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## Pseudoparallel invariant submanifolds of Kenmotsu manifolds

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**Abstract** — In this paper, we consider pseudoparallel invariant submanifolds, a particular class of invariant submanifolds of Kenmotsu manifolds, on  $W_8$  curvature tensor and investigate some of their basic characterizations, such as  $W_8$  pseudoparallel,  $W_8$ -2 pseudoparallel,  $W_8$ -Ricci generalized pseudoparallel, and  $W_8$ -2 Ricci generalized pseudoparallel. Moreover, we present some relations between these pseudoparallel invariant submanifolds and semi-parallel invariant submanifolds. We finally discuss the need for further research.

**Keywords:** *Kenmotsu manifold, pseudoparallel invariant submanifold, 2-pseudoparallel invariant submanifolds*

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### 1. Introduction

In 1972, Kenmotsu [1] studied a class of contact Riemannian manifolds and called them Kenmotsu manifolds. He proved that if a Kenmotsu manifold satisfies the condition  $R(a_1, a_2) \cdot R = 0$ , then the manifold has negative curvature  $-1$ , where  $R$  is the Riemannian curvature tensor of (1,3)-type and  $R(a_1, a_2)$  denotes the derivation of the tensor algebra at each point of the tangent space. Then, the properties of Kenmotsu manifolds have been studied by several authors, such as Haseeb [2], Wang and Liu [3], Wang and Wang [4], Özgür and De [5], Tripathi and Gupta [6], Singh et al. [7], Parakasha and Hadimani [8], De and De [9], and De and Pathak [10]. Afterward, the geometry of submanifolds has been examined on different manifolds, and many essential properties have been obtained [11–13].

The curvature tensor is one of the most important concepts used to learn the characterization of a manifold. The properties of manifolds, important for mathematics, physics, and engineering, are handled with the help of curvature tensors. One of the essential geometrical manifolds is the Kenmotsu manifolds. Kenmotsu manifolds are one-dimensional versions of complex manifolds. If an almost contact metric manifold satisfies the condition

$$(\nabla_{a_1} \varphi)a_2 = g(\varphi a_1, a_2)\xi - \eta(a_2)\varphi a_1$$

Then, the manifold is called a Kenmotsu manifold.

In this article, pseudoparallel invariant submanifolds for Kenmotsu manifolds are investigated. The Kenmotsu manifold is considered on the  $W_8$ -curvature tensor. Submanifolds of these manifolds with properties, such as  $W_8$ -pseudoparallel,  $W_8$ -2 pseudoparallel,  $W_8$ -Ricci generalized pseudoparallel, and  $W_8$ -2 Ricci generalized pseudoparallel has been investigated.

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## 2. Preliminaries

This section provides some basic properties to be required in the following sections. Let  $M$  be a  $(2n + 1)$ -dimensional differentiable manifold. If it admits a tensor field  $\varphi$  of type  $(1,1)$ , a vector field  $\xi$ , and a 1-form  $\eta$  satisfying the following conditions:

$$\varphi^2 a_1 = -a_1 + \eta(a_1)\xi \text{ and } \eta(\xi) = 1 \tag{2.1}$$

for all  $a_1, a_2, \xi \in \chi(M)$ , then  $(\varphi, \xi, \eta)$  is called almost contact structure and  $(M, \varphi, \xi, \eta)$  is called almost contact manifold. If there is a  $g$  metric on the  $(2n + 1)$ -dimensional, almost contact manifold satisfying

$$g(a_1, \xi) = \eta(a_1) \tag{2.2}$$

and

$$g(\varphi a_1, \varphi a_2) = g(a_1, a_2) - \eta(a_1)\eta(a_2) \tag{2.3}$$

for all  $a_1, a_2 \in \chi(M)$ , then  $(\varphi, \xi, \eta, g)$  is called an almost contact metric structure and  $(M, \varphi, \xi, \eta, g)$  is called an almost contact metric manifold.

On a  $(2n + 1)$ -dimensional manifold  $M$ , we have

$$g(\varphi a_1, a_2) = -g(a_1, \varphi a_2)$$

for all  $a_1, a_2 \in \chi(M)$ , that is,  $\varphi$  is an anti-symmetric tensor field according to the  $g$  metric. The transformation  $\Phi$  defined as

$$\Phi(a_1, a_2) = g(a_1, \varphi a_2)$$

for all  $a_1, a_2 \in \chi(M)$ , is called the fundamental 2-form of the  $(\varphi, \xi, \eta, g)$  almost contact metric structure where

$$\eta \wedge \Phi^n \neq 0$$

Let  $M$  be a  $(2n + 1)$ -dimensional almost contact metric manifold given the structure  $(\varphi, \xi, \eta, g)$ . If  $d\eta = 0$  and  $d\Phi = 2\eta \wedge \Phi$  on an almost contact metric manifold  $M$ , then  $M$  is called an almost Kenmotsu manifold.

