{\Gamma}^G(V_{\rho})$  on  $\mathsf{Ind}_{\Gamma}^G(V_{\rho})$  is then given by

$$J(\rho, f_{\sigma_o}) = \sum_{\pi_o \in [\pi] \in \Pi(G)} m(\pi_o, \mathsf{Ind}_{\Gamma}^G(\rho)) \operatorname{Tr}(\pi_o(f_{\sigma_o}))$$
  
$$= \sum_{\pi_o \in [\pi] \in \Pi(G)} m(\pi_o, \mathsf{Ind}_{\Gamma}^G(\rho)) \operatorname{Tr}(\sum_{g \in G} f_{\sigma_o}(g)\pi_o(g))$$
  
$$= \sum_{\pi_o \in [\pi] \in \Pi(G)} m(\pi_o, \mathsf{Ind}_{\Gamma}^G(\rho)) \sum_{g \in G} f_{\sigma_o}(g) \operatorname{Tr}(\pi_o(g)).$$

Now, by the orthogonality of irreducible characters of *G*, for  $\pi_o \in [\pi] \in \Pi(G)$ ,

$$\sum_{g \in G} f_{\sigma_o}(g) \operatorname{Tr}(\pi_o(g)) = \sum_{g \in G} \overline{\chi}_{\sigma_o}(g) \chi_{\pi_o}(g) = \begin{cases} |G|, & \pi_o = \sigma_o, \\ 0, & [\pi_o] \cap [\sigma_o] = \emptyset. \end{cases}$$

Therefore, the spectral side  $J(\rho, f_{\sigma_o})$  of the trace formula for the operator  $\operatorname{Ind}_{\Gamma}^G(\rho)(f_{\sigma_o}) : \operatorname{Ind}_{\Gamma}^G(V_{\rho}) \to \operatorname{Ind}_{\Gamma}^G(V_{\rho})$  on  $\operatorname{Ind}_{\Gamma}^G(V_{\rho})$  is

$$J(\rho, f_{\sigma_o}) = \sum_{\pi_o \in [\pi] \in \Pi(G)} m(\pi_o, \mathsf{Ind}_{\Gamma}^G(\rho)) \sum_{g \in G} f_{\sigma_o}(g) \mathrm{Tr}(\pi_o(g)) = |G| m(\sigma_o, \mathsf{Ind}_{\Gamma}^G(\rho)) = |G| \left\langle \mathsf{Ind}_{\Gamma}^G(\rho), \sigma_o \right\rangle_G,$$

that is,

$$\frac{1}{|G|}J(\rho,f_{\sigma_o}) = \left\langle \mathsf{Ind}_{\Gamma}^G(\rho),\sigma_o \right\rangle_G$$

Next, computing the " $|G|^{-1}$  multiple" of the geometric side  $I(\rho, f_{\sigma_o})$  of the trace formula for the operator  $\operatorname{Ind}_{\Gamma}^G(\rho)(f_{\sigma_o})$ :  $\operatorname{Ind}_{\Gamma}^G(V_{\rho}) \to \operatorname{Ind}_{\Gamma}^G(V_{\rho})$  on  $\operatorname{Ind}_{\Gamma}^G(V_{\rho})$ ,

$$\begin{split} \frac{1}{|G|} I(\rho, f_{\sigma_o}) &= \frac{1}{|G|} \sum_{\gamma \in \{\Gamma\}} \chi_{\rho}(\gamma) a_{\Gamma}^G(\gamma) \mathcal{O}(\gamma, f_{\sigma_o}) \\ &= \frac{1}{|G|} \sum_{\gamma \in \{\Gamma\}} \chi_{\rho}(\gamma) \operatorname{vol}(\Gamma_{\gamma} \backslash G_{\gamma}) \sum_{t \in \mathcal{R}_{G_{\gamma} \backslash G}} f_{\sigma_o}(t^{-1} \gamma t) \\ &= \frac{1}{|G|} \sum_{\gamma \in \{\Gamma\}} \chi_{\rho}(\gamma) \operatorname{vol}(\Gamma_{\gamma} \backslash G_{\gamma}) \operatorname{vol}(G_{\gamma} \backslash G) \overline{\chi}_{\sigma_o}(\gamma) \\ &= \sum_{\gamma \in \{\Gamma\}} \frac{\chi_{\rho}(\gamma) \overline{\chi}_{\sigma_o}(\gamma)}{|\Gamma_{\gamma}|} \\ &= \frac{1}{|\Gamma|} \sum_{\gamma \in \{\Gamma\}} \frac{|\Gamma|}{|\Gamma_{\gamma}|} \chi_{\rho}(\gamma) \overline{\chi}_{\sigma_o}(\gamma). \end{split}$$

Observe that, for  $\gamma \in \{\Gamma\}$ , the coset space  $\Gamma_{\gamma} \setminus \Gamma$  is in bijective correspondence with the conjugacy class  $C_{\gamma}^{\Gamma}$  of  $\gamma \in \{\Gamma\}$  in  $\Gamma$  under the bijection  $\Gamma_{\gamma} \setminus \Gamma \to C_{\gamma}^{\Gamma}$  defined by  $\Gamma_{\gamma} \delta \mapsto x^{-1} \gamma \delta$  for all  $\delta \in \Gamma$ . Therefore,  $\frac{|\Gamma|}{|\Gamma_{\gamma}|} = |C_{\gamma}^{\Gamma}|$ , and the following identities

$$\frac{1}{|G|}I(\rho, f_{\sigma_o}) = \frac{1}{|\Gamma|} \sum_{\gamma \in \{\Gamma\}} \frac{|\Gamma|}{|\Gamma_{\gamma}|} \chi_{\rho}(\gamma) \overline{\chi}_{\sigma_o}(\gamma) = \frac{1}{|\Gamma|} \sum_{\gamma \in \{\Gamma\}} |C_{\gamma}^{\Gamma}| \chi_{\rho}(\gamma) \overline{\chi}_{\sigma_o}(\gamma) = \frac{1}{|\Gamma|} \sum_{\delta \in \Gamma} \chi_{\rho}(\delta) \overline{\chi}_{\sigma_o}(\delta) = \left\langle \rho, \mathsf{Res}_{\Gamma}^G(\sigma_o) \right\rangle_{H^1}$$

follow at once, completing the proof of the Frobenius reciprocity law.

For the second example, define an inner product

$$(\bullet \mid \bullet) : \mathbb{C}[G] \times \mathbb{C}[G] \to \mathbb{C}$$

on the group algebra  $\mathbb{C}[G]$  of G over  $\mathbb{C}$  by

$$(f \mid h) := |G| \sum_{g \in G} f(g^{-1})h(g), \quad \forall f, h \in \mathbb{C}[G].$$

The Fourier transform

$$\mathcal{F}_{\mathsf{r}}: \mathbb{C}[G] \to \mathsf{End}_{\mathbb{C}}(V_{\mathsf{r}})$$

on G coupled to a representation  $r: G \to \operatorname{GL}(V_r)$  of G on a d-dimensional vector space  $V_r$  over  $\mathbb{C}$  is defined by

$$\mathcal{F}_{\mathsf{r}}: f \mapsto \mathcal{F}_{\mathsf{r}} f \eqqcolon \widehat{f}(\mathsf{r}) \stackrel{def}{=} \sum_{g \in G} f(g)\mathsf{r}(g) = \mathsf{r}(f), \quad \forall f \in \mathbb{C}[G].$$

It is well known and easy to derive that

$$\widehat{f * h}(\mathbf{r}) = \widehat{f}(\mathbf{r}) \circ \widehat{h}(\mathbf{r}), \quad \forall f, h \in \mathbb{C}[G].$$
(8)

Here, for  $f, h \in \mathbb{C}[G]$ , their convolution product  $f * h \in \mathbb{C}[G]$  is defined by  $(f * h)(x) = \sum_{g \in G} f(xg^{-1})h(g)$  for all  $x \in G$ . So  $(f * h)(1) = \sum_{g \in G} f(g^{-1})h(g)$ .

Now, having set the stage, we can now state and prove the Plancherel formula for G in the following example.

**Example 6.2.** (Plancherel formula for *G*) For any two functions  $f, h : G \to \mathbb{C}$ ,

$$(f \mid h) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathrm{d}_{\pi_o} \mathrm{Tr}(\widehat{f}(\pi_o) \circ \widehat{h}(\pi_o)).$$

**Proof.** For any two functions  $f, h: G \to \mathbb{C}$  and for any  $\pi_o \in [\pi] \in \Pi(G)$ , by (8) the identity  $\widehat{f * h}(\pi_o) = \widehat{f}(\pi_o) \circ \widehat{h}(\pi_o)$  holds true. Therefore, the right-hand side of the Plancherel formula becomes

$$\sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\widehat{f}(\pi_o) \circ \widehat{h}(\pi_o)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\widehat{f * h}(\pi_o)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)).$$

Now, we consider the standard case of the trace formula for the finite group G; that is, the trace formula for G with respect

to the subgroup  $\Gamma = \langle 1 \rangle$  and  $\rho = \mathbb{1}_{\Gamma} : \Gamma \to \operatorname{GL}(\mathbb{C})$ . Then, by (7), the spectral side  $J(\mathbb{1}_{\langle 1 \rangle}, f * h)$  of the trace formula for *G* with respect to the subgroup  $\langle 1 \rangle$  and  $\mathbb{1}_{\langle 1 \rangle} : \langle 1 \rangle \to \operatorname{GL}(\mathbb{C})$  reads as

$$J(\mathbb{F}_{\langle 1 \rangle}, f * h) = \sum_{\pi_o \in [\pi] \in \Pi(G)} m(\pi_o, \mathsf{Ind}_{\langle 1 \rangle}^G(\mathbb{F}_{\langle 1 \rangle})) \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in [\pi] \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h)) = \sum_{\pi_o \in \Pi(G)} \mathsf{d}_{\pi_o} \operatorname{Tr}(\pi_o(f * h$$

and the geometric side of  $I(\mathbb{H}_{\langle 1 \rangle}, f * h)$  of the trace formula for *G* with respect to the subgroup  $\langle 1 \rangle$  and  $\mathbb{H}_{\langle 1 \rangle} : \langle 1 \rangle \rightarrow GL(\mathbb{C})$  reduces to

$$I(\mathbb{1}_{\langle 1 \rangle}, f * h) = \sum_{\gamma \in \{\langle 1 \rangle\}} \chi_{\mathbb{1}_{\langle 1 \rangle}}(\gamma) a^G_{\langle 1 \rangle}(\gamma) \mathcal{O}(\gamma, f * h) = |G|(f * h)(1) = |G| \sum_{g \in G} f(g^{-1})h(g) = (f \mid h),$$

completing the proof of the Plancherel formula for G.

Our third example needs some preliminaries. Hence deserves discussion in a new section.

#### 7. THE "AUTOMORPHIC SIDE" OF THE MACDONALD CORRESPONDENCE FOR $GL_N(\mathbb{F}_O)$

Macdonald proved Macdonald (1980) an analogue of the local Langlands correspondence for  $GL_n(F)$  where *F* is a local field with finite residue class field  $\kappa_F = \mathbb{F}_q$  for the finite group  $GL_n(\mathbb{F}_q)$ ; namely, following the reformulation of Vogan Vogan (2020), there exists a bijective correspondence

$$\mathcal{M}_{n}(\mathbb{F}_{q}): \mathcal{X}_{n}(\mathsf{WM}_{\mathbb{F}_{q}}) \rightleftharpoons \mathsf{\Pi}(\mathsf{GL}_{n}(\mathbb{F}_{q})) \tag{9}$$

between the set  $X_n(WM_{\mathbb{F}_q})$  of "isomorphism classes of complex *n*-dimensional admissible, that is  $\operatorname{Frob}_q$  equivariant and semisimple representations of the absolute Weil-Macdonald group  $WM_{\mathbb{F}_q}$  of  $\mathbb{F}_q$ " and the set  $\Pi(\operatorname{GL}_n(\mathbb{F}_q))$  of "isomorphism classes of irreducible representations of  $\operatorname{GL}_n(\mathbb{F}_q)$  over  $\mathbb{C}$ " (but we can also assume over  $\overline{\mathbb{Q}}_\ell, \Omega_\ell, \ldots$ ) where  $q = p^f$  with *p* a prime number and  $0 < f \in \mathbb{Z}$ . Here,  $WM_{\mathbb{F}_q}$  is defined by  $WM_{\mathbb{F}_q} = (\lim_m \mathbb{F}_{q^m}^{\times}) \ltimes \mathbb{C}^+$  where the inverse limit  $\lim_m \mathbb{F}_{q^m}^{\times}$  is with respect to the connecting maps given by the norm maps  $\mathbb{F}_{q^m}^{\times} \xleftarrow{N_{md/m}}{\mathbb{F}_{q^{md}}} \mathbb{F}_{q^{md}}^{\times}$  for all  $0 < m, d \in \mathbb{Z}$ . The action of  $\operatorname{Frob}_q$  on  $WM_{\mathbb{F}_q}$  is defined by the *q*-th power map and the multiplication by *q* on the components of  $WM_{\mathbb{F}_q}$ , and the action of  $\varprojlim_q \mathbb{F}_q^{\times}$ 

WM<sub>F<sub>q</sub></sub> is defined by the *q*-th power map and the multiplication by *q* on the components of WM<sub>F<sub>q</sub></sub>, and the action of  $\varprojlim_{m} \mathbb{F}_{q^m}^{\times}$ on the additive group  $\mathbb{C}^+$  is defined via the canonical isomorphism  $\varprojlim_{m} \mathbb{F}_{q^m}^{\times} \approx I_F/P_F$  where *F* is a local field with  $\kappa_F = \mathbb{F}_q$ , and  $I_F$ ,  $P_F$  are the inertia and the wild inertia subgroups of the Weil group  $W_F$  of *F* together with the homomorphism  $|.|_F \circ \operatorname{Art}_F : W_F \xrightarrow{\operatorname{Art}_F} F^{\times} \xrightarrow{|.|_F} \mathbb{R}_{>0}^{\times}$ , where  $\operatorname{Art}_F : W_F \to F^{\times}$  is the local Artin reciprocity law of *F*. This correspondence satisfies the "naturality" properties; that is, matching of corresponding local  $\epsilon$ -factors and corresponding local  $\zeta$ - and *L*-factors, and corresponding conductors. The bijection (9) is called the Macdonald correspondence for  $\operatorname{GL}_n(\mathbb{F}_q)$ , which needs further discussion and postponed to a future study

In this note we are interested in  $\Pi(\operatorname{GL}_n(\mathbb{F}_q))$ , namely the "automorphic side" of the Macdonald correspondence (9) for  $\operatorname{GL}_n(\mathbb{F}_q)$ , and the main references that we follow closely are Carter (1993); Green (1955) and Macdonald (1980); Ye and Zelingher (2021).

#### 7.1. Parabolic induction and cuspidal representations of $GL_n(\mathbb{F}_q)$

To describe the "automorphic side" of the Macdonald correspondence (9) for  $GL_n(\mathbb{F}_q)$  precisely, let us fix :

-  $\mathcal{J} = \{j_1, \dots, j_s\}$  an ordered partition of *n*; that is, 0 < *j*<sub>1</sub>, ..., *j*<sub>s</sub> ∈  $\mathbb{Z}$  such that the ordered sum *j*<sub>1</sub> + ... + *j*<sub>s</sub> = *n*. -  $\mathsf{P}_{\mathcal{J}}$  the standard parabolic subgroup of  $\mathsf{GL}_n(\mathbb{F}_q)$  with respect to the partition  $\mathcal{J}$  defined by

$$\mathsf{P}_{\mathcal{J}} \coloneqq \begin{bmatrix} \mathsf{GL}_{j_1}(\mathbb{F}_q) & \times & \times & \times & \times \\ & \mathsf{GL}_{j_2}(\mathbb{F}_q) & \times & \times & \times \\ & & \ddots & \times & \times \\ & & & \ddots & \times \\ & & & & \mathsf{GL}_{j_s}(\mathbb{F}_q) \end{bmatrix}_{n \times n};$$

 $-M_{\mathcal{J}}$  the Levi factor of  $P_{\mathcal{J}}$  by

$$\mathsf{M}_{\mathcal{J}} \coloneqq \left[ \begin{array}{ccc} \mathsf{GL}_{j_1}(\mathbb{F}_q) & & & \\ & \mathsf{GL}_{j_2}(\mathbb{F}_q) & & \mathbf{0} \\ & & \ddots & & \\ & & \mathbf{0} & & \ddots & \\ & & & & \mathsf{GL}_{j_s}(\mathbb{F}_q) \end{array} \right]_{n \times n};$$

 $- N_{\mathcal{J}}$  the unipotent radical of  $P_{\mathcal{J}}$  by

$$\mathsf{N}_{\mathcal{J}} \coloneqq \begin{bmatrix} \mathsf{1}_{j_1} & \times & \times & \times & \times \\ & \mathsf{1}_{j_2} & \times & \times & \times \\ & & \ddots & \times & \times \\ & & & \ddots & \times \\ & & & & \mathsf{1}_{j_s} \end{bmatrix}_{n \times n}$$

Note that,  $M_{\mathcal{J}}$  acts on  $N_{\mathcal{J}}$  by conjugation, and

$$\mathsf{P}_{\mathcal{J}} = \mathsf{M}_{\mathcal{J}} \ltimes \mathsf{N}_{\mathcal{J}}.$$

For  $1 \le i \le s$ , let  $\pi_i : \operatorname{GL}_{j_i}(\mathbb{F}_q) \to \operatorname{GL}(V_{\pi_i})$  be a representation of  $\operatorname{GL}_{j_i}(\mathbb{F}_q)$  on a  $d_i$ -dimensional vector space  $V_{\pi_i}$  over  $\mathbb{C}$ . Then, the natural isomorphism  $\operatorname{M}_{\mathcal{J}} \xrightarrow{\sim} \prod_{1 \le i \le s} \operatorname{GL}_{j_i}(\mathbb{F}_q)$  yields a representation  $\operatorname{M}_{\mathcal{J}} \xrightarrow{\sim} \prod_{1 \le i \le s} \operatorname{GL}_{j_i}(\mathbb{F}_q) \xrightarrow{\mathfrak{S}_{1 \le i \le s} \pi_i} \operatorname{GL}(\bigotimes_{1 \le i \le s} V_{\pi_i})$  of the Levi factor  $\operatorname{M}_{\mathcal{J}}$  of  $\mathsf{P}_{\mathcal{J}}$  on the  $\mathbb{C}$ -linear space  $\bigotimes_{1 \le i \le s} V_{\pi_i}$ , which in return defines via inflation to  $\mathsf{P}_{\mathcal{J}}$  a representation  $\widetilde{\mathfrak{S}}_{1 \le i \le s} \pi_i : \mathsf{P}_{\mathcal{J}} \to \operatorname{GL}(\bigotimes_{1 \le i \le s} V_{\pi_i})$  of  $\mathsf{P}_{\mathcal{J}}$  on  $\bigotimes_{1 \le i \le s} V_{\pi_i}$  by letting the matrices in  $\mathsf{N}_{\mathcal{J}}$  act as the identity on  $\bigotimes_{1 \le i \le s} V_{\pi_i}$ . Consider the representation

$$\pi_1 \circ \cdots \circ \pi_s := \mathsf{Ind}_{\mathsf{P}_{\mathcal{J}}}^{\mathsf{GL}_n(\mathbb{F}_q)}(\widetilde{\boldsymbol{\otimes}}_{1 \le i \le s} \pi_i) : \mathsf{GL}_n(\mathbb{F}_q) \to \mathsf{GL}(\mathsf{Ind}_{\mathsf{P}_{\mathcal{J}}}^{\mathsf{GL}_n(\mathbb{F}_q)}(\bigotimes_{1 \le i \le s} V_{\pi_i}))$$

of  $\operatorname{GL}_n(\mathbb{F}_q)$  on  $\operatorname{Ind}_{\mathsf{P}_{\mathcal{T}}}^{\operatorname{GL}_n(\mathbb{F}_q)}(\bigotimes_{1 \le i \le s} V_{\pi_i})$  constructed by this parabolic induction process. For  $1 < n \in \mathbb{Z}$ , an irreducible representation  $\pi : \operatorname{GL}_n(\mathbb{F}_q) \to \operatorname{GL}(V_\pi)$  of  $\operatorname{GL}_n(\mathbb{F}_q)$  on a *d*-dimensional vector space  $V_\pi$  over  $\mathbb{C}$  is called cuspidal, if it does not occur in any representation of  $\operatorname{GL}_n(\mathbb{F}_q)$  of the form  $\pi_1 \circ \pi_2$ , where  $\pi_1 : \operatorname{GL}_{j_1}(\mathbb{F}_q) \to \operatorname{GL}(V_{\pi_1})$  and  $\pi_2 : \operatorname{GL}_{j_2}(\mathbb{F}_q) \to \operatorname{GL}(V_{\pi_2})$  are both irreducible and  $0 < j_1, j_2 \in \mathbb{Z}$  such that  $j_1 + j_2 = n$ . For n = 1, all irreducible representations of  $\operatorname{GL}_1(\mathbb{F}_q) = \mathbb{F}_q^{\times}$  over  $\mathbb{C}$  are by definition cuspidal. The "Philosophy of Cusp Forms" of Harish-Chandra (for details Bump (2013)) states that the cuspidal representations of  $\operatorname{GL}_n(\mathbb{F}_q)$  are the basic building blocks of all irreducible representations of  $\operatorname{GL}_n(\mathbb{F}_q)$  in the sense that for  $\pi_o \in [\pi] \in \Pi(\operatorname{GL}_n(\mathbb{F}_q))$ , there exists an ordered partition  $\mathcal{J} = \{j_1, \dots, j_s\}$  of *n* and cuspidal representations  $\pi_1, \dots, \pi_s$  of  $\operatorname{GL}_{j_1}(\mathbb{F}_q), \dots, \operatorname{GL}_{j_s}(\mathbb{F}_q)$ , respecively, such that  $\pi_o$  is an irreducible constituent of  $\pi_1 \circ \cdots \circ \pi_s$ . This completes the description of the set  $\Pi(\operatorname{GL}_n(\mathbb{F}_q))$  of isomorphism classes of irreducible representations of  $\operatorname{GL}_n(\mathbb{F}_q)$  over  $\mathbb{C}$  via the "Philosophy of Cusp Forms".

#### 7.2. $\zeta$ -functions (integrals) of $GL_n(\mathbb{F}_q)$

For a representation  $\pi : \operatorname{GL}_n(\mathbb{F}_q) \to \operatorname{GL}(V_\pi)$  of  $\operatorname{GL}_n(\mathbb{F}_q)$  on a *d*-dimensional vector space  $V_\pi$  over  $\mathbb{C}$ , denoting the set of all  $n \times n$  matrices over  $\mathbb{F}_q$  by  $\mathsf{M}_n(\mathbb{F}_q)$ , Macdonald attached a function

$$\mathsf{Z}(\bullet,\pi): \mathbb{C}[\mathsf{M}_n(\mathbb{F}_q)] \to \mathsf{End}_{\mathbb{C}}(V_\pi)$$

defined by

$$\mathsf{Z}(\Phi,\pi) := \pi(\Phi) = \sum_{g \in \mathsf{GL}_n(\mathbb{F}_q)} \Phi(g) \pi(g), \ \ ^{\forall} \Phi \in \mathbb{C}[\mathsf{M}_n(\mathbb{F}_q)],$$

called the  $\zeta$ -function of the representation  $\pi : \operatorname{GL}_n(\mathbb{F}_q) \to \operatorname{GL}(V_\pi)$  of  $\operatorname{GL}_n(\mathbb{F}_q)$  on  $V_\pi$  over  $\mathbb{C}$  (Macdonald 1980, Section 2).

Now, the trace formula for  $GL_n(\mathbb{F}_q)$  with respect to the parabolic subgroup  $\mathsf{P}_{\mathcal{J}}$  of  $GL_n(\mathbb{F}_q)$  corresponding to an ordered partition  $\mathcal{J}$  of n and  $\rho : \mathsf{P}_{\mathcal{J}} \to GL(V_\rho)$  computes the trace  $\operatorname{Tr}(\mathsf{Z}(\Phi, \mathsf{Ind}_{\mathsf{P}_{\mathcal{J}}}^{GL_n(\mathbb{F}_q)}(\rho)))$  of the operator  $\mathsf{Z}(\Phi, \mathsf{Ind}_{\mathsf{P}_{\mathcal{J}}}^{GL_n(\mathbb{F}_q)}(\rho)) :$  $\operatorname{Ind}_{\mathsf{P}_{\mathcal{J}}}^{GL_n(\mathbb{F}_q)}(V_\rho) \to \operatorname{Ind}_{\mathsf{P}_{\mathcal{J}}}^{GL_n(\mathbb{F}_q)}(V_\rho)$  on the  $\mathbb{C}$ -linear space  $\operatorname{Ind}_{\mathsf{P}_{\mathcal{J}}}^{GL_n(\mathbb{F}_q)}(V_\rho)$ . More precisely, we have the following theorem, which is essentially a reformulation of Theorem 5.1 in this setting. **Theorem 7.1.** For any function  $\Phi : \mathsf{M}_n(\mathbb{F}_q) \to \mathbb{C}$ , the trace  $\operatorname{Tr}(\mathsf{Z}(\Phi, \mathsf{Ind}_{\mathsf{P}_q}^{\operatorname{GL}_n(\mathbb{F}_q)}(\rho)))$  of the operator

$$\mathsf{Z}(\Phi,\mathsf{Ind}_{\mathsf{P}_{\mathcal{J}}}^{\mathsf{GL}_{n}(\mathbb{F}_{q})}(\rho)):\mathsf{Ind}_{\mathsf{P}_{\mathcal{J}}}^{\mathsf{GL}_{n}(\mathbb{F}_{q})}(V_{\rho})\to\mathsf{Ind}_{\mathsf{P}_{\mathcal{J}}}^{\mathsf{GL}_{n}(\mathbb{F}_{q})}(V_{\rho})$$

on the  $\mathbb{C}$ -linear space  $\operatorname{Ind}_{\mathsf{P}_{\mathcal{T}}}^{\operatorname{GL}_{n}(\mathbb{F}_{q})}(V_{\rho})$  satisfies the identity

$$\sum_{\pi_o \in [\pi] \in \Pi(\mathsf{GL}_n(\mathbb{F}_q))} m(\pi_o, \mathsf{Ind}_{\mathsf{P}_{\mathcal{J}}}^{\mathsf{GL}_n(\mathbb{F}_q)}(\rho)) \operatorname{Tr}(\mathsf{Z}(\Phi, \pi_o)) = \operatorname{Tr}(\mathsf{Z}(\Phi, \mathsf{Ind}_{\mathsf{P}_{\mathcal{J}}}^{\mathsf{GL}_n(\mathbb{F}_q)}(\rho))) = \sum_{\gamma \in \{\mathsf{P}_{\mathcal{J}}\}} \chi_{\rho}(\gamma) a_{\mathsf{P}_{\mathcal{J}}}^{\mathsf{GL}_n(\mathbb{F}_q)}(\gamma) \mathcal{O}(\gamma, \Phi),$$

where

 $- \{P_{\mathcal{J}}\} = a \text{ set consisting of all representatives for the conjugacy classes in } P_{\mathcal{J}};$  $- \mathsf{P}_{\mathcal{J}_{\gamma}} = \{\delta \in \mathsf{P}_{\mathcal{J}} \mid \delta^{-1}\gamma\delta = \gamma\} \text{ for } \gamma \in \{\mathsf{P}_{\mathcal{J}}\}; \\ - \mathsf{GL}_{n}(\mathbb{F}_{q})_{\gamma} = \{g \in \mathsf{GL}_{n}(\mathbb{F}_{q}) \mid g^{-1}\gamma g = \gamma\} \text{ for } \gamma \in \{\mathsf{P}_{\mathcal{J}}\}.$ 

*Furthermore, for*  $\gamma \in \{\mathsf{P}_{\mathcal{T}}\}$ *,* 

$$a_{\mathsf{P}_{\mathcal{J}}}^{\mathrm{GL}_{n}(\mathbb{F}_{q})}(\gamma) = \frac{|\mathrm{GL}_{n}(\mathbb{F}_{q})_{\gamma}|}{|\mathsf{P}_{\mathcal{J}_{\gamma}}|}$$

and the orbital integral  $O(\gamma, \Phi)$  of  $\Phi : M_n(\mathbb{F}_q) \to \mathbb{C}$  over the conjugacy class  $C_{\gamma}^{\operatorname{GL}_n(\mathbb{F}_q)}$  of  $\gamma$  in  $\operatorname{GL}_n(\mathbb{F}_q)$  is given by

$$\mathcal{O}(\gamma, \Phi) = \sum_{t \in \mathcal{R}_{\mathrm{GL}_n(\mathbb{F}_q)\gamma \setminus \mathrm{GL}_n(\mathbb{F}_q)} \Phi(t^{-1}\gamma t).$$

There is an important special case of Theorem 7.1. Let  $\mathcal{J}_1 = \{1, \dots, 1\}$  be the ordered partition of n given by n-copies

 $1 + \cdots + 1 = n$ . Then  $N_{\mathcal{J}_1}$  becomes the subgroup of  $GL_n(\mathbb{F}_q)$  consisting of the upper traingular unipotent matrices in  $\operatorname{GL}_n(\mathbb{F}_q)$ . Now, define a 1-dimensional representation

$$\theta_{\psi}: \mathsf{N}_{\mathcal{J}_1} \to \mathbb{C}^{\times}$$

of  $N_{\mathcal{J}_1}$  over  $\mathbb{C}$  by

$$\theta_{\psi} : [x_{ij}]_{\substack{1 \le i \le n \\ 1 \le j \le n}} \mapsto \psi(x_{12} + x_{23} + \dots + x_{(n-1)n}), \quad \forall [x_{ij}]_{\substack{1 \le i \le n \\ 1 \le j \le n}} \in \mathsf{N}_{\mathcal{J}_1}, \tag{10}$$

where  $\psi : \mathbb{F}_q^+ \to \mathbb{C}^{\times}$  is a non-trivial additive character of  $\mathbb{F}_q$ . Set  $\mathbb{C} = V_{\theta_{\psi}}$ . The representation

$$\operatorname{Ind}_{\mathsf{N}_{\mathcal{J}_{l}}}^{\mathsf{GL}_{n}(\mathbb{F}_{q})}(\theta_{\psi}): \mathsf{GL}_{n}(\mathbb{F}_{q}) \to \mathsf{GL}(\operatorname{Ind}_{\mathsf{N}_{\mathcal{J}_{l}}}^{\mathsf{GL}_{n}(\mathbb{F}_{q})}(V_{\theta_{\psi}}))$$

of  $\operatorname{GL}_n(\mathbb{F}_q)$  on the  $\mathbb{C}$ -linear space  $\operatorname{Ind}_{N_{\mathcal{T}_1}}^{\operatorname{GL}_n(\mathbb{F}_q)}(V_{\theta_{\psi}})$  is multiplicity free; that is, it has multiplicity one property, which states:

- If 
$$\pi_o \in [\pi] \in \Pi(\operatorname{GL}_n(\mathbb{F}_q))$$
 then  $m(\pi_o, \operatorname{Ind}_{\mathsf{N}_{\mathcal{J}_1}}^{\operatorname{GL}_n(\mathbb{F}_q)}(\theta_{\psi})) \le 1$ 

Now,  $\pi_o \in [\pi] \in \Pi(\operatorname{GL}_n(\mathbb{F}_q))$  is said to have a Whittaker model if there exists a non-trivial additive character  $\psi : \mathbb{F}_q^+ \to \mathbb{C}^{\times d}$ of  $\mathbb{F}_q$  such that  $m(\pi_o, \mathsf{Ind}_{N_{\mathcal{J}_1}}^{\mathbf{GL}_n(\mathbb{F}_q)}(\theta_{\psi})) = 1$ . Moreover,

- If  $\pi_o$  is a cuspidal representation of  $GL_n(\mathbb{F}_q)$ , then  $\pi_o$  has a Whittaker model.

The trace formula for  $\operatorname{GL}_n(\mathbb{F}_q)$  with respect to the subgroup  $\mathsf{N}_{\mathcal{J}_1}$  of upper triangular unipotent matrices in  $\operatorname{GL}_n(\mathbb{F}_q)$ and  $\theta_{\psi} : \mathsf{N}_{\mathcal{J}_1} \to \mathbb{C}^{\times}$  given by (10) computes the trace  $\operatorname{Tr}(\mathsf{Z}(\Phi, \operatorname{Ind}_{\mathsf{N}_{\mathcal{J}_1}}^{\operatorname{GL}_n(\mathbb{F}_q)}(\theta_{\psi})))$  of the operator  $\mathsf{Z}(\Phi, \operatorname{Ind}_{\mathsf{N}_{\mathcal{J}_1}}^{\operatorname{GL}_n(\mathbb{F}_q)}(\theta_{\psi})) :$  $\operatorname{Ind}_{\mathsf{N}_{\mathcal{J}_1}}^{\operatorname{GL}_n(\mathbb{F}_q)}(V_{\theta_{\psi}}) \to \operatorname{Ind}_{\mathsf{N}_{\mathcal{J}_1}}^{\operatorname{GL}_n(\mathbb{F}_q)}(V_{\theta_{\psi}})$  on the  $\mathbb{C}$ -linear space  $\operatorname{Ind}_{\mathsf{N}_{\mathcal{J}_1}}^{\operatorname{GL}_n(\mathbb{F}_q)}(V_{\theta_{\psi}})$ , which has a simpler form thanks to the multiplicity one property of the representation  $\operatorname{Ind}_{\operatorname{N}_{\mathcal{J}_{l}}}^{\operatorname{GL}_{n}(\mathbb{F}_{q})}(\theta_{\psi}) : \operatorname{GL}_{n}(\mathbb{F}_{q}) \to \operatorname{GL}(\operatorname{Ind}_{\operatorname{N}_{\mathcal{J}_{l}}}^{\operatorname{GL}_{n}(\mathbb{F}_{q})}(V_{\theta_{\psi}}))$  of  $\operatorname{GL}_{n}(\mathbb{F}_{q})$  on the  $\mathbb{C}$ -linear space  $\operatorname{Ind}_{\operatorname{N}_{\tau}}^{\operatorname{GL}_{n}(\mathbb{F}_{q})}(V_{\theta_{\psi}})$ , which follows as a corollary of Theorem 7.1.

**Corollary 7.2.** For any function  $\Phi : \mathsf{M}_n(\mathbb{F}_q) \to \mathbb{C}$ , the trace  $\operatorname{Tr}(\mathsf{Z}(\Phi, \mathsf{Ind}_{\mathsf{N}_{\mathcal{T}}}^{\operatorname{GL}_n(\mathbb{F}_q)}(\theta_{\psi})))$  of the operator

$$\mathsf{Z}(\Phi,\mathsf{Ind}_{\mathsf{N}_{\mathcal{T}_{l}}}^{\mathsf{GL}_{n}(\mathbb{F}_{q})}(\theta_{\psi})):\mathsf{Ind}_{\mathsf{N}_{\mathcal{T}_{l}}}^{\mathsf{GL}_{n}(\mathbb{F}_{q})}(V_{\theta_{\psi}})\to\mathsf{Ind}_{\mathsf{N}_{\mathcal{T}_{l}}}^{\mathsf{GL}_{n}(\mathbb{F}_{q})}(V_{\theta_{\psi}})$$

on the  $\mathbb{C}$ -linear space  $\mathsf{Ind}_{\mathsf{N}_{\mathcal{J}_1}}^{\mathsf{GL}_n(\mathbb{F}_q)}(V_{\theta_\psi})$  satisfies the identity

$$\underbrace{\sum_{\substack{\pi_o \in [\pi] \in \Pi(\mathsf{GL}_n(\mathbb{F}_q)) \\ \pi_o \in [\pi] \in \Pi(\mathsf{GL}_n(\mathbb{F}_q)) \\ m(\pi_o, \mathsf{Ind}_{\mathsf{N}_{\mathcal{J}_1}}^{\mathsf{GL}_n(\mathbb{F}_q)}(\theta_{\psi})) = 1}}_{\mathsf{Tr}(\mathsf{Z}(\Phi, \pi_o))} = \operatorname{Tr}(\mathsf{Z}(\Phi, \mathsf{Ind}_{\mathsf{N}_{\mathcal{J}_1}}^{\mathsf{GL}_n(\mathbb{F}_q)}(\theta_{\psi}))) = \underbrace{\sum_{\substack{\gamma \in \{\mathsf{N}_{\mathcal{J}_1}\} \\ \gamma \in \{\mathsf{N}_{\mathcal{J}_1}\}}} \chi_{\theta_{\psi}}(\gamma) a_{\mathsf{N}_{\mathcal{J}_1}}^{\mathsf{GL}_n(\mathbb{F}_q)}(\gamma) \mathsf{O}(\gamma, \Phi)}_{\mathsf{N}_{\mathcal{J}_1}}$$

where

- $\{N_{\mathcal{J}_1}\} = a$  set consisting of all representatives for the conjugacy classes in  $N_{\mathcal{J}_1}$ ;
- $-\mathsf{N}_{\mathcal{J}_{1\gamma}} = \{\delta \in \mathsf{N}_{\mathcal{J}_{1}} \mid \delta^{-1}\gamma\delta = \gamma\} \text{ for } \gamma \in \{\mathsf{N}_{\mathcal{J}_{1}}\};$
- $-\operatorname{GL}_{n}(\mathbb{F}_{q})_{\gamma} = \{g \in \operatorname{GL}_{n}(\mathbb{F}_{q}) \mid g^{-1}\gamma g = \gamma\} \text{ for } \gamma \in \{\mathsf{N}_{\mathcal{J}_{1}}\}.$

Furthermore, for  $\gamma \in \{N_{\mathcal{J}_1}\}$ ,

$$a_{\mathsf{N}_{\mathcal{J}_{1}}}^{\mathsf{GL}_{n}(\mathbb{F}_{q})}(\gamma) = \frac{|\mathsf{GL}_{n}(\mathbb{F}_{q})_{\gamma}|}{|\mathsf{N}_{\mathcal{J}_{1\gamma}}|}$$

and the orbital integral  $O(\gamma, \Phi)$  of  $\Phi : M_n(\mathbb{F}_q) \to \mathbb{C}$  over the conjugacy class  $C_{\gamma}^{\operatorname{GL}_n(\mathbb{F}_q)}$  of  $\gamma$  in  $\operatorname{GL}_n(\mathbb{F}_q)$  is given by

$$O(\gamma, \Phi) = \sum_{t \in \mathcal{R}_{\operatorname{GL}_n(\mathbb{F}_q)\gamma \setminus \operatorname{GL}_n(\mathbb{F}_q)}} \Phi(t^{-1}\gamma t).$$

#### 7.3. $\epsilon$ -factors of representations of $GL_n(\mathbb{F}_q)$

Let  $\psi : \mathbb{F}_q^+ \to \mathbb{C}^{\times}$  be a non-trivial additive character of  $\mathbb{F}_q$ . For  $x \in \mathsf{M}_n(\mathbb{F}_q)$ , let  $_x\mu : \mathsf{M}_n(\mathbb{F}_q) \to \mathsf{M}_n(\mathbb{F}_q)$  be the additive homomorphism defined by  $_x\mu : y \mapsto xy$  for all  $y \in \mathsf{M}_n(\mathbb{F}_q)$ . For  $x \in \mathsf{M}_n(\mathbb{F}_q)$ , we consider the Fourier transform

$$\mathcal{F}_{\mathsf{r}_x} : \mathbb{C}[\mathsf{M}_n(\mathbb{F}_q)] \to \mathsf{End}_{\mathbb{C}}(V_{\mathsf{r}_x})$$

on  $\mathsf{M}_n(\mathbb{F}_q)$  coupled to the representation  $\mathsf{r}_x : \mathsf{M}_n(\mathbb{F}_q) \xrightarrow{x\mu} \mathsf{M}_n(\mathbb{F}_q) \xrightarrow{\mathsf{Tr}} \mathbb{F}_q \xrightarrow{\psi} \mathbb{C}^{\times}$  of the additive group  $\mathsf{M}_n(\mathbb{F}_q)$  on the 1-dimensional vector space  $V_{\mathsf{r}_x} = \mathbb{C}$  over  $\mathbb{C}$  defined by

$$\mathcal{F}_{\mathsf{r}_x}: \Phi \mapsto \mathcal{F}_{\mathsf{r}_x} \Phi =: \widehat{\Phi}(\mathsf{r}_x) =: \widehat{\Phi}(x) \stackrel{\text{def}}{=} |\mathsf{M}_n(\mathbb{F}_q)|^{-\frac{1}{2}} \sum_{g \in \mathsf{M}_n(\mathbb{F}_q)} \Phi(g) \mathsf{r}_x(g) = \mathsf{r}_x(\Phi), \quad \forall \Phi \in \mathbb{C}[\mathsf{M}_n(\mathbb{F}_q)].$$

Let  $\pi : \operatorname{GL}_n(\mathbb{F}_q) \to \operatorname{GL}(V_\pi)$  be a representation of  $\operatorname{GL}_n(\mathbb{F}_q)$  on a *d*-dimensional vector space  $V_\pi$  over  $\mathbb{C}$ . For each  $\Phi \in \mathbb{C}[\mathsf{M}_n(\mathbb{F}_q)]$ , by Macdonald (Macdonald 1980, eq. (2.3)),

$$\mathsf{Z}(\Phi,\pi) = \sum_{g \in \mathsf{GL}_n(\mathbb{F}_q)} \Phi(g)\pi(g) = \sum_{x \in \mathsf{M}_n(\mathbb{F}_q)} \widehat{\Phi}(-x)W(\pi,\psi;x),$$

where

$$W(\pi,\psi;x) = |\mathsf{M}_n(\mathbb{F}_q)|^{-\frac{1}{2}} \sum_{h \in \mathsf{GL}_n(\mathbb{F}_q)} \psi(\mathsf{Tr}(hx))\pi(h), \quad \forall x \in \mathsf{M}_n(\mathbb{F}_q).$$
(11)

Now choosing x = 1 for  $x \in M_n(\mathbb{F}_q)$ , Macdonald proved (Macdonald 1980, eq. (2.4)) that

$$W(\pi,\psi;1)\pi(g) = \pi(g)W(\pi,\psi;1), \quad \forall g \in \mathsf{GL}_n(\mathbb{F}_q).$$

Therefore, there exists a constant  $(\pi, \psi) \in \mathbb{C}$  such that

$$W(\pi, \psi; 1) = (\pi, \psi)\pi(1).$$

The epsilon factor  $\epsilon(\pi, \psi)$  of the representation  $\pi : \operatorname{GL}_n(\mathbb{F}_q) \to \operatorname{GL}(V_\pi)$  of  $\operatorname{GL}_n(\mathbb{F}_q)$  on the *d*-dimensional vector space  $V_\pi$  over  $\mathbb{C}$  with respect to the choice of a non-trivial additive character  $\psi : \mathbb{F}_q^+ \to \mathbb{C}^\times$  is defined by

$$\epsilon(\pi,\psi) := (\check{\pi},\psi),$$

where  $\check{\pi} : \operatorname{GL}_n(\mathbb{F}_q) \to \operatorname{GL}(V_{\check{\pi}})$  denotes the contragradient of  $\pi : \operatorname{GL}_n(\mathbb{F}_q) \to \operatorname{GL}(V_{\pi})$ ; that is, the representation of  $\operatorname{GL}_n(\mathbb{F}_q)$  on the dual space  $V_{\check{\pi}}$  of  $V_{\pi}$  defined by  $\check{\pi}(g) = {}^t \pi(g^{-1})$ .

Thus, it follows from (11) that

$$W(\check{\pi},\psi;1) = |\mathsf{M}_n(\mathbb{F}_q)|^{-\frac{1}{2}} \sum_{h \in \mathsf{GL}_n(\mathbb{F}_q)} \psi(\mathsf{Tr}(h))\check{\pi}(h) = \epsilon(\pi,\psi)\check{\pi}(1).$$

Therefore,

$$\mathsf{Tr}(W(\check{\pi},\psi;1)) = |\mathsf{M}_n(\mathbb{F}_q)|^{-\frac{1}{2}} \sum_{h \in \mathsf{GL}_n(\mathbb{F}_q)} \psi(\mathsf{Tr}(h))\mathsf{Tr}(\check{\pi}(h)) = \epsilon(\pi,\psi)\mathsf{Tr}(\check{\pi}(1)),$$

proving that

$$\epsilon(\pi,\psi) = \frac{|\mathsf{M}_n(\mathbb{F}_q)|^{-\frac{1}{2}}}{\dim(\pi)} \sum_{h \in \mathsf{GL}_n(\mathbb{F}_q)} \psi(\mathsf{Tr}(h))\chi_{\check{\pi}}(h), \tag{12}$$

as  $\operatorname{Tr}(\check{\pi}(1)) = \dim(\pi)$ .

Moreover, Ye and Zelingher studied the effect of the linear algebraic operations  $\boxplus$  and  $\boxtimes$  on  $\Pi(GL_*(\mathbb{F}_q)) = \bigsqcup_{\substack{0 \le n \in \mathbb{Z} \\ 0 \le n \in \mathbb{Z}}} \Pi(GL_n(\mathbb{F}_q))$ to  $\epsilon$ -factors in Ye and Zelingher (2021). More precisely, for  $\pi_1 \in \Pi(GL_{n_1}(\mathbb{F}_q))$  and  $\pi_2 \in \Pi(GL_{n_2}(\mathbb{F}_q))$ , there exist  $\pi_1 \boxplus \pi_2 \in \Pi(GL_{n_1+n_2}(\mathbb{F}_q))$  and  $\pi_1 \boxtimes \pi_2 \in \Pi(GL_{n_1n_2}(\mathbb{F}_q))$ , whose  $\epsilon$ -factor, and  $\zeta$ - and *L*-factors are known instead of

 $\pi_1 \boxplus \pi_2$  and  $\pi_1 \boxtimes \pi_2$  themselves, and it is proved Ye and Zelingher (2021) by Ye and Zelingher that

$$\epsilon(\pi_1 \boxplus \pi_2, \psi) = \epsilon(\pi_1, \psi) \epsilon(\pi_2, \psi). \tag{13}$$

Now, combining (13) with the identity (12), for  $\pi_1 \in \Pi(\operatorname{GL}_{n_1}(\mathbb{F}_q))$  and  $\pi_2 \in \Pi(\operatorname{GL}_{n_2}(\mathbb{F}_q))$ , we have

$$\epsilon(\pi_{1} \boxplus \pi_{2}, \psi) = \frac{|\mathsf{M}_{n_{1}}(\mathbb{F}_{q})|^{-\frac{1}{2}}}{\dim(\pi_{1})} \sum_{h' \in \mathsf{GL}_{n_{1}}(\mathbb{F}_{q})} \psi(\mathsf{Tr}(h'))\chi_{\check{\pi}_{1}}(h') \frac{|\mathsf{M}_{n_{2}}(\mathbb{F}_{q})|^{-\frac{1}{2}}}{\dim(\pi_{2})} \sum_{h'' \in \mathsf{GL}_{n_{2}}(\mathbb{F}_{q})} \psi(\mathsf{Tr}(h''))\chi_{\check{\pi}_{2}}(h'')$$

$$= \frac{|\mathsf{M}_{n_{1}}(\mathbb{F}_{q}) \times \mathsf{M}_{n_{1}}(\mathbb{F}_{q})|^{-\frac{1}{2}}}{\dim(\pi_{1})\dim(\pi_{2})} \sum_{\substack{h' \in \mathsf{GL}_{n_{1}}(\mathbb{F}_{q})\\h'' \in \mathsf{GL}_{n_{2}}(\mathbb{F}_{q})}} \psi\left(\mathsf{Tr}\left[ \begin{matrix} h' & 0\\ 0 & h'' \end{matrix} \right] \right)\chi_{\check{\pi}_{1}\oplus\check{\pi}_{2}}\left( \begin{bmatrix} h' & 0\\ 0 & h'' \end{bmatrix} \right).$$
(14)

In case the representation  $\pi : \operatorname{GL}_n(\mathbb{F}_q) \to \operatorname{GL}(V_\pi)$  has no 1-component; that is,  $\pi$  is not a constituent of  $\rho_{n-1} \circ (1)$ , where  $\rho_{n-1}$  is the regular representation of  $\operatorname{GL}_{n-1}(\mathbb{F}_q)$  over  $\mathbb{C}$  and (1) is the trivial representation  $\operatorname{GL}_1(\mathbb{F}_q) \to \mathbb{C}^{\times}$ , Macdonald further proved (Macdonald 1980, Proposition 2.7) that

$${}^{t}\mathsf{Z}(\widehat{\Phi},\check{\pi}) = \epsilon(\pi,\psi)\mathsf{Z}(\Phi,\pi),\tag{15}$$

where  ${}^{t}Z(\widehat{\Phi}, \check{\pi})$  is the transpose of  $Z(\widehat{\Phi}, \check{\pi})$ . Applying Theorem 5.1, the trace formula for finite groups in Arthur form, to the identity (15), the following identities follow immediately.