Let  $M$  be  $(2n + 1)$ -dimensional almost contact metric manifold providing the structure  $(\varphi, \xi, \eta, g)$ . If it satisfies the following conditions:

$$\begin{cases} \varphi^2 a_1 = -a_1 + \eta(a_1)\xi, \varphi\xi = 0 \\ \eta(\varphi a_1) = 0, \eta(a_1) = g(a_1, \xi)\eta(\xi) = 1 \\ (\nabla_{a_1}\varphi)a_2 = g(\varphi a_1, a_2)\xi - \eta(a_2)\varphi a_1 \end{cases} \tag{2.4}$$

for all  $a_1, a_2, \xi \in \chi(M)$ , then  $M$  is called the Kenmotsu manifold.

**Lemma 2.1.** [1] Let  $M$  be a  $(2n + 1)$ -dimensional Kenmotsu manifold. In this case, the following equations are obtained.

$$\nabla_{a_1}\xi = -a_1 + \eta(a_1)\xi \tag{2.5}$$

$$(\nabla_{a_1}\eta)a_2 = g(a_1, a_2) - \eta(a_1)\eta(a_2) \tag{2.6}$$

$$R(a_1, a_2)\xi = \eta(a_1)a_2 - \eta(a_2)a_1 \tag{2.7}$$



$$R(\xi, a_1)a_2 = -g(a_1, a_2)\xi + \eta(a_2)a_1 \tag{2.8}$$

$$R(a_1, \xi)a_2 = g(a_1, a_2)\xi - \eta(a_2)a_1 \tag{2.9}$$

$$S(a_1, \xi) = -2n\eta(a_1) \tag{2.10}$$

and

$$Q\xi = -2n\xi \tag{2.11}$$

where  $\nabla, R, S,$  and  $Q$  are Levi-Civita connections on  $M,$  Riemann tensor, Ricci tensor, and Ricci operator, respectively.

**Definition 2.2.** [6] Let  $M$  be a  $(2n + 1)$ -dimensional semi-Riemannian manifold. Then, the  $W_8$ -curvature tensor is defined as

$$W_8(a_1, a_2)a_3 = R(a_1, a_2)a_3 - \frac{1}{2n}[S(a_2, a_3)a_1 - S(a_1, a_3)a_2] \tag{2.12}$$

for all  $a_1, a_2, a_3 \in \chi(M).$

If we choose  $a_1 = \xi, a_2 = \xi,$  and  $a_3 = \xi$  in (2.12) for  $(2n + 1)$ -dimensional Kenmotsu manifold respectively, we get

$$W_8(\xi, a_2)a_3 = -g(a_2, a_3)\xi + \eta(a_3)a_2 - \eta(a_2)a_3 - \frac{1}{2n}S(a_2, a_3)\xi \tag{2.13}$$

$$W_8(a_1, \xi)a_3 = g(a_1, a_3)\xi - \eta(a_1)a_3 \tag{2.14}$$

and

$$W_8(a_1, a_2)\xi = \eta(a_1)a_2 + \frac{1}{2n}S(a_1, a_2)\xi \tag{2.15}$$

Let  $\tilde{M}$  be immersed submanifold of a Kenmotsu manifold  $M(\phi, \xi, \eta, g).$  Moreover, let the tangent and normal subspaces of  $\tilde{M}$  in  $M(\phi, \xi, \eta, g)$  be  $\Gamma(T\tilde{M})$  and  $\Gamma(T^\perp\tilde{M}),$  respectively. Then, Gauss and Weingarten formulas for  $\Gamma(T\tilde{M})$  and  $\Gamma(T^\perp\tilde{M})$  are

$$\nabla_{a_1} a_2 = \tilde{\nabla}_{a_1} a_2 + \sigma(a_1, a_2) \tag{2.16}$$

and

$$\nabla_{a_1} a_5 = -A_{a_5}a_1 + \tilde{\nabla}_{a_1}^\perp a_5 \tag{2.17}$$

respectively, for all  $a_1, a_2 \in \Gamma(T\tilde{M})$  and  $a_5 \in \Gamma(T^\perp\tilde{M}),$  where  $\tilde{\nabla}$  and  $\tilde{\nabla}^\perp$  are the connections on  $\tilde{M}$  and  $\Gamma(T^\perp\tilde{M}),$  respectively,  $\sigma$  and  $A$  are the second fundamental form and the shape operator of  $\tilde{M}.$  There is a relation

$$g(A_{a_5}a_1, a_2) = g(\sigma(a_1, a_2), a_5)$$

between the second basic form and shape operator defined as above. The covariant derivative of the second fundamental form  $\sigma$  is defined as

$$(\nabla_{a_1}\sigma)(a_2, a_3) = \tilde{\nabla}_{a_1}^\perp \sigma(a_2, a_3) - \sigma(\tilde{\nabla}_{a_1} a_2, a_3) - \sigma(a_2, \tilde{\nabla}_{a_1} a_3) \tag{2.18}$$

Specifically, if  $\nabla\sigma = 0,$   $\tilde{M}$  is said to be a parallel second fundamental form.