**Theorem 7.3.** Let  $\rho : \mathsf{P}_{\mathcal{J}} \to \mathrm{GL}(V_{\rho})$  be a representation of the standard parabolic subgroup  $\mathsf{P}_{\mathcal{J}}$  of  $\mathrm{GL}_n(\mathbb{F}_q)$  with respect to the partition  $\mathcal{J}$  on the vector space  $V_{\rho}$  over  $\mathbb{C}$ . Assume that the representation

 $\mathsf{Ind}_{\mathsf{P}_{\mathcal{J}}}^{\mathrm{GL}_{n}(\mathbb{F}_{q})}(\rho): \mathsf{GL}_{n}(\mathbb{F}_{q}) \to \mathsf{GL}(\mathsf{Ind}_{\mathsf{P}_{\mathcal{J}}}^{\mathrm{GL}_{n}(\mathbb{F}_{q})}(V_{\rho}))$ 

of  $\operatorname{GL}_n(\mathbb{F}_q)$  on the induced  $\mathbb{C}$ -linear space  $\operatorname{Ind}_{\mathsf{P}_{\mathcal{J}}}^{\operatorname{GL}_n(\mathbb{F}_q)}(V_\rho)$  has no 1-component. The epsilon factor  $\epsilon(\operatorname{Ind}_{\mathsf{P}_{\mathcal{J}}}^{\operatorname{GL}_n(\mathbb{F}_q)}(\rho), \psi)$ of the representation  $\operatorname{Ind}_{\mathsf{P}_{\mathcal{J}}}^{\operatorname{GL}_n(\mathbb{F}_q)}(\rho) : \operatorname{GL}_n(\mathbb{F}_q) \to \operatorname{GL}(\operatorname{Ind}_{\mathsf{P}_{\mathcal{J}}}^{\operatorname{GL}_n(\mathbb{F}_q)}(V_\rho))$  with respect to the choice of a non-trivial additive character  $\psi : \mathbb{F}_q^+ \to \mathbb{C}^{\times}$  has then the following description:

$$\frac{\sum_{\substack{\pi_{o} \in [\pi] \in \Pi(\operatorname{GL}_{n}(\mathbb{F}_{q})) \\ \pi_{o} \in [\pi] \in \Pi(\operatorname{GL}_{n}(\mathbb{F}_{q}))}}{\sum_{\pi_{o} \in [\pi] \in \Pi(\operatorname{GL}_{n}(\mathbb{F}_{q}))}} m(\pi_{o}, \operatorname{Ind}_{\mathsf{P}_{\mathcal{J}}}^{\operatorname{GL}_{n}(\mathbb{F}_{q})}(\rho))\operatorname{Tr}(\mathsf{Z}(\Phi, \pi_{o}))} = \epsilon(\operatorname{Ind}_{\mathsf{P}_{\mathcal{J}}}^{\operatorname{GL}_{n}(\mathbb{F}_{q})}(\rho), \psi) = \frac{\sum_{\gamma \in \{\mathsf{P}_{\mathcal{J}}\}} \chi_{\check{\rho}}(\gamma) a_{\mathsf{P}_{\mathcal{J}}}^{\operatorname{GL}_{n}(\mathbb{F}_{q})}(\gamma) O(\gamma, \widehat{\Phi})}{\sum_{\gamma \in \{\mathsf{P}_{\mathcal{J}}\}} \chi_{\rho}(\gamma) a_{\mathsf{P}_{\mathcal{J}}}^{\operatorname{GL}_{n}(\mathbb{F}_{q})}(\gamma) O(\gamma, \Phi)},$$

where

$$- \{P_{\mathcal{J}}\} = a \text{ set consisting of all representatives for the conjugacy classes in } P_{\mathcal{J}};$$

$$- \mathsf{P}_{\mathcal{J}_{\gamma}} = \{\delta \in \mathsf{P}_{\mathcal{J}} \mid \delta^{-1}\gamma\delta = \gamma\} \text{ for } \gamma \in \{\mathsf{P}_{\mathcal{J}}\}$$

 $-\operatorname{GL}_{n}(\mathbb{F}_{q})_{\gamma} = \{g \in \operatorname{GL}_{n}(\mathbb{F}_{q}) \mid g^{-1}\gamma g = \gamma\} \text{ for } \gamma \in \{\mathsf{P}_{\mathcal{J}}\}.$ 

*Furthermore, for*  $\gamma \in \{\mathsf{P}_{\mathcal{J}}\}$ *,* 

$$a_{\mathsf{P}_{\mathcal{J}}}^{\operatorname{GL}_{n}(\mathbb{F}_{q})}(\gamma) = \frac{|\operatorname{GL}_{n}(\mathbb{F}_{q})_{\gamma}|}{|\mathsf{P}_{\mathcal{J}_{\gamma}}|},$$

and the orbital integral  $O(\gamma, \Phi)$  of  $\Phi : M_n(\mathbb{F}_q) \to \mathbb{C}$  over the conjugacy class  $C_{\gamma}^{\operatorname{GL}_n(\mathbb{F}_q)}$  of  $\gamma$  in  $\operatorname{GL}_n(\mathbb{F}_q)$  is given by

$$\mathcal{O}(\gamma, \Phi) = \sum_{t \in \mathcal{R}_{\mathrm{GL}_n(\mathbb{F}_q)_\gamma \setminus \mathrm{GL}_n(\mathbb{F}_q)} \Phi(t^{-1}\gamma t)$$

and the orbital integral  $O(\gamma, \widehat{\Phi})$  of  $\widehat{\Phi} : M_n(\mathbb{F}_q) \to \mathbb{C}$  over the conjugacy class  $C_{\gamma}^{\operatorname{GL}_n(\mathbb{F}_q)}$  of  $\gamma$  in  $\operatorname{GL}_n(\mathbb{F}_q)$  is given by

$$O(\gamma, \widehat{\Phi}) = \sum_{t \in \mathcal{R}_{\mathrm{GL}_n(\mathbb{F}_q)\gamma \setminus \mathrm{GL}_n(\mathbb{F}_q)}} \widehat{\Phi}(t^{-1}\gamma t)$$

The identities given by Theorem 7.3 do not seem to appear in the literature and may have applications in the  $\epsilon$ -factor analysis of representations of  $GL_n(\mathbb{F}_q)$  over  $\mathbb{C}$ .

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**RESEARCH ARTICLE** 

## **Backward Shift Operators on Bergman-Besov Spaces as Bergman Projections**

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#### ABSTRACT

We express backward shift operators on all Bergman-Besov spaces in terms of Bergman projections in one and several variables including the Banach function spaces and the special Hilbert spaces such as Drury-Arveson and Dirichlet spaces. These operators are adjoints of the shift operators and their definitions for the case p = 1 and proper Besov spaces require the use of nontrivial imbeddings of the spaces into Lebesgue classes. Our results indicate that the backward shifts are compositions of imbeddings into Lebesgue classes followed by multiplication operators by the conjugates of the coordinate variables followed by Bergman projections on appropriate spaces. We apply our results to the wandering subspace property of invariant subspaces of the shift operators on certain of our Hilbert spaces.

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#### **1. INTRODUCTION**

Shift operators and their adjoints the backward shift operators have a central position in operator theory. Forward shift operators on holomorphic function spaces have simple representations as operators of multiplication by the coordinate variables. This is true also for the adjoint of the shift operator  $f(z) \mapsto zf(z)$  on the Hardy space  $H^2$  on the unit disc. This operator is the backward shift operator with the explicit formula

$$f(z) \mapsto \frac{f(z) - f(0)}{z} \qquad (z \in \mathbb{D}, \ f \in H^2).$$

$$\tag{1}$$

Backward shift operators on other holomorphic function spaces such as the weighted Bergman spaces can be written in terms of the Taylor series of the functions in the spaces, but simple explicit expressions in the spirit of (1) have been lacking until recently.

In Gu and Luo (2024), for weighted Bergman Hilbert spaces  $A_n^2$  on the unit disc with nonnegative integer weight parameter n, explicit expressions akin to (1) have been obtained. In the same paper, another formula on the same spaces have been obtained using the Bergman projections again with integer parameters.

It turns out that, by judicious use of dual representations, it is possible to extend the Bergman projection formulas considerably. We obtain expressions for the backward shift operators on weighted Bergman and Bergman-Besov spaces  $B_a^p$  on the unit disc and the ball using Bergman projections. The spaces on which our formulas work include weighted Bergman spaces with non-integer weight parameter q > -1, Besov spaces which correspond to parameter values  $q \le -1$ , Banach Bergman-Besov with parameters  $1 \le p < \infty$ , the same spaces of holomorphic functions of several complex variables on the unit ball of  $\mathbb{C}^N$ , and in particular the Drury-Arveson and Dirichlet spaces.

To place our results in context, we introduce some notation. Let  $\mathbb{B}$  be the unit ball in  $\mathbb{C}^N$  with respect to the norm  $|z| = \sqrt{\langle z, z \rangle}$ induced by the usual Hermitian inner product  $\langle w, z \rangle = w_1 \overline{z}_1 + \dots + w_N \overline{z}_N$ , which is the unit disc  $\mathbb{D}$  for N = 1. Let  $H(\mathbb{B})$  denote the space of all holomorphic functions on  $\mathbb{B}$ , respectively.

We let v be the Lebesgue measure on  $\mathbb{B}$  normalized so that  $v(\mathbb{B}) = 1$ . For  $q \in \mathbb{R}$ , we also define on  $\mathbb{B}$  the measures

$$d\nu_q(z) := (1 - |z|^2)^q \, d\nu(z).$$

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These measures are finite for q > -1 and  $\sigma$ -finite otherwise. For  $0 , we denote the Lebesgue classes with respect to <math>v_q$  by  $L_q^p$ , writing also  $L^p = L_0^p$ .

The standard weighted Bergman spaces on  $\mathbb{B}$  are  $A_q^p = L_q^p \cap H(\mathbb{B})$  for q > -1 normed by  $||f||_{A_q^p} := ||f||_{L_q^p}$ . Equivalently, the Bergman space  $A_q^p$  is imbedded isometrically in  $L_q^p$  by the *inclusion map i*. We again write  $A^p = A_0^p$  for the unweighted Bergman spaces.

Bergman spaces are generalized to two-parameter Besov spaces  $B_q^p$  for  $q \le -1$ . We defer the precise definition of Besov spaces to a later section; see Definition 2.1. It suffices now to note that the Besov space  $B_q^p$  is imbedded isometrically in the Lebesgue space  $L_q^p$  with the same parameters p, q by a map that is a combination of a derivative of the function and the product of a power of  $1 - |z|^2$ , where the order of the derivative and the power are the same. It is also true that an  $f \in H(\mathbb{B})$  belongs to  $B_q^p$  whenever sufficiently high-order derivatives of f lie in a Bergman space.

We use the notation  $B_q^p$  for the full collection of Bergman-Besov spaces for  $q \in \mathbb{R}$ . For all  $q \in \mathbb{R}$  and  $1 \le p < \infty$ , Bergman-Besov projections  $P_s$  exist from the Lebesgue class  $L_q^p$  onto the Bergman-Besov space  $B_q^p$  for *s* satisfying a certain well-known inequality; see Theorem 3.1.

The *shift operator S* on a holomorphic function space on the unit disc  $\mathbb{D}$  is simply the operator of multiplication by the coordinate variable *z*; so S(f)(z) = zf(z). When the space on which *S* acts matters, we attach the parameters of the space to *S* and write  $S_q^p : B_q^p \to B_q^p$ .

For function spaces on the unit ball  $\mathbb{B}$ , we have N coordinate variables  $z_1, \ldots, z_N$  and hence N shift operators; so  $S_j(f)(z) = z_j f(z)$  for  $j = 1, \ldots, N$ . But we can also indicate the spaces on which the shifts act and write  $(S_q^p)_j : B_q^p \to B_q^p$ .

The adjoints  $(S_q^p)^*$  and  $(S_q^p)_j^*$  of the shift operators on  $B_q^p$  act on the dual spaces  $(B_q^p)^*$  and are called the *backward shift* operators. For  $1 , we have <math>(B_q^p)^* = B_q^{p'}$ , where p' is the exponent conjugate to p, that is, p' = p/(p-1). For p = 1, the corresponding dual spaces are the weighted Bloch spaces  $\mathcal{B}_{\alpha}^{\infty}$ , whose definitions are also deferred to a later section; see Definition 2.2. For the dual spaces, see Theorem 3.3.

The main purpose of this paper is to establish expressions for the backward shift operators on  $A_q^p$  and  $B_q^p$  in terms of Bergman projections. We use the fact that the adjoint of a shift operator on a complex Lebesgue space is merely the operator of multiplication by the *conjugate* of the coordinate variable used in the shift operator. Our formulas have the following form: We take a function in  $B_q^p$  and imbed it in the associated Lebesgue space  $L_q^p$  as explained above, then we multiply the imbedded function by the conjugate of the corresponding coordinate variable, and lastly we project back to the Bergman or Besov space by a suitable Bergman projection.

Our main results in this direction are Theorems 4.2, 4.4, 6.2, and 6.4. They and their proofs occupy Sections 4 and 6. In Sections 2 and 3 following, we summarize all relevant information on the spaces we work on and the projections used in the theorems. In Section 5, we show that the invariant subspaces of the backward shifts in certain Besov spaces on the disc have the wandering subspace property.

#### 2. PRELIMINARIES

In this section, we give the remaining notation and the necessary details on the function spaces. We use multi-index notation in which  $\alpha = (\alpha_1, \ldots, \alpha_N)$  is an *N*-tuple of nonnegative integers,  $|\alpha| = \alpha_1 + \cdots + \alpha_N$ ,  $\alpha! = \alpha_1! \cdots \alpha_N!$ ,  $0^0 = 1$ , and  $z^{\alpha} = z_1^{\alpha_1} \cdots z_N^{\alpha_N}$  for  $z \in \mathbb{C}^n$ . A star ()\* indicates adjoints for operators and duals for spaces. We show an integral inner product on a function space *X* by  $[\cdot, \cdot]_X$ .

The Pochhammer symbol  $(a)_b$  is defined by

$$(a)_b := \frac{\Gamma(a+b)}{\Gamma(a)}$$

when *a* and *a*+*b* are off the pole set  $-\mathbb{N}$  of the gamma function  $\Gamma$ . This is a shifted rising factorial since  $(a)_k = a(a+1)\cdots(a+k-1)$  for positive integer *k*. In particular,  $(1)_k = k!$  and  $(a)_0 = 1$ . A very useful identity is

$$(a)_{n+m} = (a)_n (a+n)_m$$
(2)

for  $n, m \in \mathbb{N}$ . Stirling formula gives

$$\frac{\Gamma(c+a)}{\Gamma(c+b)} \sim c^{a-b}, \qquad \frac{(a)_c}{(b)_c} \sim c^{a-b}, \qquad \frac{(c)_a}{(c)_b} \sim c^{a-b} \qquad (\text{Re } c \to \infty), \tag{3}$$

where  $A \sim B$  means that |A/B| is bounded above and below by two strictly positive constants, that is, A = O(B) and B = O(A) for all A, B of interest. For A = O(B), we also write  $A \leq B$ .

For  $q \in \mathbb{R}$  and  $w, z \in \mathbb{B}$ , the *Bergman-Besov kernels* are

$$K_{q}(z,w) := \begin{cases} \frac{1}{(1-\langle z,w\rangle)^{1+N+q}} = \sum_{k=0}^{\infty} \frac{(1+N+q)_{k}}{k!} \langle z,w\rangle^{k}, & q > -(1+N) \\ {}_{2}F_{1}(1,1;1-(N+q);\langle z,w\rangle) = \sum_{k=0}^{\infty} \frac{k! \langle z,w\rangle^{k}}{(1-(N+q))_{k}}, & q \leq -(1+N) \end{cases}$$

where  ${}_2F_1 \in H(\mathbb{D})$  is the Gauss hypergeometric function. They are the reproducing kernels of Hilbert Bergman-Besov spaces. Notice that

$$K_{-(1+N)}(z,w) = \frac{1}{\langle z,w\rangle} \log \frac{1}{1-\langle z,w\rangle}.$$

These kernels are positive definite and sesquiholomorphic, and hence give rise to reproducing kernel Hilbert spaces of holomorphic functions which are the Bergman-Besov Hilbert spaces  $B_q^2$ . In particular, for q > -1, the  $B_q^2$  are weighted Bergman spaces  $A_q^2$ ,  $B_{-1}^2$  is the Hardy space  $H^2$ ,  $B_{-N}^2$  is the Drury-Arveson space, and  $B_{-(1+N)}^2$  is the Dirichlet space. When N = 1, the Hardy and the Drury-Arveson spaces coincide.

To define the Bergman-Besov spaces for  $p \neq 2$ , we proceed as follows. Let the coefficient of  $(z, w)^k$  in the series expansion of  $K_q(z, w)$  be  $c_k(q)$  for any  $q \in \mathbb{R}$ . Note that  $c_0(q) = 1$ ,  $c_k(q) > 0$  for any k, and by (3),

$$c_k(q) \sim k^{N+q} \qquad (k \to \infty),\tag{4}$$

for every q. This explains the choice of the parameters of the hypergeometric function in  $K_q$ .

Let  $f \in H(\mathbb{B})$  be given on  $\mathbb{B}$  by its convergent *homogeneous expansion*  $f = \sum_{k=0}^{\infty} f_k$  in which  $f_k$  is a homogeneous polynomial in  $z_1, \ldots, z_N$  of degree k. For N = 1,  $f_k$  is simply the kth term in the Taylor series of  $f \in H(\mathbb{D})$ . For any  $s, t \in \mathbb{R}$ , we define the *radial fractional differential operator*  $D_s^t$  on  $H(\mathbb{B})$  by

$$D_{s}^{t}f := \sum_{k=0}^{\infty} d_{k}(s,t)f_{k} := \sum_{k=0}^{\infty} \frac{c_{k}(s+t)}{c_{k}(s)}f_{k}.$$
(5)

Note that  $d_0(s,t) = 1$  so that  $D_s^t(1) = 1$ ,  $d_k(s,t) > 0$  for any k, and

$$d_k(s,t) \sim k^t \qquad (k \to \infty),$$

for any *s*, *t* by (4). So  $D_s^t$  is a continuous operator on  $H(\mathbb{B})$  and is of order *t*. In particular,  $D_s^t z^{\gamma} = d_{|\gamma|}(s,t)z^{\gamma}$  for any multi-index  $\gamma$ . More importantly,

$$D_s^0 = I$$
,  $D_{s+t}^u D_s^t = D_s^{t+u}$ , and  $(D_s^t)^{-1} = D_{s+t}^{-t}$ 

for any s, t, u, where the inverse is two-sided. Thus any  $D_s^t$  maps  $H(\mathbb{B})$  onto itself. The coefficients  $d_k(s, t)$  are chosen in such a way that

$$D_a^t K_q(z, w) = K_{q+t}(z, w) \tag{6}$$

for any  $q, t \in \mathbb{R}$ , where differentiation is performed in the holomorphic variable z.

Consider now the linear transformation  $I_s^t$  defined for  $f \in H(\mathbb{B})$  by

$$I_{s}^{t}f(z) := (1 - |z|^{2})^{t} D_{s}^{t}f(z).$$

When t = 0, s is irrelevant and  $I_s^0$  is just the inclusion i.

**Definition 2.1.** For  $q \in \mathbb{R}$  and 0 , we define the*Bergman-Besov space* $<math>B_q^p$  to consist of all  $f \in H(\mathbb{B})$  for which  $I_s^t f$  belongs to  $L_q^p$  for some s, t satisfying

$$q + pt > -1. \tag{7}$$

It is well-known that under (7), Definition 2.1 is independent of *s*, *t* and the norms  $||f||_{B_q^p} := ||I_s^t f||_{L_q^p}$  are all equivalent. For p = 2, these norms are also equivalent to the norms obtained from the reproducing kernels. Explicitly,

$$\|f\|_{B^p_q}^p = \int_{\mathbb{B}} |D^t_s f(z)|^p (1-|z|^2)^{q+pt} \, d\nu(z) \qquad (q+pt>-1).$$
(8)

When q > -1, we can take t = 0 in (7) and obtain the weighted Bergman spaces  $A_q^p = B_q^p$ . When  $q \le -1$ , we call the spaces  $B_q^p$  proper Besov spaces. For 0 , what we call norms are actually quasinorms.

The Lebesgue class of all essentially bounded functions on  $\mathbb{B}$  with respect to any  $\nu_q$  is the same, so we denote them all by  $\mathcal{L}^{\infty}$ .

For  $\alpha \in \mathbb{R}$ , we also define the weighted Lebesgue spaces  $\mathcal{L}^{\infty}_{\alpha}$  to consist of all measurable  $\varphi$  defined on  $\mathbb{B}$  for which  $(1 - |z|^2)^{\alpha} \varphi(z)$  belongs to  $\mathcal{L}^{\infty}$  normed by

$$\|\varphi\|_{\mathcal{L}^{\infty}_{\alpha}} := \operatorname{ess\,sup}_{z \in \mathbb{B}} (1 - |z|^2)^{\alpha} |\varphi(z)|.$$

**Definition 2.2.** For  $\alpha \in \mathbb{R}$ , we define the *Bloch-Lipschitz space*  $\mathcal{B}^{\infty}_{\alpha}$  to consist of all  $f \in H(\mathbb{B})$  for which  $I_s^t f$  belongs to  $\mathcal{L}^{\infty}_{\alpha}$  for some *s*, *t* satisfying

$$\alpha + t > 0. \tag{9}$$

It is well-known that under (9), Definition 2.2 is independent of s, t and the norms  $||f||_{\mathcal{B}^{\infty}_{\alpha}} := ||I_s^t f||_{\mathcal{L}^{\infty}_{\alpha}}$  are all equivalent. Explicitly,

$$\|f\|_{\mathcal{B}^{\infty}_{\alpha}} = \sup_{z \in \mathbb{B}} |D_{s}^{t}f(z)| (1-|z|^{2})^{\alpha+t} \qquad (\alpha+t>0).$$
(10)

If  $\alpha > 0$ , we can take t = 0 in (9) and obtain the weighted Bloch spaces. When  $\alpha < 0$ , these spaces are the holomorphic Lipschitz spaces  $\Lambda_{-\alpha} = \mathcal{B}^{\infty}_{\alpha}$ . The *usual Bloch space*  $\mathcal{B}^{\infty}_{0} = \mathcal{B}^{\infty}$  corresponds to  $\alpha = 0$ . There is no mention of the little Bloch space in this paper.

**Remark 2.3.** Definitions 2.1 and 2.2 imply that  $I_s^t$  imbeds  $B_q^p$  isometrically into  $L_q^p$  if and only if (7) holds, and  $I_s^t$  imbeds  $\mathcal{B}_{\alpha}^{\infty}$  isometrically into  $\mathcal{L}_{\alpha}^{\infty}$  if and only if (9) holds. By (8) and (10),  $f \in B_q^p$  if and only if  $D_s^t f \in A^p$  for q + pt = 0, and  $f \in \mathcal{B}_{\alpha}^{\infty}$  if and only if  $D_s^t f \in \mathcal{B}^{\infty}$  for  $\alpha + t = 0$ .

The reproducing property in the  $B_q^2$  is this: Given a  $q \in \mathbb{R}$ , there are  $t, s_1, s_2 \in \mathbb{R}$  such that for any  $f \in B_q^2$  and  $z \in \mathbb{B}$ , we have

$$f(z) = [f(\cdot), K_q(z, \cdot)]_{B_q^2} = C_q \int_{\mathbb{B}} D_{s_1}^t f(w) D_{s_2}^t K_q(z, w) (1 - |w|^2)^{q+2t} dv(w),$$

where  $[\cdot, \cdot]$  are the inner products associated to the norms in (8) and the  $C_q$  are normalizing constants. For Bergman spaces, q > -1 and naturally t = 0.

**Proposition 2.4.** (*Kaptanoğlu and Üreyen 2008, Proposition 3.1*) (*Kaptanoğlu and Tülü 2011, Proposition 2.1*) For any p > 0and  $q, \alpha, s, t \in \mathbb{R}$ , the maps  $D_s^t : B_q^p \to B_{q+pt}^p$  and  $D_s^t : \mathcal{B}_{\alpha}^{\infty} \to \mathcal{B}_{\alpha+t}^{\infty}$  are Banach space isomorphisms. They are also isometries when the parameters of the imbeddings I in the norms of the spaces are chosen as s, u for the domain and as s + t, u - t for the target space.

#### 3. BERGMAN-BESOV PROJECTIONS

Bergman-Besov projections are the linear transformations  $P_s$  defined for  $s \in \mathbb{R}$  and suitable  $\varphi$  by

$$P_s\varphi(z) = \int_{\mathbb{B}} \varphi(w) K_s(z, w) \, d\nu_s(w) \qquad (z \in \mathbb{B}).$$

**Theorem 3.1.** (*Kaptanoğlu 2005*, *Theorem 1.2*)(*Kaptanoğlu and Tülü 2011*, *Theorem 1.3*) For  $1 \le p < \infty$ , the map  $P_s : L_q^p \to B_q^p$  is bounded if and only if

$$q+1 < p(s+1).$$
 (11)

Given an s satisfying (11), if t satisfies (7), then

$$P_s I_s^t f = \frac{N!}{(1+s+t)_N} f \tag{12}$$

holds for  $f \in B^p_q$ . Further,  $P_s : \mathcal{L}^{\infty}_{\alpha} \to \mathcal{B}^{\infty}_{\alpha}$  is bounded if and only if

$$\alpha < s+1. \tag{13}$$

Given an s satisfying (13), if t satisfies (9), then (12) holds for  $f \in \mathcal{B}_{\alpha}^{\infty}$ .

**Remark 3.2.** Note that 1 + s + t > 0 if either (7) and (11), or (9) and (13) hold, thus in all cases considered in Theorem 3.1.

The *dual* of a Banach (or Hilbert) space is the space of all bounded linear functionals on the space. For  $1 , the dual of <math>L_q^p$  is  $L_q^{p'}$  under the pairing  $[\cdot, \cdot]_q$ , where

$$\left[\varphi,\psi\right]_{q} \coloneqq \int_{\mathbb{B}} \varphi \,\overline{\psi} \,d\nu_{q}. \tag{14}$$

The dual of any  $L^1_q$  can be realized as any one of  $\mathcal{L}^{\infty}_{\alpha}$  under the pairing  $[\cdot, \cdot]_{q+\alpha}$ .

**Theorem 3.3.** (*Kaptanoğlu 2005, Remark 7.3*) (*Kaptanoğlu and Tülü 2011, Theorem 6.2*) For  $1 , the dual space of <math>B_q^p$  can be identified with  $B_q^{p'}$  under each of the pairings

$$\left[f, g\right]_{q,s,t} \coloneqq \int_{\mathbb{B}} I_s^t f \,\overline{I_{q+t}^{-q+s}g} \, d\nu_q \tag{15}$$

for s,t satisfying (11) and (7), that is, for every bounded linear functional  $\Phi$  on  $B_q^p$ , there is a unique  $g \in B_q^{p'}$  such that  $\Phi f = [f,g]_{q,s,t}$  for  $f \in B_q^p$ . The dual space of any  $B_q^1$  can be identified with any  $\mathcal{B}_{\alpha}^{\infty}$  under each of the pairings  $[f,g]_{q+\alpha,s,t}$  for s,t satisfying (11) and (7) with p = 1, that is, for every bounded linear functional  $\Phi$  on  $B_q^1$ , there is a unique  $g \in \mathcal{B}_{\alpha}^{\infty}$  such that  $\Phi f = [f,g]_{q+\alpha,s,t}$  for  $f \in B_q^1$ .

Equation (15) takes simpler forms for Bergman spaces for which q > -1 and we can take t = 0. For 1 , we can also take <math>s = q, but for p = 1, we must have s > q. Then the pairings are

$$\int_{\mathbb{B}} f \,\overline{g} \, d\nu_q \quad \text{and} \quad \int_{\mathbb{B}} f \,\overline{I_{q+\alpha}^{-q-\alpha+s}g} \, d\nu_{q+\alpha} \tag{16}$$

for 1 and <math>p = 1, respectively.

So we have two pairings (14) and (15) with one and three parameters to use without and with an  $I_s^t$ , respectively.

Most useful is the Banach space adjoint of  $I_s^t : B_q^p \to L_q^p$  for  $1 \le p < \infty$  under the conditions (7) and (11). We use Theorem 3.3. For  $1 , the adjoint is the operator <math>(I_s^t)^* : L_q^{p'} \to B_q^{p'}$  such that  $[I_s^t f, \psi]_q = [f, (I_s^t)^* \psi]_{q,s,t}$  for  $f \in B_q^p$  and  $\psi \in L_q^{p'}$ , where *s* satisfies (11). For p = 1, it is the operator  $(I_s^t)^* : \mathcal{L}_{\alpha}^{\infty} \to \mathcal{B}_{\alpha}^{\infty}$  such that  $[I_s^t f, \psi]_{q+\alpha} = [f, (I_s^t)^* \psi]_{q+\alpha,s,t}$  for  $f \in B_q^1$  and  $\psi \in \mathcal{L}_{\alpha}^{\infty}$ .

**Theorem 3.4.** Let  $q \in \mathbb{R}$ . For  $1 , we have <math>(I_s^t)^* = \frac{(1+s+t)_N}{N!} P_{q+t}$ , and for p = 1, we have  $(I_s^t)^* = \frac{(1+s+t)_N}{N!} P_{q+\alpha+t}$  for any  $\alpha \in \mathbb{R}$ , where s, t satisfy (11) and (7). Explicitly, for  $f \in B_q^p$  and  $\psi \in (L_q^p)^*$ ,

$$\int_{\mathbb{B}} I_s^t f \,\overline{\psi} \, d\nu_{q+\alpha} = \frac{(1+s+t)_N}{N!} \int_{\mathbb{B}} I_s^t f \,\overline{I_{q+\alpha+t}^{-q-\alpha+s} P_{q+\alpha+t} \psi} \, d\nu_{q+\alpha}$$

where  $\alpha = 0$  for  $1 and <math>\alpha \in \mathbb{R}$  is arbitrary for p = 1.

This theorem says that the composition of an *I*-type operator following a *P*-type operator can be removed under certain integrals.

**Proof.** We give the proof only for 1 ; the proof for <math>p = 1 follows the same lines and is omitted.

Let  $f \in B_q^p$ ,  $\psi \in L_q^p$ , and put  $F = D_s^t f$ . By Proposition 2.4,  $F \in B_{q+pt}^p$ ; but since q + pt > -1, actually  $F \in A_{q+pt}^p$ , a Bergman space which can be described without using any derivative. We have q + pt + 1 < p(s + t + 1), so by Theorem 3.1,  $P_{s+t}$  maps  $A_{q+pt}^p$  onto itself and  $P_{s+t}F = \frac{N!}{(1 + s + t)_N}F$ . We compute by first writing the integrals explicitly, next differentiating under the integral sign using (6), then interchanging the order of integration by the Fubini theorem, and finally using the information about F just stated. We obtain

$$\begin{split} \left[f, \ P_{q+t}\psi\right]_{q,s,t} &= \int_{\mathbb{B}} (1-|z|^2)^t D_s^t f(z) \ \overline{(1-|z|^2)^{-q+s}} \\ &\quad \overline{D_{q+t}^{-q+s}} \int_{\mathbb{B}} \psi(w) K_{q+t}(z,w) (1-|w|^2)^{q+t} \ dv(w) \ (1-|z|^2)^q \ dv(z) \\ &= \int_{\mathbb{B}} (1-|z|^2)^{s+t} F(z) \int_{\mathbb{B}} \overline{\psi(w)} K_{s+t}(z,w) \ (1-|w|^2)^{q+t} \ dv(w) \ dv(z) \\ &= \int_{\mathbb{B}} (1-|w|^2)^{q+t} \ \overline{\psi(w)} \int_{\mathbb{B}} F(z) K_{s+t}(w,z) (1-|z|^2)^{s+t} \ dv(z) \ dv(w) \\ &= \int_{\mathbb{B}} (1-|w|^2)^{q+t} \ \overline{\psi(w)} \ P_{s+t} F(w) \ dv(w) \\ &= \int_{\mathbb{B}} (1-|w|^2)^t \ \frac{N!}{(1+s+t)_N} F(w) \ \overline{\psi(w)} \ dv_q(w) \\ &= \int_{\mathbb{B}} \frac{N!}{(1+s+t)_N} I_s^t f(w) \ \overline{\psi(w)} \ dv_q(w) = \left[ \frac{N!}{(1+s+t)_N} \ I_s^t f, \psi \right]_q. \end{split}$$

The proof is complete.

Theorem 3.4 takes simpler forms for Bergman spaces for which q > -1 and we can take t = 0. For 1 , we can further take <math>s = q and then  $i^* = \frac{(1+q)_N}{N!}P_q$ , where *i* is the inclusion from  $A_q^p$  into  $L_q^p$ . For p = 1, we must have q < s, and then

 $i^* = \frac{(1+s)_N}{N!} P_q$  upon taking  $\alpha = 0$ . The simpler explicit forms for  $f \in A_q^p$  and  $\psi \in (L_q^p)^*$  for general  $\alpha$  are

$$\int_{\mathbb{B}} f \,\overline{\psi} \, d\nu_q = \frac{(1+q)_N}{N!} \int_{\mathbb{B}} f \,\overline{P_q \psi} \, d\nu_q \qquad (1$$

$$\int_{\mathbb{B}} f \,\overline{\psi} \,d\nu_{q+\alpha} = \frac{(1+s)_N}{N!} \int_{\mathbb{B}} f \,\overline{I_{q+\alpha}^{-q-\alpha+s}} P_{q+\alpha} \psi \,d\nu_{q+\alpha} \qquad (p=1).$$
(18)

We need the following results when we compute the backward shifts explicitly on specific Bergman-Besov spaces. First, using multi-index notation,

$$\langle z, w \rangle^k = \sum_{|\gamma|=k} \frac{k!}{\gamma!} z^{\gamma} \overline{w}^{\gamma}.$$
<sup>(19)</sup>

**Lemma 3.5.** Let  $\alpha$ ,  $\beta$  be two multi-indices,  $|\alpha| = n$ , and s > -1. Then

$$\int_{\mathbb{B}} z^{\alpha} \overline{z}^{\beta} (1-|z|^2)^s \, d\nu(z) = \begin{cases} 0, & \text{if } \beta \neq \alpha, \\ \frac{N! \, \alpha!}{(1+s)_{N+n}}, & \text{if } \beta = \alpha. \end{cases}$$

*Proof.* This is (Alpay and Kaptanoğlu 2001, Lemma 1).

**Lemma 3.6.** Let  $\alpha, \beta$  be two multi-indices,  $n = |\alpha|, m = |\beta|$ , and  $r, s \in \mathbb{R}$  with r + s > -1. Let  $J = P_s(z^{\alpha}\overline{z}^{\beta}(1 - |z|^2)^r)$ . Then

$$J = \begin{cases} \frac{N! (1+N+s)_{n-m}}{(1+r+s)_{N+n}} \frac{\alpha!}{(\alpha-\beta)!} z^{\alpha-\beta}, & \text{if } s > -(1+N), \\ \frac{N! ((n-m)!)^2}{(1-(N+s))_{n-m} (1+r+s)_{N+n}} \frac{\alpha!}{(\alpha-\beta)!} z^{\alpha-\beta}, & \text{if } s \le -(1+N), \end{cases}$$

for  $\alpha \ge \beta$ , and J = 0 otherwise, where  $\alpha \ge \beta$  means  $\alpha_j \ge \beta_j$  for all j = 1, ..., N.

**Proof.** In what follows, by Lemma 3.5, the only value of  $\gamma$  that gives a nonzero integral is  $\gamma = \alpha - \beta \ge 0$ , which also explains why the integral is 0 for  $\alpha < \beta$ .

For s > -(1 + N), by the way Bergman-Besov projections and kernels are defined, (19), and Lemma 3.5,

$$J = \int_{\mathbb{B}} w^{\alpha} \overline{w}^{\beta} (1 - |w|^2)^{r+s} \sum_{k=0}^{\infty} \frac{(1 + N + s)_k}{k!} \sum_{|\gamma|=k} \frac{k!}{\gamma!} z^{\gamma} \overline{w}^{\gamma} d\nu(w)$$
$$= \frac{(1 + N + s)_{n-m}}{(\alpha - \beta)!} z^{\alpha - \beta} \int_{\mathbb{B}} |w^{\alpha}|^2 (1 - |w|^2)^{r+s} d\nu(w)$$
$$= \frac{(1 + N + s)_{n-m}}{(\alpha - \beta)!} z^{\alpha - \beta} \frac{N! \alpha!}{(1 + r + s)_{N+n}}.$$

For  $s \leq -(1 + N)$ , similarly,

$$\begin{split} J &= \int_{\mathbb{B}} w^{\alpha} \overline{w}^{\beta} (1 - |w|^2)^{r+s} \sum_{k=0}^{\infty} \frac{k!}{(1 - (N+s))_k} \sum_{|\gamma|=k} \frac{k!}{\gamma!} z^{\gamma} \overline{w}^{\gamma} \, d\nu(w) \\ &= \frac{((n-m)!)^2}{(1 - (N+s))_{n-m}} \frac{1}{(\alpha - \beta)!} z^{\alpha - \beta} \int_{\mathbb{B}} |w^{\alpha}|^2 (1 - |w|^2)^{r+s} \, d\nu(w) \\ &= \frac{((n-m)!)^2}{(1 - (N+s))_{n-m}} \frac{1}{(\alpha - \beta)!} z^{\alpha - \beta} \frac{N! \, \alpha!}{(1 + r + s)_{N+n}}. \end{split}$$

We use Lemma 3.6 only for m = 1.

#### 4. BACKWARD SHIFT OPERATORS ON SPACES ON UNIT DISC

The spaces we work on have infinite families of equivalent norms. The pairings under which the dual spaces are realized depend strongly on the particular norms used. Likewise, the adjoint operators take different forms depending on the pairings. For this reason, for each type of space, we define the adjoints anew.

Throughout this section, N = 1. When (7) and (11) both hold, always s + t > -1.

**Definition 4.1.** For q > -1, let  $S_q^p : A_q^p \to A_q^p$  be the shift operator acting on a Bergman space. If  $1 , we define its adjoint <math>(S_q^p)^* : A_q^{p'} \to A_q^{p'}$  by  $[S_q^p f, g]_q = [f, (S_q^p)^* g]_q$ , where  $f \in A_q^p$  and  $g \in A_q^{p'}$ . If p = 1, we define its adjoint  $(S_q^1)^* : \mathcal{B}_{\alpha}^{\infty} \to \mathcal{B}_{\alpha}^{\infty}$  by  $[S_q^1 f, g]_{q+\alpha} = [f, (S_q^1)^* g]_{q+\alpha,s,0}$ , where  $f \in A_q^1$  and  $g \in \mathcal{B}_{\alpha}^{\infty}$ .

Theorem 4.2. The adjoint of a Bergman shift operator is

$$(S_q^p)^*g(z) = (1+s)P_{q+\alpha}(\overline{z}g(z)) = (1+s)\int_{\mathbb{D}} \frac{\overline{w}\,g(w)}{(1-\overline{w}z)^{2+q+\alpha}}\,d\nu_{q+\alpha}(w).$$

where  $g \in A_q^{p'}$ ,  $\alpha = 0$ , and s = q for  $1 , and <math>g \in \mathcal{B}_{\alpha}^{\infty}$ ,  $\alpha \in \mathbb{R}$ , and s satisfies (11) for p = 1. **Proof.** Let  $1 and <math>g \in A_q^{p'}$  first. Definition 4.1 and (17) give

$$\begin{split} \left[S_q^p f, g\right]_q &= \int_{\mathbb{D}} z f(z) \,\overline{g(z)} \, d\nu_q(z) = \int_{\mathbb{D}} f(z) \,\overline{\overline{z}g(z)} \, d\nu_q(z) \\ &= (1+q) \int_{\mathbb{D}} f(z) \,\overline{P_q(\overline{z}g(z))} \, d\nu_q(z) = \left[f, \, (1+q)P_q(\overline{z}g(z))\right]_q \end{split}$$

Then

$$(S^p_q)^*g(z) = (1+q)P_q\big(\overline{z}g(z)\big) \qquad (1$$

Let p = 1 and  $g \in \mathcal{B}^{\infty}_{\alpha}$  next. Definition 4.1 and (18) give

$$\begin{split} \left[S_q^1 f, g\right]_{q+\alpha} &= \int_{\mathbb{D}} zf(z) \,\overline{g(z)} \, d\nu_{q+\alpha}(z) = \int_{\mathbb{D}} f(z) \,\overline{\overline{z}g(z)} \, d\nu_{q+\alpha}(z) \\ &= (1+s) \int_{\mathbb{D}} f(z) \, \overline{I_{q+\alpha}^{-q-\alpha+s} P_{q+\alpha}(\overline{z}g(z))} \, d\nu_{q+\alpha}(z) \\ &= \left[f, \, (1+s) P_{q+\alpha}(\overline{z}g(z))\right]_{q+\alpha,s,0}. \end{split}$$

Thus  $(S_a^1)^* g(z) = (1+s)P_{q+\alpha}(\overline{z}g(z)).$ 

We keep  $\alpha$  when p = 1 for flexibility. But if we choose  $\alpha = 0$ , then the only difference between the two cases in Theorem 4.2 is whether the coefficient is 1 + q or 1 + s with s > q.

**Definition 4.3.** Let  $q \leq -1$  and t, s satisfy (7) and (11). Also let s > -2 for convenience. Let  $S_q^p : B_q^p \to B_q^p$  be the shift operator acting on a proper Besov space. If  $1 , we define its adjoint <math>(S_q^p)^* : B_q^{p'} \to B_q^{p'}$  by the identity  $[S_q^p f, g]_{q,s,t} = [f, (S_q^p)^* g]_{q,s+1,t}$ , where  $f \in B_q^p$  and  $g \in B_q^{p'}$ . If p = 1, we define its adjoint  $(S_q^1)^* : \mathcal{B}_{\alpha}^{\infty} \to \mathcal{B}_{\alpha}^{\infty}$  by  $\left[S_q^1 f, g\right]_{q+\alpha,s,t}^{q+\alpha,s,t} = \left[f, (S_q^1)^* g\right]_{q+\alpha,s+1,t}^{q+\alpha,s+1,t}$ , where  $f \in B_q^1$  and  $g \in \mathcal{B}_{\alpha}^{\infty}$ .

Theorem 4.4. The adjoint of a proper Besov shift operator is

$$(S_q^p)^*g(z) = \frac{(2+s+t)^2}{2+s} P_{q+\alpha+t} \big( \overline{z} I_{q+\alpha+t}^{-q-\alpha+s} g(z) \big),$$

where  $g \in B_q^{p'}$  and  $\alpha = 0$  for  $1 , <math>g \in \mathcal{B}_{\alpha}^{\infty}$  and  $\alpha \in \mathbb{R}$  for p = 1, t, s satisfy (7) and (11), and s > -2 for convenience.

The explicit integral expression for  $P_{q+\alpha+t}$  depends on whether  $q + \alpha + t > -2$  or  $q + \alpha + t \le -2$ .

**Proof.** Let  $f \in B_q^p$  be given by its Taylor series  $f(z) = \sum_{k=0}^{\infty} f_k z^k$ . Since s > -2 and s + t > -1 > -2, by (5) we have

$$D_s^t(zf(z)) = \sum_{k=0}^{\infty} \frac{(2+s+t)_{k+1}}{(2+s)_{k+1}} f_k z^{k+1} = \frac{2+s+t}{2+s} z \sum_{k=0}^{\infty} \frac{(2+s+1+t)_k}{(2+s+1)_k} f_k z^k = \frac{2+s+t}{2+s} z D_{s+1}^t f(z)$$

and hence  $I_s^t(zf(z)) = \frac{2+s+t}{2+s} z I_{s+1}^t f(z)$ . Let  $1 and <math>g \in B_q^{p'}$  first. Definition 4.3, the previous calculation, and Theorem 3.4 give

$$\begin{split} \left[ S_q^p f, g \right]_{q,s,t} &= \int_{\mathbb{D}} I_s^t(zf(z)) \, \overline{I_{q+t}^{-q+s} g(z)} \, d\nu_q(z) \\ &= \int_{\mathbb{D}} I_{s+1}^t f(z) \, \overline{\frac{2+s+t}{2+s}} \, \overline{z} I_{q+t}^{-q+s} g(z) \, d\nu_q(z) \\ &= (2+s+t) \int_{\mathbb{D}} I_{s+1}^t f(z) \, \overline{\frac{2+s+t}{2+s}} \, I_{q+t}^{-q+s+1} P_{q+t} \big( \overline{z} I_{q+t}^{-q+s} g(z) \big) \, d\nu_q(z) \\ &= \left[ f(z), \, \frac{(2+s+t)^2}{2+s} P_{q+t} \big( \overline{z} I_{q+t}^{-q+s} g(z) \big) \right]_{q,s+1,t}. \end{split}$$

The desired formula is obtained.

Let p = 1 and  $g \in \mathcal{B}^{\infty}_{\alpha}$  next. Similar to the previous case, Definition 4.3, the above calculation, and Theorem 3.4 give

$$\begin{split} \left[ S_{q}^{p}f, g \right]_{q+\alpha,s,t} &= \int_{\mathbb{D}} I_{s}^{t}(zf(z)) \,\overline{I_{q+\alpha+t}^{-q-\alpha+s}g(z)} \, d\nu_{q+\alpha}(z) \\ &= \int_{\mathbb{D}} I_{s+1}^{t}f(z) \, \overline{\frac{2+s+t}{2+s}} \, \overline{z} I_{q+\alpha+t}^{-q-\alpha+s}g(z) \, d\nu_{q+\alpha}(z) \\ &= \int_{\mathbb{D}} I_{s+1}^{t}f(z) \, \overline{\frac{(2+s+t)^{2}}{2+s}} \, I_{q+\alpha+t}^{-q-\alpha+s+1} P_{q+\alpha+t} \big( \overline{z} I_{q+\alpha+t}^{-q-\alpha+s}g(z) \big) \, d\nu_{q+\alpha}(z) \\ &= \left[ f(z), \, \frac{(2+s+t)^{2}}{2+s} P_{q+\alpha+t} \big( \overline{z} I_{q+\alpha+t}^{-q-\alpha+s}g(z) \big) \right]_{q+\alpha,s+1,t}. \end{split}$$

The desired formula follows.

We check some well-known Hilbert spaces to see the differences between our formulas and the more commonly known ones. Such differences are bound to happen since we base our formulas on integral inner products while many formulas in the literature are based on the norms derived from reproducing kernels. Since all the spaces involved consist of holomorphic functions on  $\mathbb{D}$ , it is enough to check the results on  $g(z) = z^n$  for n = 0, 1, 2, ...

**Remark 4.5.** Let q > -1 and consider first the Bergman Hilbert spaces  $A_q^2$ . Here there must be no difference in the literature among the backward shift operators since the reproducing kernels of Bergman spaces are derived from standard integral norms. Theorem 4.2 and Lemma 3.6 give

$$(S_q^2)^*(z^n) = (1+q)P_q(z^n\overline{z}) = (1+q)\frac{(2+q)_{n-1}}{(1+q)_{1+n}}nz^{n-1} = \frac{n}{1+q+n}z^{n-1},$$

which agrees with (Kaptanoğlu 2014, (26)), as expected.

**Remark 4.6.** For the proper Besov spaces  $B_q^2$  with  $q \le -1$ , there are two possibilities, q + t > -2 or  $q + t \le -2$ . In the first possibility (q + t > -2), we have  $D_{q+t}^{-q+s}(z^n) = \frac{(2 + s + t)_n}{(2 + q + t)_n} z^n$  by (5). Then Theorem 4.4 and Lemma 3.6 give

$$(S_q^2)^*(z^n) = \frac{(2+s+t)^2}{2+s} \frac{(2+s+t)_n}{(2+q+t)_n} P_{q+t} (\overline{z}(1-|z|^2)^{-q+s} z^n)$$
  
=  $\frac{(2+s+t)^2}{2+s} \frac{(2+s+t)_n}{(2+q+t)_n} \frac{(2+q+t)_{n-1}}{(1+s+t)_{1+n}} n z^{n-1}$   
=  $\frac{(2+s+t)^2}{2+s} \frac{1}{1+s+t} \frac{n}{1+q+t+n} z^{n-1}.$ 

Let  $s \to \infty$  since it can be as large as we wish; then essentially

$$(S_q^2)^*(z^n) = \frac{n}{1+q+t+n} z^{n-1}.$$
(20)

For q = -1, we have  $B_{-1}^2 = H^2$  for which essentially  $(S_{-1}^2)^*(z^n) = \frac{n}{t+n} z^{n-1}$ . For  $H^2$ , any small t > 0 works. If we further let  $t \to 0^+$ , we obtain  $(S_{-1}^2)^*(z^n) \to z^{n-1}$ , which is what (1) says.

**Remark 4.7.** In the second possibility  $(q+t \le -2)$  when  $q \le -1$ , by (5) again, we have  $D_{q+t}^{-q+s}(z^n) = \frac{(2+s+t)_n}{n!} \frac{(-(q+t))_n}{n!} z^n$ . Then Theorem 4.4 and Lemma 3.6 give

$$(S_q^2)^*(z^n) = \frac{(2+s+t)^2}{2+s} \frac{(2+s+t)_n}{n!} \frac{(-(q+t))_n}{n!} P_{q+t}(\overline{z}(1-|z|^2)^{-q+s}z^n)$$
  
=  $\frac{(2+s+t)^2}{2+s} \frac{(2+s+t)_n}{n!} \frac{(-(q+t))_n}{n!} \frac{(n-1)!}{(-(q+t))_{n-1}} \frac{n!}{(1+s+t)_{1+n}} z^{n-1}$   
=  $\frac{(2+s+t)^2}{2+s} \frac{1}{1+s+t} \frac{-(1+q+t)+n}{n} z^{n-1}.$ 

As  $s \to \infty$  again, essentially

$$(S_q^2)^*(z^n) = \frac{-(1+q+t)+n}{n} z^{n-1}.$$
(21)

For q = -2,  $B_{-2}^2$  is the Dirichlet space for which  $(S_{-2}^2)^*(z^n) = \frac{1-t+n}{n} z^{n-1}$  essentially. For this space, we must have t > 1/2. In

spite of this, if we further let  $t \to 0^+$ , we obtain  $(S_{-2}^2)^*(z^n) \to \frac{1+n}{n} z^{n-1}$ , which is what (Kaptanoğlu 2014, (26)) says, contrary to intuition.

#### 5. WANDERING SUBSPACE PROPERTY

In this section, we identify some shift operators acting on Bergman-Besov Hilbert spaces  $B_q^2$  whose invariant subspaces have the wandering subspace property.

Let *T* be a left-invertible operator on a Hilbert space *H* and let  $E \subset H$  be a closed *T*-invariant subspace of *H*. We say *E* has the *wandering subspace property* if *E* is the smallest closed *T*-invariant subspace including  $E \ominus TE$ , where  $\ominus$  indicates orthogonal complement, that is, if  $E = \bigvee_{i=0}^{\infty} T^n(E \ominus TE)$ , where  $\lor$  indicates closed linear span.

In (Richter 1988, Theorem 1 and Corollary), it is shown that the invariant subspaces of the shift operator on the Besov Hilbert spaces  $B_q^2$  with  $-2 \le q \le -1$ , that is, on those spaces between the Hardy Hilbert and Dirichlet spaces, have the wandering subspace property. In (Aleman et al. 1996, Theorem 3.5), it is shown that the invariant subspaces of the shift operator on the unweighted Bergman Hilbert space has the wandering subspace property. It should be noted that all results of this form are norm (or inner product) dependent since the adjoint depends on it, except perhaps those on Bergman spaces in whose norms there is universal agreement. In fact, in Gallardo-Gutiérrez et al. (2020) it is shown that by renorming, one can force the wandering subspace property.

In (Shimorin 2001, Theorem 4.1), a very practical sufficient condition is given for the wandering subspace property in which  $A \le B$  means B - A is a positive operator.

**Theorem 5.1.** (Shimorin (2001)) If S is the shift operator on a space of holomorphic functions on  $\mathbb{D}$  and  $SS^* + (S^*S)^{-1} \leq 2I$ , then the invariant subspaces of S have the wandering subspace property.

Checking the hypothesis of this theorem is especially easy since both  $S_q^2(S_q^2)^*$  and  $(S_q^2)^*S_q^2$  are diagonal operators on the orthogonal basis  $\{1, z, z^2 \dots\}$  for all  $B_q^2$ . We also see that renorming does have an effect.

**Theorem 5.2.** For  $-1 < q \le 0$ , the shift operator  $S_q^2$  on the Bergman space  $A_q^2$  has the wandering subspace property.

**Proof.** By Remark 4.5, we have  $S_q^2(S_q^2)^*(z^n) = \frac{n}{1+q+n}z^n$  for  $n \ge 1$ ,  $S_q^2(S_q^2)^*(1) = 0$ ,  $(S_q^2)^*S_q^2(z^n) = \frac{1+n}{2+q+n}z^n$ , and  $((S_q^2)^*S_q^2)^{-1}(z^n) = \frac{2+q+n}{1+n}z^n$ . Applying Theorem 5.1,  $S_q^2(S_q^2)^* + (S_q^2)^*S_q^2 \le 2I$  if and only if

$$\frac{2+q}{1} \le 2$$
 and  $\frac{n}{1+q+n} + \frac{2+q+n}{1+n} \le 2.$ 

The first inequality gives  $q \le 0$  and the second  $q \ge -1$ .

**Theorem 5.3.** For  $q \le -1$ , the shift operator  $S_q^2$  on the Besov space  $B_q^2$  using the adjoints from (Kaptanoğlu 2014, (26)) has the wandering subspace property if q = -1, that is, for the Hardy space  $H^2$  with the usual norm and adjoint.

**Proof.** For  $-2 < q \le -1$ ,  $(S_q^2)^*(z^n) = \frac{n}{1+q+n} z^{n-1}$ , which is identical to the adjoints in Theorem 5.2. So we have only q = -1 from the proof of that theorem.

from the proof of that theorem. For  $q \le -2$ ,  $(S_q^2)^*(z^n) = \frac{-1-q+n}{n} z^{n-1}$ . Then  $S_q^2(S_q^2)^*(z^n) = \frac{-1-q+n}{n} z^n$  and  $((S_q^2)^*S_q^2)^{-1}(z^n) = \frac{1+n}{-q+n} z^n$ . Hence  $S_q^2(S_q^2)^* + (S_q^2)^*S_q^2 \le 2I$  if and only if

$$\frac{1}{-q} \le 2$$
 and  $\frac{-1-q+n}{n} + \frac{1+n}{-q+n} \le 2$ 

The first inequality gives  $q \le -1/2$  and the second  $q \ge -1$ . Thus there is no  $q \le -2$  with desired properties.

**Theorem 5.4.** For  $q \le -1$ , the shift operator  $S_q^2$  on the Besov space  $B_q^2$  using the adjoints in Theorem 4.4 has the wandering subspace property if t is chosen to obtain  $-1 \le q + t \le 0$ .

Note that it is compulsory to have q + 2t > -1 by (7).

**Proof.** To make the formulas amenable to computation, we use the adjoints in Remarks 4.6 and 4.7 in their limiting form as  $s \rightarrow \infty$ .

For 
$$q + t > -2$$
, by using (20) we have  $(S_q^2)^*(z^n) = \frac{n}{1+q+t+n} z^{n-1}$ . Then also  $S_q^2(S_q^2)^*(z^n) = \frac{n}{1+q+t+n} z^n$  and

$$((S_q^2)^*S_q^2)^{-1}(z^n) = \frac{2+q+t+n}{1+n} z^n. \text{ Hence } S_q^2(S_q^2)^* + (S_q^2)^*S_q^2 \le 2I \text{ if and only if}$$
$$\frac{2+q+t}{1} \le 2 \qquad \text{and} \qquad \frac{n}{1+q+t+n} + \frac{2+q+t+n}{1+n} \le 2.$$

The first inequality gives  $q + t \le 0$  and the second  $q + t \ge -1$ . Thus for  $q \le -1$ , if we choose t with  $-1 \le q + t \le 0$ , then  $S_q^2$  on  $B_q^2$  has the wandering subspace property.

For  $q + t \le -2$ , by using (21) we have  $(S_q^2)^*(z^n) = \frac{-1 - q - t + n}{n} z^{n-1}$ . Then also  $S_q^2(S_q^2)^*(z^n) = \frac{-1 - q - t + n}{n} z^n$  and  $((S_q^2)^*S_q^2)^{-1}(z^n) = \frac{1 + n}{-q - t + n} z^n$ . Hence  $S_q^2(S_q^2)^* + (S_q^2)^*S_q^2 \le 2I$  if and only if

$$\frac{1}{-q-t} \le 2$$
 and  $\frac{-1-q-t+n}{n} + \frac{1+n}{-q-t+n} \le 2.$ 

The first inequality gives  $q + t \ge 1/2$  and the second  $q + t \ge -1$ , which contradict  $q + t \le -2$ . So no q and t can be found with the desired properties in this case.

Some other shift operators are checked in Gu and Luo (2024).

#### 6. BACKWARD SHIFT OPERATORS ON SPACES ON UNIT BALL

Shift operators  $S_j$ , j = 1, ..., N, on holomorphic function spaces on the unit ball  $\mathbb{B}$  in  $\mathbb{C}^N$  are investigated from many perspectives in Kaptanoğlu (2014). Here we concentrate only on their adjoints represented as Bergman-Besov projections. For readability, we refrain from attaching the parameters q, p of the spaces to the shift operators since they are clear from the context. We also take  $\alpha = 0$  when p = 1 again for simplicity.

**Definition 6.1.** For q > -1, let  $S_j : A_q^p \to A_q^p$  be a shift operators acting on a Bergman space, j = 1, ..., N. If  $1 , we define its adjoint <math>S_j^* : A_q^{p'} \to A_q^{p'}$  by  $[S_j f, g]_q = [f, S_j^* g]_q$ , where  $f \in A_q^p$  and  $g \in A_q^{p'}$ . If p = 1, we define its adjoint  $S_j^* : \mathcal{B}^{\infty} \to \mathcal{B}^{\infty}$  by  $[S_j f, g]_q = [f, S_j^* g]_{q,s,0}$ , where  $f \in A_q^p$  and  $g \in \mathcal{B}^{\infty}$ .

**Theorem 6.2.** For j = 1, ..., N, the adjoint of the Bergman shift operator  $S_j$  is

$$S_{j}^{*}g(z) = \frac{(1+s)_{N}}{N!} P_{q}(\overline{z}_{j}g(z)) = \frac{(1+s)_{N}}{N!} \int_{\mathbb{B}} \frac{\overline{w}_{j}g(w)}{(1-\langle z,w \rangle)^{1+N+q}} \, dv_{q}(w),$$

where  $g \in A_q^{p'}$  and s = q for  $1 , and <math>g \in \mathcal{B}^{\infty}$  and s > q for p = 1.

**Proof.** The proof is very similar to that of Theorem 4.2 and we omit it. The only thing that requires attention is that now we work in  $\mathbb{C}^N$  with N > 1. The same are true for the proof of Theorem 6.4 below.

**Definition 6.3.** Let  $q \leq -1$  and t, s satisfy (7) and (11). Also let s > -(1 + N) for convenience. Let  $S_j : B_q^p \to B_q^p$  be a shift operator acting on a proper Besov space, j = 1, ..., N. If  $1 , we define its adjoint <math>S_j^* : B_q^{p'} \to B_q^{p'}$  by the identity  $[S_j f, g]_{q,s,t} = [f, S_j^* g]_{q,s+1,t}$ , where  $f \in B_q^p$  and  $g \in B_q^{p'}$ . If p = 1, we define its adjoint  $S_j^* : \mathcal{B}^\infty \to \mathcal{B}^\infty$  by the same identity, where  $f \in B_q^1$  and  $g \in \mathcal{B}^\infty$ .

**Theorem 6.4.** For j = 1, ..., N, the adjoint of the proper Besov shift operator  $S_j$  is

$$S_{j}^{*}g(z) = \frac{1+N+s+t}{1+N+s} \frac{(2+s+t)_{N}}{N!} P_{q+t}(\bar{z}_{j}I_{q+t}^{-q+s}g(z)),$$

where  $g \in B_q^{p'}$  for  $1 , <math>g \in \mathcal{B}^{\infty}$  for p = 1, t, s satisfy (7) and (11), and s > -(1 + N) for convenience.

The explicit integral expression for  $P_{q+t}$  depends on whether q + t > -(1 + N) or  $q + t \le -(1 + N)$ .

Let's evaluate the formulas in Theorems 6.2 and 6.4 on a monomial for all values of q and see their actual effects on certain standard reproducing kernel Hilbert spaces. In the Remarks below  $g(z) = z^{\alpha}$ ,  $n = |\alpha|$ ,  $\beta = e_j$ ,  $e_j = (0, ..., 0, 1, 0, ..., 0)$  with 1 in *j*th position, j = 1, ..., N, and  $|\beta| = m = 1$ . Note that  $\frac{\alpha!}{(\alpha - e_j)!} = \alpha_j$ .

**Remark 6.5.** Let q > -1 and consider the Bergman Hilbert spaces  $A_q^2$  on  $\mathbb{B}$ . Theorem 6.2, Lemma 3.6, and (2) give

$$S_j(z^{\alpha}) = \frac{(1+q)_N}{N!} P_q(\overline{z}_j z^{\alpha}) = \frac{(1+q)_N}{N!} \frac{N! (1+N+q)_{n-1}}{(1+q)_{N+n}} \frac{\alpha!}{(\alpha-e_j)!} z^{\alpha-e_j} = \frac{\alpha_j}{N+q+n} z^{\alpha-e_j},$$

which agrees with (Kaptanoğlu 2014, (26)).

**Remark 6.6.** For the proper Besov spaces  $B_q^2$  with  $q \le -1$ , when q + t > -2, we have  $D_{q+t}^{-q+s}(z^{\alpha}) = \frac{(1+N+s+t)_n}{(1+N+q+t)_n} z^{\alpha}$  by (5). Theorem 6.4, Lemma 3.6, and (2) give

$$\begin{split} (S_q^2)^*(z^{\alpha}) &= \frac{1\!+\!N\!+\!s\!+\!t}{1+N+s} \,\frac{(2+s+t)_N}{N!} \,\frac{(1+N+s+t)_n}{(1+N+q+t)_n} \,P_{q+t}\big(\bar{z}_j(1-|z|^2)^{-q+s}z^n\big) \\ &= \frac{1\!+\!N\!+\!s\!+\!t}{1+N+s} \,\frac{(2\!+\!s\!+\!t)_N}{N!} \,\frac{(1\!+\!N\!+\!s\!+\!t)_n}{(1\!+\!N\!+\!q\!+\!t)_n} \,\frac{N!\,(1\!+\!N\!+\!q\!+\!t)_{n-1}}{(1+s+t)_{N+n}} \,\alpha_j z^{\alpha-e_j} \\ &= \frac{(1+N+s+t)^2}{(1+N+s)(1+s+t)} \,\frac{\alpha_j}{N+q+t+n} \,z^{\alpha-e_j}. \end{split}$$

Let  $s \to \infty$  as before since it can be as large as we wish; then essentially

$$(S_q^2)^*(z^n) = \frac{\alpha_j}{N+q+t+n} \, z^{\alpha-e_j}$$

The cases q = -1 and q = -N pertain to the Hardy space  $H^2$  and the Drury-Arveson space. We must have q + 2t > 0 for this formula to make sense by Definition 6.3. But again contrary to intuition, if we let  $t \rightarrow 0+$ , we obtain the adjoint formulas in (Kaptanoğlu 2014, (26)) that are derived from the reproducing kernel norms.

**Remark 6.7.** For the proper Besov spaces  $B_q^2$  with  $q \le -1$ , when  $q + t \le -2$ , we have

$$D_{q+t}^{-q+s}(z^{\alpha}) = \frac{(1+N+s+t)_n}{n!} \frac{(1-(N+q+t))_n}{n!} z^{\alpha}$$

by (5). Theorem 6.4, Lemma 3.6, and (2) give

$$\begin{split} (S_q^2)^*(z^{\alpha}) &= \frac{1 + N + s + t}{1 + N + s} \frac{(2 + s + t)_N}{N!} \frac{(1 + N + s + t)_n}{n!} \frac{(1 - (N + q + t))_n}{n!} P_{q + t} (\overline{z}_j (1 - |z|^2)^{-q + s} z^n) \\ &= \frac{1 + N + s + t}{1 + N + s} \frac{(2 + s + t)_N}{N!} \frac{(1 + N + s + t)_n}{n!} \frac{(1 - (N + q + t))_n}{n!} \frac{N! (n - 1)! (n - 1)!}{(1 - (N + q + t))_{n - 1} (1 + s + t)_{N + n}} \alpha_j z^{\alpha - e_j} \\ &= \frac{(1 + N + s + t)^2}{(1 + N + s)(1 + s + t)} \frac{-(N + q + t) + n}{n^2} \alpha_j z^{\alpha - e_j}. \end{split}$$

Let  $s \to \infty$  again; then essentially

$$(S_q^2)^*(z^n) = \frac{-(N+q+t)+n}{n^2} \alpha_j z^{\alpha-e_j}.$$

The case q = -(1 + N) pertains to the Dirichlet space. We must have q + 2t > 0 for this formula to make sense by Definition 6.3. But again contrary to intuition, if we let  $t \to 0+$ , we obtain the adjoint formulas in (Kaptanoğlu 2014, (26)) that are derived from the reproducing kernel norms.

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**RESEARCH ARTICLE** 

# The *nX*-complementary generations of the group PSL(3,5)

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#### ABSTRACT

Let G be a finite non-abelian simple group and nX be a non-trivial conjugacy class of elements of order n in G. We say that G is *nX*-complementary generated, if for every  $x \in G$ , there exists an element  $y \in nX$  such that  $G = \langle x, y \rangle$ . In this paper we study the nX-complementary generations for all the non-trivial conjugacy classes of the projective special linear group PSL(3, 5). We approach this kind of generation using the structure constant method. GAP [The GAP Group, GAP - Groups, Algorithms, and Programming, Version 4.9.3; 2018. (http://www.gap-system.org)] is used frequently in our computations.

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#### 1. INTRODUCTION

The problem of generation of finite groups has great interest and has many applications to groups and their representations. The classification of finite simple groups is involved heavily and plays a pivotal role in most general results on the generation of finite groups. The study of generating sets in finite groups has a rich history, with numerous applications. We are interested in three kinds of generations of a finite simple group G, namely the (p, q, r)-generation, the nX-complementary generation and the ranks of the non-trivial conjugacy classes of G.

**Definition 1.1.** A finite group G is called (l, m, n)-generated, if it is a quotient group of the triangle group T(l, m, n) =  $\langle x, y, z | x^l = y^m = z^n = xyz = 1 \rangle$ .

In our work we generally restrict ourselves to the cases when l, m and n are primes and we use the notation (p, q, r)-generation rather than (l, m, n)-generation.

**Definition 1.2.** Let G be a finite simple group and nX be a non-trivial conjugacy class of elements of G. We define the rank of nX in G, denoted by rank(G:nX), to be the minimum number of elements in nX that generate G.

**Definition 1.3.** A finite group G is said to be *nX*-complementary generated, if for every  $x \in G$ , there exists an element  $y \in nX$ such that  $G = \langle x, y \rangle$ . The element y is called *complementary*.

In Woldar (1994), Woldar proved that every sporadic simple group G is pX-complementary generated where p is the largest prime dividing the order of G. In Ganief (1997), Ganief conjectured that every finite simple group is nX-complementary generated for some conjugacy class nX. In an attempt to further the theory on nX-complementary generation, he posed the problem: **Problem 1:** Given a finite non-abelian simple group G, find all conjugacy classes nX of G such that G is nX-complementary

generated. In Ganief (1997) Ganief gave a complete answer to Problem 1 for the following sporadic simple group: the Janko groups  $J_1$ ,

 $J_2$ ,  $J_3$ ,  $J_4$ ; the Higman-Sims group HS; the McLaughlin group McL; the Conway groups  $Co_3$ ,  $Co_2$  and the Fischer group  $Fi_{22}$ . The previous results have been published by Ganief and Moori in a series of papers Ganief and Moori (1997, 1998), Ganief and Moori (1998, 1999). Ashrafi in Ashrafi (2003, 2004) did the same for the sporadic groups He, Th, HN and O'N. Also Darafsheh, Ashrafi and Moghani established in Ashrafi et. al (2006); Darafsheh et. al. (2003, 2004), the nX-complementary generations for the sporadic groups  $Fi_{23}$ , Ru, Ly and  $Co_1$ .

With nX being a non-trivial conjugacy class of the group G = PSL(3, 5) as in the Atlas ATLAS (2024), the main result on the nX-complementary generation of the projective special linear group PSL(3,5) can be summarized in the following theorem.

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**Theorem 1.4.** The group G = PSL(3,5) is nX-complementary generated for all the conjugacy classes of G except when  $nX \in \{1A, 2A, 4A, 4B, 5A\}$ .

The proof of Theorem 1.4 will be done through sequence of propositions and corollaries that will be established in Section 3. The (p, q, r)-generations and the ranks of the conjugacy classes of the group PSL(3, 5) have been determined by the authors in Basheer and Seretlo (2019). We mainly used the structure constant method. In this paper we study the *nX*-complementary generation for the non-trivial conjugacy classes of the group PSL(3, 5). For the notation, description of the structure constant method and known results, we follow precisely Basheer and Seretlo (2019); Basheer et. al. (2019); Basheer et. al. (2024).

#### 2. THE PROJECTIVE SPECIAL LINEAR GROUP *PSL*(3,5)

The projective special linear group PSL(3, 5) is a simple group of order  $372000 = 2^5 \times 3 \times 5^3 \times 31$ . By the Atlas ATLAS (2024), the group PSL(3, 5) has exactly 30 conjugacy classes of its elements, of which 14 of these classes have elements of prime orders. These are the classes 2A, 3A, 5A, 5B, 31A, 31B, 31C, 31D, 31E, 31F, 31G, 31H, 31I and 31J. Also PSL(3, 5) has 5 conjugacy classes of these classes of maximal subgroups, where representatives of these classes of maximal subgroups can be taken as follows:

	$ H_i $	$[G:H_i]$
$H_1 = 5^2 : GL(5, 2)$	12000	31
$H_2 = 5^2 : GL(5, 2)$	12000	31
$H_3 = S_5$	120	3100
$H_4 = 4^2 : S_3$	96	3875
$H_5 = 31:3$	93	4000

**Table 1.**The maximal subgroups of G = PSL(3, 5)

Throughout this paper and unless otherwise stated, by G we always mean the projective special linear group PSL(3,5).

#### **3.** THE *NX*-COMPLEMENTARY GENERATIONS OF THE *PSL*(3, 5)

The following lemma is very crucial in the determination of which conjugacy classes nX of G are nX-complementary generated.

**Lemma 3.1.** A group G is nX-complementary generated if and only if for every conjugacy class pY of G, p prime, there exists a conjugacy class  $t_{pY}Z$ , depending on pY, such that the group G is  $(pY, nX, t_{pY}Z)$ -generated. Moreover; if G is a finite simple group, then G is not a 2X-complementary generated, for any conjugacy class of involutions.

Proof. See Lemma 2.3.8 of Ganief Ganief (1997).

**Remark 3.2.** Lemma 3.1 gives us a necessary and sufficient condition to determine whether a group *G* is *nX*-complementary generated or not. To check that the group *G* is *nX*-complementary generated, we need to check that *G* is  $(pY, nX, t_{pY}Z)$ -generated group for all the classes *pY*, where *p* is a prime number divides the order of *G*.

**Remark 3.3.** Recall that two involutions generate a dihedral group. Thus if *G* is a finite simple group and 2*X* is an involution class of *G*, then *G* is not a 2*X*-complementary generated. To see this, suppose that *G* is a 2*X*-complementary generated group. Then by Lemma 3.1, it follows that *G* is  $(2X, 2X, t_{2X}Z)$ -generated, which means that *G* is a dihedral group, contradicting the fact that *G* is a finite simple group. Therefore in the investigation on the classes of *G* whether they are *nX*-complementary generated or not we start by those classes where elements are of order at least 3.

The following result also helps a lot in determining whether G is an nX-complementary generated with the information that G is complementary generated by some conjugacy class sY and a power map of nX gives sY.

**Lemma 3.4.** If G is sY-complementary generated and  $(rX)^n = sY$ , then G is rX-complementary generated.

**Proof.** Let rX and sY be non-trivial conjugacy classes of G such that  $(rX)^n = sY$  for some positive integer n. Now assume that G is not rX-complementary generated group. It follows that there exits an element x of prime order such that  $\langle x, y \rangle < G$  for all  $y \in rX$ . Since  $x, y^n \in \langle x, y \rangle$ , it follows that  $\langle x, y^n \rangle \le \langle x, y \rangle < G$ , for all  $y^n \in sY$ . We conclude that if G is not rX-complementary generated, then it is also not sY-complementary generated. The contrapositive of this gives the result.

It is clear that the group G = PSL(3, 5) is neither 1A- nor 2A-complementary generated. In the next proposition we show that G is not 3A-complementary generated.

**Proposition 3.5.** *The group G is* 3*A-complementary generated.* 

**Proof.** By Propositions 3.1, 3.7, 3.11 and 3.12 of Basheer and Seretlo (2019), the group *G* is (2A, 3A, 31X)-, (3A, 3A, 5B)-, (3A, 5Y, 31X)- and (3A, 31X, 31X)-generated, for  $Y \in \{A, B\}$  and  $X \in \{A, B, C, D, E, F, G, H, I, J\}$ . We know that if  $G = \langle x, y \rangle$ , then it is also  $\langle y, x \rangle$ . Therefore *G* is (5Y, 3A, 31X)- and (31X, 3A, 31X)-generated. The result follows by Lemma 3.1.

**Proposition 3.6.** The group G is neither 4A- nor 4B-complementary generated.

**Proof.** Here we show that *G* is not (2A, 4X, nZ)-generated for  $X \in \{A, B\}$  and all the conjugacy classes of *G*. The direct computations with GAP show that  $\Delta_G(2A, 4X, nZ) = 0$  for  $X \in \{A, B\}$  and all the classes nZ of *G* except for the cases (2A, 4X, 4Y), (2A, 4X, 4C), (2A, 4X, 20Y), (2A, 4A, 24Z) and (2A, 4B, 24Y) for  $X, Y \in \{A, B\}, X \neq Y$  and  $Z \in \{C, D\}$ . Here we have

$$\begin{split} \Delta_G(2A, 4X, 4Y) &= 49 < 480 = |C_G(g)|, g \in 4Y, Y \in \{A, B\}, \\ \Delta_G(2A, 4X, 4C) &= 9 < 16 = |C_G(g)|, g \in 4C, \\ \Delta_G(2A, 4X, 8Y) &= 6 < 24 = |C_G(g)|, g \in 8Y, Y \in \{A, B\}, \\ \Delta_G(2A, 4X, 20Y) &= 4 < 20 = |C_G(g)|, g \in 20Y, Y \in \{A, B\}, \\ \Delta_G(2A, 4A, 24Z) &= 6 < 24 = |C_G(g)|, g \in 24Z, Z \in \{C, D\}, \\ \Delta_G(2A, 4B, 24Y) &= 6 < 24 = |C_G(g)|, g \in 24Y, Y \in \{A, B\}. \end{split}$$

It follows by Lemma 2.7 of Basheer and Seretlo (2020) that *G* is not generated by any of the previous 3-tuples. Therefore *G* is not generated by (2A, 4X, nZ),  $X \in \{A, B\}$  and all the classes nZ of *G*. This completes the proof that *G* is not 4X-complementary generated for  $X \in \{A, B\}$ .

#### **Proposition 3.7.** *The group G is 4C-complementary generated.*

**Proof.** Here we do some computations regarding the triples (pY, 4C, 31A) for all the primes p dividing the order of G. We firstly prove that G is (2A, 4C, 31A)-generated group. The direct computations with GAP show that  $\Delta_G(2A, 4C, 31A) = 31$ . Now from Table 1, we can see that only  $H_5 = 31:3$  is the maximal subgroup of G that contains elements of order 31. However it is clear that  $H_5$  neither contains elements of order 2 nor of order 4. Thus in the computations of  $\Delta_G^*(2A, 4C, 31A)$  there is no contribution from any maximal subgroup of G. It follows that  $\Delta_G^*(2A, 4C, 31A) = \Delta_G(2A, 4C, 31A) = 31$  and thus G is (2A, 4C, 31A)-generated group. Next we show that G is (3A, 4C, 31A)-generated group. The direct computations with GAP gives  $\Delta_G(3A, 4C, 31A) = 961$ . Again since  $H_5$  is the only maximal subgroup of G with elements of order 31, however it does not contain an element of order 4. Therefore  $\Delta_G^*(3A, 4C, 31A) = \Delta_G(3A, 4C, 31A) = 961$  and consequently G is (3A, 4C, 31A)-generated group. Similar arguments show that G is (5X, 4C, 31A)-generated group for  $X \in \{A, B\}$  ( $\Delta_G^*(5A, 4C, 31A) = \Delta_G(5A, 4C, 31A) = 31$ , while  $\Delta_G^*(5B, 4C, 31A) = \Delta_G(31X, 4C, 31A) = 930$ ). Finally using similar arguments we obtain for  $X \in \{A, B, C, D, E, F, G, H, I, J\}$  that  $\Delta_G^*(31X, 4C, 31A) = \Delta_G(31X, 4C, 31A) = 806$ , establishing the generation of G by the triple (31X, 4C, 31A) for X in the previous set. Now by applying Lemma 3.1 we deduce that G is 4C-complementary generated group.

#### **Proposition 3.8.** The group G is not 5A-complementary generated.

**Proof.** To show that G is not 5A-complementary generated, we prove that G is not (2A, 5A, nZ)-generated for all the conjugacy classes nZ of G. The direct computations with GAP reveal that  $\Delta_G(2A, 5A, nZ) = 0$  for all the classes nZ except when  $nZ \in \{2A, 10A, 12A, 12B, 20A, 20B\}$ . Clearly the group G cannot be (2A, 5A, 2A)-generated as this violets the condition  $\frac{1}{l} + \frac{1}{m} + \frac{1}{n} < 1$  for the group to be (l, m, n)-generated. Now we have the following:

It follows by Lemma 2.7 of Basheer and Seretlo (2020) that G is not generated by any of the previous 3-tuples. Therefore G is not generated by (2A, 5A, nZ) and all the classes nZ of G. Hence G is not 5A-complementary generated.

#### **Proposition 3.9.** The group G is 5B-complementary generated.

**Proof.** By Propositions 3.4, 3.11, 3.15 and 3.17 of Basheer and Seretlo (2019), the group *G* is (2A, 5B, 31X)-, (3A, 5B, 31X)-, (5Z, 5B, 31Y)- and (5B, 31X, 31Y)-generated, for  $Z \in \{A, B\}$  and  $X, Y \in \{A, B, C, D, E, F, G, H, I, J\}$ . We know that if  $G = \langle x, y \rangle$ , then it is also  $\langle y, x \rangle$ . Therefore *G* is (31X, 5B, 31Y)-generated for *X* and *Y* in the previous set. The result follows by Lemma 3.1.

#### **Proposition 3.10.** The group G is 6A-complementary generated.

**Proof.** The proof is similar to the one of Proposition 3.7. We show that G is (pY, 6A, 31A)-generated group for all  $pY \in \{2A, 3A, 5A, 5B, 31X\}, X \in \{A, B, C, D, E, F, G, H, I, J\}$ . From Table 1, the only maximal subgroup that has elements of order 31 is  $H_5 = 31:3$ . However it is clear that  $H_5$  does not contain an element of order 6. Thus there is no contribution from any maximal subgroup of G in the computations of  $\Delta_G^*(pY, 6A, 31A)$ . Using GAP we obtain that

 $\begin{array}{lll} \Delta^*_G(2A, 6A, 31A) &=& \Delta_G(2A, 6A, 31A) = 31, \\ \Delta^*_G(3A, 6A, 31A) &=& \Delta_G(3A, 6A, 31A) = 651, \\ \Delta^*_G(5A, 6A, 31A) &=& \Delta_G(5A, 6A, 31A) = 31, \\ \Delta^*_G(5B, 6A, 31A) &=& \Delta_G(5B, 6A, 31A) = 620, \\ \Delta^*_G(31X, 6A, 31A) &=& \Delta_G(31X, 6A, 31A) = 496, \end{array}$ 

for all  $X \in \{A, B, C, D, E, F, G, H, I, J\}$ . It follows that *G* is (pY, 6A, 31A)-generated group for all  $pY \in \{2A, 3A, 5A, 5B, 31X\}$  and  $X \in \{A, B, C, D, E, F, G, H, I, J\}$ . By Lemma 3.1 we deduce that *G* is 6*A*-complementary generated.

Proposition 3.11. The group G is 12A- and 12B-complementary generated.

**Proof.** Since G has only one class of elements of order 6, it becomes obvious that the power maps  $(12A)^2 = (12B)^2 = 6A$ . By Proposition 3.10 we have G is 6A-complementary generated. It follows by Lemma 3.4 that G is also 12A- and 12B-complementary generated group.

**Proposition 3.12.** The group G is 24X-complementary generated group for  $X \in \{A, B, C, D\}$ .

**Proof.** The power maps of the classes of elements of order 24 as follows:  $(24A)^2 = 12A$ ,  $(24B)^2 = 12A$ ,  $(24C)^2 = 12B$  and  $(24D)^2 = 12B$ . By Corollary 3.11, we know that *G* is 12*A*- and 12*B*-complementary generated. It follows by Lemma 3.4 that *G* is 24*X*-complementary generated group for  $X \in \{A, B, C, D\}$ .

**Proposition 3.13.** The group G is 8A- and 8B-complementary generated.

**Proof.** The proof is similar to the one of Propositions 3.7 and 3.10. We show that G is (pY, 8X, 31A)-generated group for all  $pY \in \{2A, 3A, 5A, 5B, 31Z\}, Z \in \{A, B, C, D, E, F, G, H, I, J\}$  and  $X \in \{A, B\}$ . From Table 1, the only maximal subgroup that has elements of order 31 is  $H_5 = 31:3$ . However it is clear that  $H_5$  does not contain an element of order 8. Thus there is no contribution from any maximal subgroup of G in the computations of  $\Delta_G^*(pY, 8X, 31A)$ . Using GAP we obtain that

$$\begin{split} &\Delta_{G}^{*}(2A,8X,31A) = \Delta_{G}(2A,8X,31A) = 31, \\ &\Delta_{G}^{*}(3A,8X,31A) = \Delta_{G}(3A,8X,31A) = 651, \\ &\Delta_{G}^{*}(5A,8X,31A) = \Delta_{G}(5A,8X,31A) = 651, \\ &\Delta_{G}^{*}(5B,8X,31A) = \Delta_{G}(5B,8X,31A) = 31, \\ &\Delta_{G}^{*}(5B,8X,31A) = \Delta_{G}(5B,8X,31A) = 620, \\ &\Delta_{G}^{*}(31Z,8X,31A) = \Delta_{G}(31Z,8X,31A) = 496, \end{split}$$

for all  $Z \in \{A, B, C, D, E, F, G, H, I, J\}$  and  $X \in \{A, B\}$ . It follows that *G* is (pY, 8X, 31A)-generated group for all  $pY \in \{2A, 3A, 5A, 5B, 31Z\}$  and  $Z \in \{A, B, C, D, E, F, G, H, I, J\}$  and  $X \in \{A, B\}$ . By Lemma 3.1 we deduce that *G* is 8*X*-complementary generated group for  $X \in \{A, B\}$ .

**Proposition 3.14.** The group G is 10A-complementary generated.

**Proof.** The proof is similar to the previous ones handling the cases 4*C*, 6*A*, 8*A* and 8*B*. We show that *G* is (pY, 10A, 31A)generated group for all  $pY \in \{2A, 3A, 5A, 5B, 31X\}$  and  $X \in \{A, B, C, D, E, F, G, H, I, J\}$ . From Table 1, the only maximal
subgroup that has elements of order 31 is  $H_5 = 31:3$ . However it is clear that  $H_5$  does not contain an element of order 10. Thus
there is no contribution from any maximal subgroup of *G* in the computations of  $\Delta_G^*(pY, 10A, 31A)$ . Using GAP we obtain that

$$\begin{split} \Delta_{G}^{*}(2A, 10A, 31A) &= \Delta_{G}(2A, 10A, 31A) = 31, \\ \Delta_{G}^{*}(3A, 10A, 31A) &= \Delta_{G}(3A, 10A, 31A) = 775, \\ \Delta_{G}^{*}(5A, 10A, 31A) &= \Delta_{G}(5A, 10A, 31A) = 31, \\ \Delta_{G}^{*}(5B, 10A, 31A) &= \Delta_{G}(5B, 10A, 31A) = 774, \\ \Delta_{G}^{*}(31X, 10A, 31A) &= \Delta_{G}(31X, 10A, 31A) = 620, \end{split}$$

for all  $X \in \{A, B, C, D, E, F, G, H, I, J\}$ . It follows that G is (pY, 6A, 31A)-generated group for all  $pY \in \{2A, 3A, 5A, 5B, 31X\}$  and  $X \in \{A, B, C, D, E, F, G, H, I, J\}$ . By Lemma 3.1 we deduce that G is 6A-complementary generated.

**Proposition 3.15.** The group G is 20A-complementary generated.

**Proof.** Since G has only one class of elements of order 10, it becomes obvious that the power map  $(20A)^2 = 10A$ . By Proposition 3.14 we have G is 10A-complementary generated. It follows by Lemma 3.4 that G is also 20A-complementary generated group.

**Proposition 3.16.** The group G is 31X-complementary generated for  $X \in \{A, B, C, D, E, F, G, H, I, J\}$ .

**Proof.** By Propositions 3.5, 3.12, 3.17 and 3.18 of Basheer and Seretlo (2019), the group *G* is (2A, 31X, 31Y)-, (3A, 31X, 31Y)-, (5B, 31X, 31Y)- and (31X, 31Y, 31Z)-generated, for  $X, Y \in \{A, B, C, D, E, F, G, H, I, J\}$ . Also for  $X, Y \in \{A, B, C, D, E, F, G, H, I, J\}$  and  $X \neq Y$ , the group *G* is (5A, 31X, 31Y)-generated. Therefore *G* is (pY, 31X, nZ)-generated for all the conjugacy classes pY of *G*, where *p* is a prime divides the order of *G*. The result follows by Lemma 3.1.

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#### **RESEARCH ARTICLE**

### Generalizations of third-order recurrence relation

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#### ABSTRACT

This paper presents a generalization of the sequence defined by the third-order recurrence relation  $V_n(a_j, p_j) = \sum_{j=1}^{3} p_j V_{n-j}, n \ge 4,$  $p_3 \neq 0$  with initial terms  $V_j = a_j$ , where  $a_j$  and  $p_j$  j = 1, 2, 3, are any non-zero real numbers. The generating function and Binet's formula are derived for this generalized tribonacci sequence. Classical second-order generalized Fibonacci sequences and other existing sequences based on second-order recurrence relations are implicitly included in this analysis. These derived sequences are discussed as special cases of the generalization. A pictorial representation is provided, illustrating the growth and variation of tribonacci numbers for different initial terms  $a_i$  and coefficients  $p_i$ . Additionally, the tribonacci constant is examined and visually represented. It is observed that the constant is influenced solely by the coefficients  $p_i$  of the recurrence relation and is unaffected by the initial terms  $a_i$ .

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Keywords: Generalized Tribonacci sequence, generating function, Binet's formula, Tribonacci constant.

#### **1. INTRODUCTION**

Tribonacci sequences are the generalization of the classical Fibonacci sequence, defined by a recurrence relation involving the sum of the three preceding terms, where each term is the sum of the three preceding terms. The enigmatic tribonacci number sequences with its captivating properties, has piqued the curiosity of mathematicians and researchers, opening doors to a world of intriguing applications as it has attracted attention in various branches of physical sciences and its applications. Sequence terms in a recursive relations are generated sequentially, the process of calculating any specific term is computationally intensive, as it necessitates the calculation of all its predecessors. Alternatively, using the index form of a generating function or Binet's formula provides efficient methods for directly computing any term of a recursive sequence. Although extensive research has been conducted on second-order Fibonacci sequences and their generalizations, the exploration of third-order recurrence relations, particularly in the context of third-order Fibonacci-like sequences, has received comparatively less attention. A generalized tribonacci sequence,  $\{V_n\}$ , is result of the recurrence relations with coefficients  $p_i$  and arbitrary first three initial terms  $a_i$ . The concept of tribonacci sequence mentioned and studied, first time by Feinberg M. Feinberg (1963), then number of generalizations of the Fibonacci sequence have been considered and examined by many authors W. R. Spickerman (1982); T. Komatsu (2018); R. Frontczak (2018); A. G. Shannon (1972); A. C. F. Bueno (2015); T. Komatsu and R. Li (2017); T. Koshy (2001); P. Y. Lin (1988); S. Pethe (1988); Y. Soykan (2019); C. C. Yalavigi (1972). F. T. Howard (2001) extended and generalize the main result obtained by F. T. Howard (1999) for tribonacci sequences. Generalization of Tribonacci sequences for quaternions studied by G. Cerda-Morales (2017). In the literature. Generalized Tribonacci sequence has also been considered and studied by A. G. Shannon and A. F. Horadam (1972); M. E. Waddill and L. Sacks (1967); T. Komatsu and R. Li (2017) and Y. Soykan, I. et al. (2020); A. Scott, T. et al. (1997). This research aims to address by considering and exploring the properties, patterns, and potential applications of generalized third-order Fibonacci sequences. In this article, generalized third-order recurrence relations with variable coefficients  $p_i$  and initial terms  $a_i$  are taken to derive the generalized form of generating function and the Binet's formula. Classical second-order generalized Fibonacci sequences and other existing sequences based on second-order recurrence relations are implicitly included in this analysis. These derived sequences are discussed as special cases of the generalization. A pictorial representation is provided, illustrating the growth and variation of tribonacci numbers for different initial terms  $a_i$  and coefficients  $p_i$ . Additionally, the

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Tribonacci constant is examined and visually represented. It is observed that the constant is influenced solely by the coefficients  $p_j$  of the recurrence relation and is unaffected by the initial terms  $a_j$ .

**Definition 1.1.** We define the Generalized Tribonacci sequence  $\{V_n\}$  by the following linear recurrence relation:

$$V_n(a_1, a_2, a_3, p_1, p_2, p_3) = p_1 V_{n-1} + p_2 V_{n-2} + p_3 V_{n-3}, \ n \ge 4,$$
(1)

with the initial conditions,  $a_i = V_i$ ,  $a_j$ ,  $p_j$ , j = 1, 2, 3 are any non-zero real numbers.

The expression for  $\{V_n\}$  in (1) is holds true T. Koshy (2001) for every integer  $n \ge 4$ . Terms of the Generalized Tribonacci Sequence The first few terms in the generalized form of the sequence defined in (1) are:

$$\{V_n\} = \begin{cases} a_1, a_2, a_3, p_1a_3 + p_2a_2 + p_3a_1, (p_1^2 + p_2)a_3 + (p_1p_2 + p_3)a_2 + p_1p_3a_1, \\ (p_1^3 + p_3 + 2p_1p_2)a_3 + (p_1^2p_2 + p_2^2 + p_1p_3)a_2 + (p_1^2p_3 + p_2p_3)a_1 + \cdots \end{cases} \end{cases}.$$

**Tribonacci Sequences pictorial representations** A few values Y. Soykan, I. et al. (2020) of Tribonacci sequences represented in the following figure.



Figure 1. Tribonacci sequences progression and comparison

#### **Special Cases**

**Remark 1.2.** With initial conditions  $V_0 = 0$ ,  $V_1 = 1$ ,  $V_2 = 1$ , and  $p_1 = p_2 = p_3 = 1$ , recurrence relation (1) is known as the generalized Lucas tribonacci sequence and is denoted by  $T_n$  in F. T. Howard (1999). The first few terms of the sequence deduced from the above generalization:

$$\{V_n\}_{n\geq 0} = \{T_n\} = \{0, 1, 1, 2, 4, 7, 13, 24, 44, 81, 149, 274, 504, 927, 1705, 3136, \cdots\}$$

This tribonacci number sequence is A000073 on the OEIS, N. J. A. Sloane (1973).

**Remark 1.3.** If we substitute the initial conditions  $V_0 = 3$ ,  $V_1 = 1$ ,  $V_2 = 3$ , and  $p_1 = p_2 = p_3 = 1$  in (1), it reduces to  $K_n$  sequence which is explained in ?. The first few terms of the sequence  $K_n$  are:

$$\{V_n\}_{n\geq 0} = \{K_n\} = \{3, 1, 3, 7, 11, 21, 39, 71, 131, 241, 443, 815, 1499, 2757, 5071, 9327, \cdots\}$$

This tribonacci number sequence is A001644 on the OEIS, N. J. A. Sloane (1973).

#### 2. GENERALIZED GENERATING FUNCTIONS

A generating function W. Watkins (1987) is a representation of a sequence as the coefficients of a power series in mathematics. By analyzing the generating function, we can derive various properties of the generalized Tribonacci sequence, such as closed-form expressions, asymptotic behavior, and generating function identities.

**Theorem 2.1.** (Generalized Generating Functions) The generalized generating function of the sequence defined in (1) is

$$V(x) = \frac{f(x)}{1 - p_1 x - p_2 x^2 - p_3 x^3},$$
(2)

where  $f(x) = V_0 + (V_1 - p_1 V_0) x + (V_2 - p_1 V_1 - p_2 V_0) x^2$ .

**Proof.** If V(x) is the generating function of  $V_n = p_1V_{n-1} + p_2V_{n-2} + p_3V_{n-3}$ , then we have

$$V(x) = \sum_{n=0}^{\infty} V_n x^n = V_0 + V_1 x + V_2 x^2 + V_3 x^3 + \dots$$
(3)

Multiplying V(x) by  $p_1x$ ,  $p_2x^2$  and  $p_3x^3$ , we have

$$p_{1}xV(x) = p_{1}V_{0}x + p_{1}V_{1}x^{2} + p_{1}V_{2}x^{3} + p_{1}V_{3}x^{4} + \cdots$$

$$p_{2}x^{2}V(x) = p_{2}V_{0}x^{2} + p_{2}V_{1}x^{3} + p_{2}V_{2}x^{4} + p_{2}V_{3}x^{5} + \cdots$$

$$p_{3}x^{3}V(x) = p_{3}V_{0}x^{3} + p_{3}V_{1}x^{4} + p_{3}V_{2}x^{5} + p_{3}V_{3}x^{6} + \cdots$$
(4)

Subtracting (3)- (4) and rearranging the above equations, we have

$$V(x) \left[ 1 - p_1 x - p_2 x^2 - p_3 x^3 \right] = f(x).$$

Solving for V(x), we obtain

$$V(x) = \frac{f(x)}{1 - p_1 x - p_2 x^2 - p_3 x^3},$$
(5)

where  $f(x) = V_0 + (V_1 - p_1V_0)x + (V_2 - p_1V_1 - p_2V_0)x^2$  is a polynomial. Hence V(x) is the generating function of the sequence  $\{V_n\}$ .

**Remark 2.2.** If we substitute  $V_0 = 3$ ,  $V_1 = 1$ ,  $V_2 = 3$ , and  $p_1 = p_2 = p_3 = 1$  in the result obtained in (5), it reduces to the generating function

$$V(x) = \frac{3 - 2x - x^2}{1 - x - x^2 - x^3} = T(x),$$

which is the same as result, which is explained in M. Elia (2001); M. Catalani (2002).

**Remark 2.3.** If we substitute  $V_0 = 0$ ,  $V_1 = 1$ ,  $V_2 = 1$ , and  $p_1 = p_2 = p_3 = 1$  in result of (5), it reduces to the generating function

$$V(x) = \frac{x}{1 - x - x^2 - x^3} = K(x),$$

which is the same as result, which is explained in M. Elia (2001); M. Catalani (2002).

#### 2.1. Even and odd terms Generating Functions of the Generalized Tribonacci Sequence

**Theorem 2.4.** [Even and odd terms Generating Functions] The generating functions of even  $V_{2n}(x)$  and odd  $V_{2n+1}(x)$  terms of the Generalized Tribonacci Sequence (1) are:

$$V_{even}(x) = \frac{V_0 - \left[(2p_2 + p_1^2)V_0 - V_2\right]x + \left[(p_2^2 - p_1p_3)V_0 + (p_1p_2 + p_3)V_1 - p_2V_2\right]x^2}{1 - (p_1^2 + 2p_2)x - (2p_1p_3 - p_2^2)x^2 - p_3^2x^3},$$

and

$$V_{odd}(x) = \frac{V_1 + \left[V_0 p_3 - (p_1^2 + p_2)V_1 + p_1 V_2\right] x + \left[p_3 V_2 - p_1 p_3 V_1 - p_2 p_3 V_0\right] x^2}{1 - (p_1^2 + 2p_2)x - (2p_1 p_3 - p_2^2)x^2 - p_3^2 x^3}$$

**Proof.** From the definition of the even  $V_{2n}(x) = \frac{V_n(\sqrt{x}) + V_n(-\sqrt{x})}{2}$  and odd  $V_{2n+1}(x) = \frac{V_n(\sqrt{x}) - V_n(-\sqrt{x})}{2\sqrt{x}}$  functions and employing the Generalized generating function of the Tribonacci sequence (1) obtained in the Theorem (2.1) we have

$$V_n(x) = \frac{f(x)}{1 - p_1 x - p_2 x^2 - p_3 x^3}$$

where  $f(x) = V_0 + (V_1 - p_1 V_0) x + (V_2 - p_1 V_1 - p_2 V_0) x^2$ .

On simplification we obtained the Generalized Generating function of even and odd terms of Tribonacci sequence

$$V_{even}(x) = \frac{V_0 - \left[ (2p_2 + p_1^2)V_0 - V_2 \right] x + \left[ (p_2^2 - p_1p_3)V_0 + (p_1p_2 + p_3)V_1 - p_2V_2 \right] x^2}{1 - (p_1^2 + 2p_2)x - (2p_1p_3 - p_2^2)x^2 - p_3^2x^3},$$
(6)

and

$$V_{odd}(x) = \frac{V_1 + \left[V_0 p_3 - (p_1^2 + p_2)V_1 + p_1 V_2\right]x + \left[p_3 V_2 - p_1 p_3 V_1 - p_2 p_3 V_0\right]x^2}{1 - (p_1^2 + 2p_2)x - (2p_1 p_3 - p_2^2)x^2 - p_3^2 x^3}.$$
(7)

#### 2.2. Special cases of Even and odd terms Generating Functions

**Remark 2.5.** With initial conditions  $V_0 = 0$ ,  $V_1 = 1$ ,  $V_2 = 1$ , and  $p_1 = p_2 = p_3 = 1$ , the even and odd terms Generating Functions of the generalized Lucas sequence  $T_n$  T. Koshy (2001)) are deduced from the (6) and (7) generalized even and odd terms generating functions as:

$$V_{even}(x) = T_{even}(x) = \frac{x + x^2}{1 - 3x - x^2 - x^3}$$

and

$$V_{odd}(x) = T_{odd}(x) = \frac{1-x}{1-3x-x^2-x^3}$$

Similarly with initial conditions  $V_0 = 3$ ,  $V_1 = 1$ ,  $V_2 = 3$ , and  $p_1 = p_2 = p_3 = 1$  in (1), the even and odd terms Generating Functions of the generalized Lucas sequence  $K_n$ . T. Koshy (2001)) are deduced from the (6) and (7) generalized even and odd terms Generating Functions are:

$$V_{2n}(x) = K_{even}(x) = \frac{3 - 6x - x^2}{1 - 3x - x^2 - x^3},$$

and

$$V_{odd}(x) = K_{odd}(x) = \frac{3 + 4x - x^2}{1 - 3x - x^2 - x^3}$$

These even and odd terms of the Generating Functions of  $T_n$  and  $K_n$  are same as obtained by T. Komatsu (2018).

**Theorem 2.6.** (Generalized Binet's formula for Tribonacci sequence) Generalized form of the Binet's formula for the sequence defined in (1) is

$$V_n(x) = \sum_{j=1}^3 \left[ \frac{A_1 \alpha_j^2 + A_2 \alpha_j + A_3}{\prod\limits_{\substack{1 \le i \le 3 \\ i \ne j}} (\alpha_j - \alpha_i)} \right] \alpha_j^n = \sum_{j=1}^3 \frac{\left(\alpha_j^2 A_1 + \alpha_j A_2 + A_3\right) p_3 \alpha_j^{n+1}}{\alpha_j^3 p_3 - \alpha_j p_1 + 2}.$$

**Proof.** Since V(x) is the generating function of the sequence  $\{V_n\}$ 

$$V(x) = \frac{f(x)}{1 - p_1 x - p_2 x^2 - p_3 x^3},$$

where  $f(x) = V_0 + (V_1 - p_1 V_0) x + (V_2 - p_1 V_1 - p_2 V_0) x^2$ .

Consider the partial fraction decomposition of the right-hand side of the generating function , we have

$$V(x) = \frac{A_1 + A_2 x + A_3 x^2}{1 - p_1 x - p_2 x^2 - p_3 x^3} = \frac{A_1 + A_2 x + A_3 x^2}{(1 - \alpha_1 x) (1 - \alpha_2 x) (1 - \alpha_3 x)},$$

where  $A_1 = V_0$ ,  $A_2 = V_1 - p_1 V_0$ ,  $A_3 = V_2 - p_1 V_1 - p_2 V_0$  and  $\alpha_i$ , i = 1, 2, 3, are roots of the equation  $1 - p_1 x - p_2 x^2 - p_3 x^3 = 0$ .

On simplification we have

$$V_n(x) = \sum_{j=1}^3 \left[ \frac{A_1 \alpha_j^2 + A_2 \alpha_j + A_{3k}}{\prod\limits_{\substack{1 \le i \le 3\\ i \ne j}} (\alpha_j - \alpha_i)} \right] \alpha_j^n = \sum_{j=1}^3 \frac{\left(\alpha_j^2 A_1 + \alpha_j A_2 + A_3\right) p_3 \alpha_j^{n+1}}{p_3 \alpha_j^3 - \alpha_j p_1 + 2}.$$
(8)

The above relation is the Generalized Binet's formula for Tribonacci sequence

#### 2.3. Special cases: Generalized Binet's formula for Tribonacci sequence

Remark 2.7. Generalized form of the Binet's formula (8) for the generalized sequence(1) can also be written as

$$V_{n} = \begin{bmatrix} \left(\frac{\alpha_{3}^{n+2} - \alpha_{2}^{n+2}}{\alpha_{3} - \alpha_{2}}\right) \frac{\alpha_{1}}{(\alpha_{1} - \alpha_{3})(\alpha_{2} - \alpha_{1})} + \left(\frac{\alpha_{1}^{n+2} - \alpha_{3}^{n+2}}{\alpha_{1} - \alpha_{3}}\right) \frac{\alpha_{2}}{(\alpha_{3} - \alpha_{2})(\alpha_{2} - \alpha_{1})} \\ + \left(\frac{\alpha_{2}^{n+2} - \alpha_{1}^{n+2}}{\alpha_{2} - \alpha_{1}}\right) \frac{\alpha_{3}}{(\alpha_{3} - \alpha_{2})(\alpha_{1} - \alpha_{3})} \end{bmatrix}.$$
$$= \sum_{j=0}^{n} \left(\sum_{k=0}^{n-j} \alpha_{1}^{j} \alpha_{k} \alpha_{3}^{n-j-k}\right)$$

**Remark 2.8.** If we put  $V_3 = 0$ ,  $p_3 = 0$ , in equation (1) then tribonacci sequences becomes the generalized classical Fibonacci sequence, and the Binet's formula (8) in this case reduces to

$$\begin{split} V_n(x) &= \frac{A_1 + A_2 x}{1 - p_1 x - p_2 x^2} \\ V_n(x) &= \frac{(\alpha_1 A_1 + A_2) (\alpha_1^n) - (\alpha_2 A_1 + A_2) (\alpha_2^n)}{\alpha_1 - \alpha_2} \\ V_n(x) &= \frac{A_1 (\alpha_1^{n+1} - \alpha_2^{n+1}) + A_2 (\alpha_1^n - \alpha_2^n)}{\alpha_1 - \alpha_2} = A_1 \left( \frac{\alpha_1^{n+1} - \alpha_2^{n+1}}{\alpha_1 - \alpha_2} \right) + A_2 \left( \frac{\alpha_1^n - \alpha_2^n}{\alpha_1 - \alpha_2} \right) \end{split}$$

where  $A_1 = V_0, A_2 = (V_1 - p_1 V_0)$  and  $\alpha_i, i = 1, 2$  are roots of the equation  $1 - p_1 x - p_2 x^2 = 0$ .

**Remark 2.9.** If we take  $V_0 = 0$ ,  $V_1 = 1$ ,  $V_2 = 1$ , and  $p_1 = p_2 = p_3 = 1$ , in the expression (8) this reduces to

$$V_n(x) = \frac{\alpha_1^{n+1}}{(\alpha_1 - \alpha_2)(\alpha_1 - \alpha_3)} + \frac{\alpha_2^{n+1}}{(\alpha_2 - \alpha_1)(\alpha_2 - \alpha_3)} + \frac{\alpha_3^{n+1}}{(\alpha_3 - \alpha_1)(\alpha_3 - \alpha_2)} = T_n$$

. which is same, as obtained by R. Frontczak (2018).

When  $V_0 = 3$ ,  $V_1 = 1$ ,  $V_2 = 3$ , and  $p_1 = p_2 = p_3 = 1$ , in the expression (8) this reduces to

$$V(x) = \alpha_1^n + \alpha_2^n + \alpha_3^n = K_n$$

where  $\alpha_i$ , i = 1, 2, 3 are roots of the equation  $1 - x - x^2 - x^3 = 0$ . This is in agreement with W. R. Spickerman (1982); R. Frontczak (2018).

Theorem 2.10. If

$$V_n = \begin{cases} a_i \text{ if } 1 \le n \le 3\\ p_1 V_{n-1} + p_2 V_{n-2} + \dots + p_3 V_{n-3} \text{ if } n > 3 \end{cases}$$

then for  $n \ge 4$ , we have

$$V_{n} = 2p_{1}V_{n-1} + (p_{2} - p_{1}^{2})V_{n-2} + (p_{3} - p_{1}p_{2})V_{n-3} - p_{1}p_{3}V_{n-4}.$$

*Proof.* Rewrite the recurrence relation (1) as

$$V_{n} = p_{1}V_{n-1} + p_{2}V_{n-2} + p_{3}V_{n-3} + 0$$
  
=  $p_{1}V_{n-1} + p_{2}V_{n-2} + p_{3}V_{n-3} + (p_{1}V_{n-1} - p_{1}^{2}V_{n-2} - p_{1}p_{2}V_{n-3} - p_{1}p_{3}V_{n-4})$   
=  $2p_{1}V_{n-1} + (p_{2} - p_{1}^{2})V_{n-2} + (p_{3} - p_{1}p_{2})V_{n-3} - p_{1}p_{3}V_{n-4}$ 

$$\begin{bmatrix} \because V_n = p_1 V_{n-1} + p_2 V_{n-2} + p_3 V_{n-3} \text{ by multipling } p_1 \text{ and replacing } n \text{ by } (n-1), \text{ we have } \\ p_1 V_{n-1} - p_1^2 V_{n-2} - p_1 p_2 V_{n-3} - p_1 p_3 V_{n-4} \end{bmatrix}$$

$$V_{n} = 2p_{1}V_{n-1} + \left(p_{2} - p_{1}^{2}\right)V_{n-2} + \left(p_{3} - p_{1}p_{2}\right)V_{n-3} - p_{1}p_{3}V_{n-4}.$$
(9)

**Remark 2.11.** On substituting  $p_1 = p_2 = p_3 = 1$ , in the result of above Theorem (2.10) we have

$$V_n = 2V_{n-1} + (0) V_{n-2} + (0) V_{n-3} - V_{n-4}$$

, this implies that

$$V_n = 2V_{n-1} - V_{n-4}$$

. which is in agreement with F. T. Howard and C. Cooper (1970); M. E. Waddill and L. Sacks (1967).

**Theorem 2.12.** If 
$$V_n = p_1 V_{n-1} + p_2 V_{n-2} + p_3 V_{n-3}$$
,  $n > 3$ ,  $f(x) = x^3 - p_1 x^2 - p_2 x - p_3 = 0$ ,, then  

$$\lim_{n \to \infty} \frac{V_{n+1}(a_1, a_2, a_3, p_1, p_2, p_3)}{V_n(a_1, a_2, a_3, p_1, p_2, p_3)}$$

$$= \begin{cases} \alpha, real root of f(x) = 0, p_i > 0, others roots are complex, \\ \alpha \ (largest root), if all roots of f(x) = 0 are real, \\ p_i > 0, others roots are complex, \\ 1.839, if p_j = 1 and a_j \ (j = 1, 2, 3) are any real numbers, \\ 1.618, if p_3 = 0, a_3 = 0, and p_j, a_j, \ (j = 1, 2) are any real numbers \end{cases}$$

**Remark 2.13.** Graphical representation of the theorem (2.12) for the polynomials  $f(x) = x^3 - x^2 - x = 0$ ,  $f(x) = x^3 - x^2 - x - 1 = 0$ , and  $f(x) = x^3 - x^2 - x - 3 = 0$ .



Figure 2. Tribonacci sequences progression and comparison

#### **3. IDENTITIES**

**Theorem 3.1.** If  $n \ge m$ , then on employing the result of theorem (2.6)

$$V_n V_{n+m} = \left( \sum_{\substack{j=1\\j \in I}}^3 \left[ \frac{A_1 \alpha_j^2 + A_2 \alpha_j + A_3}{\prod\limits_{\substack{1 \le i \le 3\\i \ne j}} (\alpha_j - \alpha_i)} \right] \right) \alpha_j^n \cdot \left( \sum_{\substack{j=1\\j \in I}}^3 \left[ \frac{A_1 \alpha_j^2 + A_2 \alpha_j + A_3}{\prod\limits_{\substack{1 \le i \le 3\\i \ne j}} (\alpha_j - \alpha_i)} \right] \right) \alpha_j^{n+m}.$$

Proof. Using

$$V_n(x) = \sum_{j=1}^3 \left[ \frac{A_1 \alpha_j^2 + A_2 \alpha_j + A_{3k}}{\prod\limits_{\substack{1 \le i \le 3 \\ i \ne j}} (\alpha_j - \alpha_i)} \right] \alpha_j^n.$$

On simplifying the RHS, we obtain

$$V_n V_{n+m} = V_{2n+m} + V_n V_m - \sum_{j=1}^3 \left( \frac{A_1 \alpha_j^2 + A_2 \alpha_j + A_3}{\prod\limits_{\substack{1 \le i \le 3 \\ i \ne j}} (\alpha_j - \alpha_i)} \right)^2 \alpha_j^{2n+m}.$$

#### 3.1. Special cases: Identities

If we replace n by n - 1 and taking m = 1, in (3.1) then we obtain

$$V_{n-1}V_n = V_{2n-1} + V_{n-1}V_1 - \sum_{j=1}^3 \left( \frac{A_1 \alpha_j^2 + A_2 \alpha_j + A_3}{\prod\limits_{\substack{1 \le i \le 3 \\ i \ne j}} (\alpha_j - \alpha_i)} \right)^2 \alpha_j^{2n-1}.$$

If we take m = n then we get

$$V_n V_{2n} = V_{3n} + V_n V_n - \sum_{j=1}^3 \left( \frac{A_1 \alpha_j^2 + A_2 \alpha_j + A_3}{\prod_{\substack{1 \le i \le 3 \\ i \ne j}} (\alpha_j - \alpha_i)} \right)^2 \alpha_j^{3n}.$$

If we take m = 0 in (3.1) then we get

$$V_n^2 = V_{2n} + V_n V_0 - \sum_{j=1}^3 \left( \frac{A_1 \alpha_j^2 + A_2 \alpha_j + A_3}{\prod\limits_{\substack{1 \le i \le 3 \\ i \ne j}} (\alpha_j - \alpha_i)} \right)^2 \alpha_j^{2n}$$
$$V_n^3 = V_n^2 V_n = V_{2n} V_n + V_n^2 V_0 - V_n \sum_{j=1}^3 \left( \frac{A_1 \alpha_j^2 + A_2 \alpha_j + A_3}{\prod\limits_{\substack{1 \le i \le 3 \\ i \ne j}} (\alpha_j - \alpha_i)} \right)^2 \alpha_j^{2n} V_n$$

In general from (3.1), we have

$$V_n V_{nm} = V_{mn+n} + V_n V_{nm-n} - \sum_{j=1}^3 \left( \frac{A_1 \alpha_j^2 + A_2 \alpha_j + A_3}{\prod\limits{\substack{1 \le i \le 3 \\ i \ne j}} \left( \alpha_j - \alpha_i \right)} \right)^2 \alpha_j^{nm-n}.$$

#### 4. DISCUSSION AND CONCLUSION

This study investigates a generalized third-order recurrence relation. After defining the initial terms in general form, we present a graphical representation in Figure 1 to illustrate the progression of Tribonacci numbers for various cases considered by previous authors. Figure 2 depicts the ratio of consecutive terms as the number of terms approaches infinity. We observe that the Tribonacci constant is solely influenced by the coefficients  $p_j$  of the recurrence relation and is unaffected by the terms  $a_j$ . We derive the generating function and Binet formula in their general forms. By applying these results, we show that many existing results from previous studies emerge as special cases. Future research could delve deeper into this generalized third-order sequence, extending the analysis to explore additional properties and applications. Employing alternative approaches, such as matrix methods, combinatorial arguments, or number theory, may lead to the discovery of new identities and theorems.

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**RESEARCH ARTICLE** 

# A New Liu-Ratio Estimator For Linear Regression Models

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#### ABSTRACT

In statistical modeling, regression analysis is a set of statistical processes for estimating the relationships between a dependent variable and one or more independent variables. Although there are various methods for estimating parameters, the most popular is the Ordinary Least Squares (OLS) method. However, in the presence of multicollinearity and outliers, the OLS estimator may give inaccurate values and also misleading inference results. There are many modified biased robust estimators for the simultaneous occurrence of outliers and multicollinearity in the data. In this paper, a new estimator called the Liu-Ratio Estimator (LRE), which can be used as an alternative to the Least Squares Ratio (LSR) estimator and the Ridge Ratio estimator (RRE), is proposed to mitigate the effect of y-direction outliers and multicollinearity in the data. The performance of the proposed estimator is examined in two Monte Carlo simulation studies in the presence of multicollinearity and y-direction outliers. According to the simulation results, LRE is a strong alternative to LSR and RRE in the presence of multicollinearity and y-direction outliers in the data.

#### Mathematics Subject Classification (2020): 62J05,62J07

Keywords: Least Squares Ratio Estimator, Liu Estimator, Multicollinearity, Ridge Estimator.

#### 1. INTRODUCTION

Regression analysis is a statistical technique for investigating and modeling the relationship between variables. Applications for regression models are numerous and occur in almost every field, including engineering, the physical and chemical sciences, economics, management, life and biological sciences, and social sciences. The classical linear regression model assumes a relation of the form:

$$y_i = \beta_0 + \sum_{j=1}^p x_{ij}\beta_j + \varepsilon_i, \quad i = 1, 2, ..., n$$
 (1)

where n is the number of observations,  $x_{ij} = 1, 2, ..., p$  are the independent variables for observation i,  $y_i$  the observed response variable, the  $\varepsilon_i$  is the error term for the observation i and  $\beta_i$  are the coefficients to be estimated, representing the relationship between each independent variable and the dependent variable.

The most popular way of estimating  $\beta$  is to minimize the Ordinary Least Squares (OLS) criterion. Unfortunately, the wellknown problem of multicollinearity in regression analysis due to high correlation between independent variables affects the OLS estimator. As a result of multicollinearity between explanatory variables, the variance of OLS becomes so large that estimates become unstable (Montgomery et al. 2001). Many biased estimators have been proposed for the multicollinearity problem, but the Ridge Estimator (RE) proposed by Hoerl and Kennard (1970) and the Liu Estimator (LE) proposed by Liu (1993) are some of the most widely used estimators.

In addition, there are many situations where the distribution of errors is nonnormal. In the case of nonnormal distributions, particularly heavy-tailed distributions, the OLS estimator no longer has the desirable properties. These heavy-tailed distributions tend to generate outliers, which may have an improper effect on the OLS estimates (Montgomery et al. 2001). Numerous robust estimating techniques, including the M-estimator, the least squares median estimator, the least truncated sum of squares estimator, the S-estimator, and the MM-estimator, have been presented to generate parameter estimates in the presence of outliers (Rousseeuw and Leroy 1987), (Maronna et al. 2006). However, while robust estimators are robust techniques for obtaining parameter estimates that are not affected by outliers, some unstable estimates may still be obtained due to the presence of multicollinearity between variables. Therefore, to mitigate the effects of both outliers and multicollinearity to some extent is to use biased-robust estimators.

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For example, various modifications of RE and LE, which are used for the multicollinearity problem, are widely used to address both outliers and multicollinearity (Silvapulle 1991), (Arslan and Billor 2000), (Maronna 2011), (Kan et al. 2013), (Jadhav and Kashid 2016), (Ertaş et al. 2017), (Filzmoser and Kurnaz 2018).

Recently, Akbilgic and Akinci (2009) proposed the Least Squares Ratio (LSR) as an alternative for OLS in order to estimate the beta parameter vector in the presence of *y*-direction outliers. On the other hand, Jadhav and Kashid (2018) developed an estimator called the Ridge Ratio Estimator (RRE) as an alternative to RE and LSR in the presence of outliers and multicollinearity in the data. Therefore, one of the objectives of this paper is to propose a new estimator as an alternative to LSR and RRE to overcome the simultaneous occurrence of outliers and multicollinearity in the data, based on the fact that LE is always an alternative to RE as known from the multicollinearity problem. Another objective is to investigate the performance of the proposed estimator with respect to LSR and RRE through extensive simulation studies.

The organization of the paper is as follows: The main ideas underlying the proposed estimator are highlighted in Section 2. In Section 3, two separate Monte Carlo simulation studies are conducted to evaluate the performance of the proposed estimator with respect to LSR and RRE. In Section 4, the performance of the proposed estimator is evaluated against that of other estimators on artificial data. Finally, the conclusions of the study are presented in Section 5.

#### 2. A NEW ROBUST LIU RATIO ESTIMATOR

For the regression model given by (1), OLS minimizes the sum of squares of the distances between the observed value  $y_i$ and the fitted value  $\hat{y}_i$  where i = 1, 2, ..., n. As an alternative to OLS, LSR method starts with the same goal  $y_i = \hat{y}_i$ , or  $y_i - \hat{y}_i = 0$ , i = 1, 2, ..., n as in OLS. Note that the OLS approach satisfies this aim by finding the regression parameters minimizing the sum of  $(y_i - \hat{y}_i)^2$ . However, LSR proceeds by dividing through by  $y_i$  and so  $\frac{\hat{y}_i}{y_i} = 1$  is obtained under an assumption of  $y_i \neq 0$  where i = 1, 2, ..., n (Akbilgic and Akinci 2009). Hence, it is obvious that, equations  $\frac{\hat{y}_i}{y_i} - 1 = 0$  and thus  $\frac{y_i - \hat{y}_i}{y_i} = 0$  where i = 1, 2, ..., n are obtained by basic mathematical operations. As a result, the LSR estimator is obtained by minimizing the objective function as follows:

$$\min_{\beta} \sum_{i=1}^{n} \left( \frac{y_i - \hat{y}_i}{y_i} \right)^2 \quad \text{or} \quad \min_{\beta} \sum_{i=1}^{n} \left( 1 - \hat{\beta}_j \frac{x_{ij}}{y_i} \right)^2 \tag{2}$$

where  $\hat{y}_i = \beta_0 + \sum_{j=1}^{p} \hat{\beta}_j x_{ij}$ , i = 1, 2, ..., n. Taking the partial derivatives of (2) with respect to the  $\beta$  components and setting them equal to zero, Akbilgic and Akinci (2009) defined the LSR estimator as follows:

$$\hat{\beta}_{LSR} = \left( \left( \frac{X}{Y} \right)' \left( \frac{X}{Y} \right) \right)^{-1} \left( \frac{X}{Y^2} \right)' Y \tag{3}$$

where X/Y matrix is obtained by dividing the values  $x_{ij}$  by  $y_i$ , and  $X/Y^2$  is computed by dividing the values  $x_{ij}$  by  $y_i^2$  where j = 1, 2, ..., p.

On the other hand, Jadhav and Kashid (2018) developed an estimator called RRE as an alternative to RE and LSR. Note that RRE using RE and LSR estimator is proposed to tackle the problem of outliers and multicollinearity. For the parameters  $\beta$  in Equation (1), the RRE is defined as:

$$\hat{\beta}_{RRE} = \left( \left( \frac{X}{Y} \right)' \left( \frac{X}{Y} \right) + kI \right)^{-1} \left( \frac{X}{Y^2} \right)' Y, \quad k > 0,$$
(4)

where *k* is a biasing parameter.

Let us state that the LSR and RRE given by (3) and (4) are obtained by minimization of the objective function given below:

$$S(\beta) = (1 - \underline{X}\beta) \ (1 - \underline{X}\beta) + k\beta'\beta$$
<sup>(5)</sup>

where 1 is the  $n \times 1$  dimensional matrix of 1s, <u>X</u> is obtained by dividing the values  $x_{ij}$  by  $y_i$  for j = 1, ..., p and the parameter  $k \ge 0$  controls the amount of shrinkage. Note that minimization of the objective function given by (5) with respect to the parameter vector  $\beta$  yields the LSR estimator given by (3) when k = 0 and the RRE given by (4) when k > 0.

As an alternative to the objective function (5), which yields the LSR and RRE given by (3) and (4), consider the following penalized objective function:

$$S(\beta) = \left(1 - \underline{X}\beta\right)' \left(1 - \underline{X}\beta\right) + \left(d\hat{\beta}_{LSR} - \beta\right)' \left(d\hat{\beta}_{LSR} - \beta\right), \qquad 0 < d < 1$$
(6)

where  $\hat{\beta}_{LSR}$  is the LSR estimator given in (3) and  $\underline{X}$  is obtained by dividing the values  $x_{ij}$  by  $y_i$  for j = 1, ..., p. When  $S(\beta)$  in (6) is differentiated with respect to  $\beta$ , the following equation is obtained:

$$\frac{\partial S}{\partial \beta}\Big|_{\hat{\beta}} = -2\underline{X}' + 2\underline{X}'\underline{X}\beta - 2d\hat{\beta}_{LSR} + 2\beta = 0.$$
<sup>(7)</sup>

Solving the system given in (7) with respect to  $\beta$  defines the Liu Ratio Estimator (LRE) as follows:

$$\hat{\beta}_{LRE} = \left(\underline{X}'\underline{X} + I\right)^{-1} \left(\underline{X}' + d\hat{\beta}_{LSR}\right), \qquad 0 < d < 1,$$
(8)

where d is a biasing parameter. If the estimator (8) is restated in the structure of (3) or (4), LRE is obtained as follows:

$$\hat{\beta}_{LRE} = \left( \left(\frac{X}{Y}\right)' \left(\frac{X}{Y}\right) + I \right)^{-1} \left( \left(\frac{X}{Y^2}\right)' Y + d\hat{\beta}_{LSR} \right) , \qquad 0 < d < 1$$
(9)

where X/Y matrix is obtained by dividing the values  $x_{ij}$  by  $y_i$ , and  $X/Y^2$  is computed by dividing the values  $x_{ij}$  by  $y_i^2$  where j = 1, 2, ..., p.

#### 3. THE MONTE CARLO SIMULATION STUDIES

J

In this section, the performance of LRE is compared with other existing estimators, OLS, RE, LE, LSR and RRE using two different Monte Carlo simulation designs. In the first design, we investigated the effects of sample size (*n*), the degree of the collinearity ( $\rho$ ), the number of the explanatory variables (*p*) and the variance ( $\sigma^2$ ) on the performances of the considered estimators. In the second simulation design, we examined LSR, RRE and LRE performances for each of *n*, *p*,  $\rho$  and  $\sigma^2$  values at certain values of *k* and *d*. For both simulation designs, we generate the explanatory variables by the following McDonald and Galarneau (1975) as

$$x_{ij} = \left(1 - \rho^2\right)^{1/2} u_{ij} + \rho u_{ip+1}, \quad i = 1, 2, ..., n, \quad j = 1, 2, ..., p$$
(10)

where  $u_{ij}$  are independent standard normal pseudo-random numbers.  $\rho$  is specified so that the correlation between any two variables is given by  $\rho^2$ . These variables are standardized such that X'X is a correlation matrix. Investigations are conducted on three distinct sets of correlations that correspond to  $\rho = 0.8, 0.9$  and 0.95. The response variable is generated by

$$y_i = \beta_0 + \beta_1 x_{1i} + \beta_2 x_{2i} + \dots + \beta_p x_{pi} + \varepsilon_i, \quad i = 1, 2, \dots, n$$
(11)

where  $\varepsilon_i \sim N(0, \sigma^2)$  and  $\beta_0$  is equal to zero. The values of  $\sigma^2$  are 1, 5, and 10 for various comparisons of the error term. For each set of explanatory variables, the parameter vector  $\beta$  is chosen as the normalized eigenvector corresponding to the largest eigenvalue of X'X so that  $\beta'\beta = 1$ . The sample sizes *n* are 50, 100 and 200. The number of explanatory variables is chosen as p = 4, 8, and 12.

We examine the effects of y-direction outliers on the estimators by considering three different cases such as no outlier, one outlier and two outliers. When there is no outlier, dependent variables are taken into consideration as in Equation (11). In the case of one outlier, the *n* observation is changed as y(n) = 500. For two outlier case, y(1) = 500 and y(n) = 500 altered observations are used.

In order to estimate the biasing parameters in the simulation, based on the studies of Kibria (2003) and Qasim et al. (2020), the biasing parameters for RE, LE, RRE, and LRE are taken as follows:

RE: 
$$\hat{k}_{RE} = \frac{\hat{\sigma}_{OLS}}{\left(\prod_{j=1}^{p+1} \hat{\beta}_{OLS(j)}^2\right)^{\frac{1}{p+1}}}$$
 where  $\hat{\sigma}_{OLS}^2 = \frac{\sum_{i=1}^{n} (y_i - \hat{y}_{OLS(i)})}{n-p-1}$   
LE:  $\hat{d}_{LE} = \max\left(0, \min\left(\frac{\hat{\beta}_{OLS(j)}^2 - \hat{\sigma}_{OLS}^2}{\max\left(\frac{\hat{\sigma}_{OLS}^2}{\lambda_j}\right) + \max\left(\hat{\beta}_{OLS(j)}^2\right)}\right)\right)$  where  $\lambda_j$  is the *j*th eigenvalues of  $X'X, j = 1, 2, ..., p + 1$ .  
RRE:  $\hat{k}_{RRE} = \frac{\hat{\sigma}_{LSR}^2}{\left(\prod_{j=1}^{p+1} \hat{\beta}_{LSR(j)}^2\right)^{\frac{1}{p+1}}}$  where  $\hat{\sigma}_{LSR}^2 = \frac{\sum_{i=1}^{n} (y_i - \hat{y}_{LSR(i)})^2}{n-p-1}$   
LRE:  $\hat{d}_{LRE} = \max\left(0, \min\left(\frac{\hat{\beta}_{LSR(j)}^2 - \hat{\sigma}_{LSR}^2}{\max\left(\frac{\hat{\sigma}_{LSR}^2}{\lambda_j}\right) + \max\left(\hat{\beta}_{LSR(j)}^2\right)}\right)\right)$  where  $\lambda_j$  is the *j*th eigenvalues of  $\underline{X'X}, j = 1, 2, ..., p + 1$ .

As a measure of performance we use the estimated Mean Squared Error (MSE) between the estimated parameters in the *l*-th repetition,  $\hat{\beta}^{(l)}$ , and the true parameters  $\beta$ :

$$MSE = \frac{1}{m} \sum_{l=1}^{m} \frac{1}{p} \left\| \beta - \hat{\beta}^{(l)} \right\|^2$$
(12)

where p is the number of explanatory variables. The simulation experiment is replicated m = 2000 times by generating new pseudo-random numbers. The R programming language was used to carry out the calculations. The results are given in Tables 1-3 where the lowest estimated MSE values in each row are indicated by bold.

In all 81 scenarios in Tables 1-3, the LSR, RRE and LRE outperformed other estimators according to criterion (12). With the

10 200 0.95 113.453	5 200 0.95 54.63	1 200 0.95 10.419	10 200 0.9 56.529	5 200 0.9 29.04	1 200 0.9 5.75	10 200 0.8 39.440	5 200 0.8 18.474	1 200 0.8 3.840	10 100 0.95 129.27	5 100 0.95 71.71	1 100 0.95 13.699	10 100 0.9 49.678	5 100 0.9 23.743	1 100 0.9 4.78	10 100 0.8 34.433	5 100 0.8 17.47	1 100 0.8 3.3	10 50 0.95 142.48	5 50 0.95 72.72	1 50 0.95 14.33	10 50 0.9 81.96	5 50 0.9 42.25	1 50 0.9 8.58	10 50 0.8 39.37:	5 50 0.8 18.75	1 50 0.8 3.87	$\sigma^2 n \rho$ OLS	No out	
2 38.663	6 17.793	9 3.527	9 19.381	7 10.274	7 2.24	6 14.739	4 6.78	6 1.639	2 41.231	3 23.493	9 4.709	8 17.979	3 8.541	8 1.916	8 12.756	4 6.768	4 1.471	7 46.331	7 25.501	2 4.986	4 27.041	1 14.49	5 3.144	5 14.953	5 7.000	4 1.731	S RE	lier	
23.827	10.267	1.636	10.749	5.329	0.964	8.691	3.755	0.774	24.767	14.264	2.265	9.756	4.500	0.851	7.631	3.864	0.720	28.765	15.425	2.313	14.999	7.867	1.367	8.504	3.602	0.836	LE		
2.237	1.58	1.096	1.645	1.276	1.04	1.406	1.203	1.01	3.997	2.583	1.262	2.015	1.432	1.062	1.771	1.396	1.036	6.875	4.03	1.565	4.822	3.02	1.33	2.547	1.796	1.104	LSR		
1.359	1.154	1.018	1.185	1.072	1.003	1.125	1.062	0.993	1.865	1.463	1.058	1.312	1.109	1.003	1.233	1.121	0.996	2.787	1.88	1.159	2.097	1.605	1.072	1.466	1.243	1.008	RRE		Table
1.337	1.197	1.058	1.219	1.124	1.029	1.176	1.114	1.006	1.656	1.378	1.104	1.281	1.147	1.035	1.225	1.169	1.02	2.124	1.614	1.178	1.629	1.443	1.102	1.324	1.229	1.043	LRE		1.The esti
40655.728	40580.392	40589.394	1771.988	1741.125	1723.361	7985.94	7965.217	7926.647	16270.935	16206.988	16134.448	6314.094	6287.381	6251.16	10251.047	10203.427	10198.92	110708.454	110530.006	110682.31	10387.775	10412.218	10400.479	66525.692	66755.55	66639.985	OLS	)ne outlier	mated MSE
15509.057	15466.929	15480.793	495.737	488.224	483.201	1998.333	1981.025	1957.891	1124.121	1099.17	1079.382	384.904	372.356	362.017	2176.151	2151.653	2144.602	22374.722	22269.075	22309.457	283.39	279.069	275.513	33542.163	33738.42	33649.654	RE		values of t
8562.385	8503.168	8489.903	634.393	633.732	632.332	1381.326	1363.837	1343.945	529.387	516.107	504.879	279.665	270.937	264.557	1018.585	999.082	984.846	16479.652	16397.836	16422.522	273.565	271.616	271.375	10818.309	10868.439	10840.251	LE		ne considere
2.299	1.595	1.099	1.651	1.279	1.040	1.420	1.206	1.010	4.054	2.598	1.264	2.021	1.442	1.063	1.795	1.404	1.038	7.279	4.228	1.595	4.875	3.058	1.340	2.753	1.893	1.115	LSR		d estimators
1.377	1.157	1.02	1.188	1.073	1.003	1.130	1.064	0.993	1.879	1.462	1.059	1.31	1.113	1.003	1.237	1.123	0.996	2.878	1.94	1.167	2.116	1.611	1.076	1.53	1.266	1.011	RRE		for the mod
1.346	1.199	1.06	1.221	1.125	1.029	1.18	1.115	1.006	1.663	1.378	1.104	1.28	1.151	1.036	1.228	1.171	1.021	2.203	1.646	1.181	1.637	1.444	1.104	1.345	1.242	1.045	LRE		lel when <i>p</i>
38665.172	38592.549	38599.933	14577.619	14504.736	14523.593	5435.076	5415.279	5383.217	3910.352	3838.046	3786.59	1644.439	1625.594	1603.233	505.923	496.307	480.365	25391.9	25272.394	25303.971	334751.036	335134.314	335131.132	47403.547	47585.798	47482.474	OLS	<b>Iwo outliers</b>	y = 2
8132.565	8082.718	8068.549	4691.152	4667.649	4669.841	581.752	572.762	563.529	688.784	669.735	659.29	87.799	85.726	83.091	3.628	3.431	3.225	321.936	313.56	310.034	160565.563	160891.027	160914.664	13909.209	13989.384	13934.638	RE		
3237.893	3204.612	3190.09	2204.976	2204.356	2203.649	530.902	529.15	526.902	1606.804	1598.714	1599.82	661.543	662.281	659.89	89.693	87.961	85.917	253.227	245.276	239.406	89372.943	89610.788	89564.179	6374.627	6389.664	6376.756	LE		
2.297	1.604	1.099	1.652	1.285	1.040	1.419	1.207	1.010	4.083	2.615	1.272	2.045	1.449	1.065	1.818	1.421	1.042	7.340	4.375	1.619	5.368	3.364	1.392	2.781	1.906	1.119	LSR		
1.376	1.164	1.020	1.189	1.076	1.002	1.129	1.063	0.993	1.886	1.470	1.062	1.319	1.114	1.004	1.243	1.127	0.998	2.865	1.981	1.175	2.259	1.699	1.088	1.534	1.27	1.012	RRE		
1.344	1.202	1.059	1.223	1.127	1.029	1.178	1.116	1.006	1.662	1.382	1.107	1.286	1.153	1.037	1.233	1.175	1.024	2.200	1.663	1.188	1.711	1.499	1.114	1.340	1.245	1.048	LRE		

		LRE	1.220	1.497	1.509	1.410	1.514	1.533	1.432	1.492	1.538	1.143	1.420	1.534	1.250	1.491	1.520	1.375	1.531	1.561	1.094	1.338	1.460	1.152	1.423	1.526	1.277	1.529	1.528
		RRE	1.073	1.763	2.242	1.444	3.018	5.238	1.582	4.322	6.674	1.025	1.291	1.697	1.097	1.578	2.127	1.217	2.124	3.322	1.018	1.170	1.342	1.034	1.296	1.663	1.110	1.689	2.136
		LSR	1.505	4.154	6.501	2.949	9.589	18.564	3.587	14.358	24.527	1.224	2.349	3.811	1.496	3.531	5.898	2.011	5.862	10.69	1.120	1.743	2.447	1.220	2.261	3.728	1.523	3.868	6.125
		LE	0069.709	0070.666	0074.035	5601.218	5852.306	5688.226	3624.173	3634.782	3646.722	3139.145	3137.823	3144.359	4777.114	4780.66	4792.289	4475.914	4477.368	4479.598	3735.021	3734.765	3736.432	1201.213	1201.764	1205.384	1870.807	1863.449	1854.619
		RE	8211.508 1	8214.168 1	8228.755	8378.421 10	8678.157 10	8260.815 10	2328.384	2252.271	2347.954	9956.498	9945.318	9973.805	6209.444	6197.107	6331.478	8415.657	8479.119	8419.736	7941.71	7941.875	7946.63	9553.022	9546.238	9583.597	3503.082	3546.479	3700.271
a antilana	o outliers	OLS	69474.34 1	9486.601 1	9527.885 1	1440.542 41	1857.779 41	1521.878 41	8257.454 6	378000.4 6	8210.213 6	9141.245	9114.256	9165.728	1044.994 1	1 180.1660	1333.569 1	1563.018 18	81755.21 18	1791.619 18	4028.221	4039.073	4058.517	4633.513	4615.021	4693.284	4111.006 3	4218.044 3	4527.453 3
	MT	LRE	1.217	1.492 6	1.509 6	1.406 75	1.513 75	1.530 75	1.435 37	1.489	1.534 37	1.140 4	1.417 4	1.533 4	1.243 7	1.491 7	1.519 7	1.369 38	1.529 3	1.553 38	1.093 2	1.336 2	1.461 2	1.152 4	1.421 4	1.526 4	1.276 12	1.528 12	1.530 12
		RRE	1.069	1.73	2.223	1.407	2.921	5.085	1.576	4.298	6.522	1.024	1.287	1.692	1.093	1.555	2.06	1.207	2.096	3.244	1.018	1.167	1.339	1.035	1.278	1.664	1.110	1.682	2.129
		LSR	1.490	4.051	6.405	2.821	9.110	17.662	3.548	14.122	23.951	1.218	2.325	3.773	1.473	3.422	5.654	1.973	5.726	10.369	1.118	1.731	2.433	1.219	2.225	3.721	1.521	3.841	6.078
		LE	166.68621	2921.074	2797.552	8147.935	8198.149	8228.282	1318.697	1318.486	1320.502	1109.349	1110.635	1114.098	2919.152	2924.204	2928.893	1401.182	1407.93	1427.14	257.37	260.112	263.682	956.247	981.318	1008.822	638.058	638.615	643.211
		RE	19414.94	19423.137	19429.209	123807.12	23954.815	23804.205	63099.131	62984.916	63068.59	1785.804	1790.82	1805.585	15515.865	15551.268	15562.731	29058.228	29054.883	29170.418	88.718	91.726	95.502	5544.276	5543.911	5582.191	5531.456	5580.152	5671.806
	ne outlier	OLS	44899.659	44931.556	44959.982	71966.879	272216.47 1	72119.315 1	59525.725	59308.276	59489.553	14856.18	14857.174	14892.954	49290.511	49375.88	49387.911	97667.155	97701.742	97951.323	1707.04	1740.713	1780.684	22948.371	22950.016	23038.957	35295.806	35410.954	35640.676
		LRE	1.21	1.481	1.501	1.393 2	1.515	1.542 2	1.436 2	1.497 2	1.539 2	1.138	1.416	1.532	1.238	1.488	1.520	1.364	1.529	1.550	1.092	1.336	1.461	1.151	1.419	1.525	1.276	1.528	1.531
		RRE	1.064	1.693	2.173	1.366	2.783	4.793	1.532	4.054	6.208	1.023	1.285	1.686	1.090	1.536	2.050	1.199	2.085	3.199	1.018	1.167	1.336	1.035	1.276	1.660	1.110	1.681	2.125
		LSR	1.471	3.907	6.154	2.657	8.52	16.46	3.376	13.223	22.63	1.211	2.308	3.739	1.458	3.355	5.571	1.942	5.633	10.147	1.118	1.728	2.425	1.217	2.211	3.704	1.517	3.817	6.052
		LE	0.908	4.247	8.414	0.703	3.429	6.668	0.761	3.455	6.899	006.0	4.317	8.529	0.782	3.67	7.265	0.729	3.433	6.700	0.895	4.313	8.524	0.738	3.692	7.195	0.702	3.637	6.875
	_	RE	2.658	12.939	25.567	6.951	32.634	65.53	10.103	47.601	90.852	2.682	12.628	25.239	4.531	20.61	41.436	8.287	38.539	82.078	2.668	13.247	26.201	4.537	21.798	43.559	9.17	47.719	89.211
Ma and a		OLS	8.284	42.778	85.032	22.801	110.602	223.867	33.631	163.61	319.828	8.016	40.411	80.741	14.385	69.687	140.746	27.765	135.335	279.99	8.202	42.141	84.549	14.696	73.322	147.872	31.562	162.176	314.547
		d u	50 0.8	50 0.8	50 0.8	50 0.9	50 0.9	50 0.9	50 0.95	50 0.95	50 0.95	100 0.8	100 0.8	100 0.8	100 0.9	100 0.9	100 0.9	100 0.95	100 0.95	100 0.95	200 0.8	200 0.8	200 0.8	200 0.9	200 0.9	200 0.9	200 0.95	200 0.95	200 0.95
		$\sigma_{7}^{7}$	-	S	10	Γ	S	10	-	S	0	Γ	Ś	10	-	S	10	Γ	S	10	-	5	10	Γ	Ś	10	-	5	10

**Table 2.** The estimated MSE values of the considered estimators for the model when p = 4

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inclusion of the *y*-direction outliers, the performance of the commonly used OLS, RE and LE is quite poor. On the other hand, LSR, RRE and LRE exhibited different behaviors in different scenarios. The following observations can be obtained from Tables 1-3:

1. When the number of outliers is gradually increased along with the number of variables in the model by keeping  $\rho$ , *n*, and  $\sigma^2$  constant, an increase in the estimated MSE values of all estimators is observed.

2. When *n*, *p* and  $\sigma^2$  are held constant, we observe that the estimated MSE values of LSR generally increase as the correlation between variables is increased, while the estimated MSE values of RRE and LRE remain almost constant. On the other hand, when the correlation between the variables and the outliers in the data are increased, the estimated MSE values of the LSR and RRE estimators increase. On the other hand, for *p* = 8, the estimated MSE value of LRE decreases when the model variance is large.

3. When *n*, *p* and  $\rho$  are kept constant and the variance  $\sigma^2$  is increased, the MSE values of the LSR, RRE and LRE estimators generally increase. When the model variance increases with the number of outliers, the estimated MSE values of the LSR and RRE increase. On the contrary, for *p* = 8, the estimated MSE values of LRE decrease at high correlation and small sample size.

4. When p,  $\rho$  and  $\sigma^2$  are kept constant and the number of observations in the model is increased, a decrease is observed in the estimated MSE values of all estimators. When the number of outliers and the number of variables in the model are increased, a decrease is observed in the estimated MSE values of the LSR and RRE. On the other hand, the estimated MSE values of the LRE for p = 8 show an increase at high correlation and large variance values.

As a result, we can conclude that the estimated MSE values for LSR, RRE and LRE for variables such as  $n, p, \rho$ , and  $\sigma^2$  with the change in the number of outliers are considerably lower than OLS, RE and LE.

In the second simulation scheme, we investigate the performance of LSR, RRE and LRE in the presence of y-direction outliers for each n, p,  $\rho$ , and  $\sigma^2$ . The purpose of this simulation is to investigate the performance of LSR, RRE and LRE with respect to MSE values given in (12) with various values of the biasing parameter k and d and the presence of outliers in the y-direction. The biasing parameters k and d are not estimated in the second simulation scheme. Only the MSE values obtained by increasing k and d values in the range [0, 1] by 0.1 are compared. We only consider the cases  $\rho = 0.8$ , 0.95, n = 50, 200, and p = 2, 8, and  $\sigma^2 = 1$ , 10. Depending on these n,  $\rho$ , p, and  $\sigma^2$  values, the explanatory variables are generated according to equation (10). Similar to the previous simulation scheme, we examine the effects of outliers in the y-direction on the estimators considering three different cases: no outliers, one outlier and two outliers. For every values of k and d, the simulation is run 2000 times. The results are collectively presented graphically in Figures 1-6.

Figures 1-6 clearly show the effects of varying the biasing parameter k and d between 0 and 1 on the estimated MSE values of the estimators. According to the figures, we can obtain the following results depending on each( $n, \rho, p, \sigma^2$ ).

1) The LSR estimator showed an increase in the estimated MSE values in the presence of none, one and two outliers in the *y*-direction, but generally showed a stable behavior.

2) Although the MSE values estimated for RRE decreased with increasing values of the biasing parameter k, it did not affect the MSE values estimated from the outliers in the *y*-direction.

3) Although the MSE values estimated for LRE increased with increasing values of the biasing parameter d, it did not affect the MSE values estimated from the outliers in the y-direction.

As a result, no dramatic change is observed in the MSE values estimated by comparing LSR, RRE and LSR among themselves as OLS, RE and LE. On the other hand, for large values of the biasing parameter k, RRE and for small values of the biasing parameter d, LRE stand out due to their performance.

#### 4. AN EMPIRICAL APPLICATION

In this section, we created an experimental dataset to study the performance of LSR, RRE and LRE. To do this, we created a dataset using Equation (10) with n = 100, p = 4 and  $\rho = 0.95$ . We used set.seed(4) in the R Program. Using equation (11) to create the response variable with  $\sigma^2 = 5$ . Modified observations y(1) = 500 and y(n) = 500 were used to create two outliers. In this case, the eigenvalues of the X'X matrix were calculated as 100.000, 3.738, 0.106, 0.092, and 0.064. The condition number is approximately 39.410, therefore the matrix X is moderate ill-conditioned. The eigenvalues of the  $\underline{X'X}$  matrix were calculated as 164.869, 5.437, 0.122, 0.077, and 0.060. The condition number is approximately 52.593, therefore the matrix  $\underline{X}$  is moderate ill-conditioned. The numerical results are summarized in Table 4.

From Table 4, it can be observed that the estimated MSE values of LSR, RRE, and LRE give smaller values compared to OLS, RE, and LE. As a result, RRE and LRE outperform LSR in the presence of multicollinearity and *y*-direction outliers. It also seems that LRE can be a strong alternative to RRE.



Figure 1.The estimated MSE values of LSR, RRE and LRE as a function k and d where p = 2 with no outlier

	$\hat{eta}_0$	$\hat{eta}_1$	$\hat{eta}_2$	$\hat{eta}_3$	$\hat{eta}_4$	$MSE(\hat{\beta})$
$\hat{\beta}_{OLS}$	11.0549	59.8429	455.3388	26.2779	-451.0035	83022.074
$\hat{\beta}_{RE} \left( \hat{k}_{RE} = 0.7087 \right)$	10.9771	14.8855	67.4696	22.2895	-30.0934	1255.141
$\hat{\beta}_{LE} \left( \hat{d}_{LE} = 0 \right)$	10.9454	14.598	53.2606	20.1941	-18.1441	777.143
$\hat{\beta}_{LSR}$	0.1297	6.8485	-4.443	-5.1036	1.8292	19.359
$\hat{\beta}_{RRE} \left( \hat{k}_{RRE} = 0.2234 \right)$	) 0.1239	1.2467	-1.202	-1.4109	0.6017	1.224
$\hat{\beta}_{LRE} \left( \hat{d}_{LRE} = 0 \right)$	0.1253	0.2183	-0.439	-0.5042	0.0808	0.253

Table 4.The estimated parameter values and the estimated MSE values of the estimators



Figure 2. The estimated MSE values of LSR, RRE and LRE as a function k and d where p = 8 with no outlier



Figure 3.The estimated MSE values of LSR, RRE and LRE as a function k and d where p = 2 with one outlier



Figure 4.The estimated MSE values of LSR, RRE and LRE as a function k and d where p = 8 with one outlier



Figure 5.The estimated MSE values of LSR, RRE and LRE as a function k and d where p = 2 with two outliers



Figure 6. The estimated MSE values of LSR, RRE and LRE as a function k and d where p = 8 with two outliers

#### 5. CONCLUSION

In this article, we proposed a new estimator named the LRE as an alternative to LSR and RRE in the presence of multicollinearity and y-direction outliers. Two separate Monte Carlo simulation study are conducted to examine the performance of LRE. In the first simulation study, we compared the considered estimators together with the estimates of the biasing parameters k and d. When the y-direction outliers are taken into account, the performance of OLS, RE and LE is considerably poor, while the performance of LSR, RRE and LRE is more stable. In the second simulation study, the performance of LSR, RRE and LRE are analyzed by choosing k and d values as fixed and equally spaced. According to the simulation results, LRE performs better for small values of d and RRE performs better for large values of k. According to the simulation results and the analysis of synthetic data, we recommend LRE as an alternative to RRE in the presence of y-direction outliers and multicollinearity between variables.

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