Let  $\tilde{R}$  be Riemann curvature tensor of  $\tilde{M}$ . In this case, the Gauss equation can be expressed as

$$R(a_1, a_2)a_3 = \tilde{R}(a_1, a_2)a_3 + A_{\sigma(a_1, a_3)}a_2 - A_{\sigma(a_2, a_3)}a_1 + (\nabla_{a_1}\sigma)(a_2, a_3) - (\nabla_{a_2}\sigma)(a_1, a_3)$$

for all  $a_1, a_2, a_3 \in \Gamma(T\tilde{M})$ , where

$$(\tilde{\nabla}_{a_1}\sigma)(a_2, a_3) - (\tilde{\nabla}_{a_2}\sigma)(a_1, a_3) = 0$$

then it is called a curvature-invariant submanifold. Let  $\tilde{M}$  be a Riemannian manifold,  $T$  be  $(0, k)$ -type tensor field and  $A$  be  $(0, 2)$ -type tensor field. In this case, Tachibana tensor field  $Q(A, T)$  is defined as

$$Q(A, T)(X_1, \dots, X_k; a_1, a_2) = -T((a_1 \wedge_A a_2)X_1, \dots, X_k) - \dots - T(X_1, \dots, X_{k-1}, (a_1 \wedge_A a_2)X_k) \quad (2.19)$$

where

$$(a_1 \wedge_A a_2)a_3 = A(a_2, a_3)a_1 - A(a_1, a_3)a_2, k \geq 1, X_1, X_2, \dots, X_k, a_1, a_2 \in \Gamma(T\tilde{M}) \quad (2.20)$$

**Definition 2.3.** [5] A submanifold of a Riemannian manifold  $(M, g)$  is said to be pseudoparallel, 2-pseudoparallel, Ricci-generalized pseudoparallel, and 2-Ricci generalized pseudoparallel if

$$R \cdot \sigma \text{ and } Q(g, \sigma)$$

$$R \cdot \nabla\sigma \text{ and } Q(g, \nabla\sigma)$$

$$R \cdot \sigma \text{ and } Q(S, \sigma)$$

$$R \cdot \nabla\sigma \text{ and } Q(S, \nabla\sigma)$$

are linearly dependent, respectively.

### 3. Pseudoparallel Invariant Submanifolds of Kenmotsu Manifold

Let  $\tilde{M}$  be the immersed submanifold of a  $(2n + 1)$ -dimensional Kenmotsu manifold  $M(\phi, \xi, \eta, g)$ . If  $\phi(T_{a_1}M) \subset T_{a_1}M$  in every  $a_1$  point, the  $\tilde{M}$  manifold is called an invariant submanifold. We note that all of the properties of an invariant submanifold inherit the ambient manifold. Throughout this paper, let  $\tilde{M}$  be an invariant submanifold of the Kenmotsu manifold  $M(\phi, \xi, \eta, g)$ . Therefore, for all  $a_1, a_2 \in \Gamma(T\tilde{M})$ ,

$$\sigma(\phi a_1, a_2) = \sigma(a_1, \phi a_2) = \phi\sigma(a_1, a_2) \quad (3.1)$$

and

$$\sigma(a_1, \xi) = 0 \quad (3.2)$$

**Lemma 3.1.** Let  $\tilde{M}$  be the invariant submanifold of the  $(2n + 1)$ -dimensional Kenmotsu manifold  $M(\phi, \xi, \eta, g)$ . The second fundamental form  $\sigma$  of  $\tilde{M}$  is parallel if and only if  $\tilde{M}$  is the total geodesic submanifold.

Consider the invariant submanifolds of the Kenmotsu manifold on the  $W_8$ -curvature tensor.

**Definition 3.2.** Let  $\tilde{M}$  be the invariant submanifold of the  $(2n + 1)$ -dimensional Kenmotsu manifold  $M(\phi, \xi, \eta, g)$ . If  $W_8 \cdot \sigma$  and  $Q(g, \sigma)$  are linearly dependent,  $\tilde{M}$  is called  $W_8$ -pseudoparallel submanifold.

In this mean, it can be said that there is a function  $k_1$  on the set  $M_1 = \{x \in \tilde{M} \mid \sigma(x) \neq g(x)\}$  such that

$$W_8 \cdot \sigma = k_1 Q(g, \sigma)$$

If  $k_1 = 0$  specifically,  $\tilde{M}$  is called a  $W_8$ -semi-parallel submanifold.

**Theorem 3.3.** Let  $\tilde{M}$  be an invariant submanifold of a  $(2n + 1)$ -dimensional Kenmotsu manifold  $M(\phi, \xi, \eta, g)$ . If  $\tilde{M}$  is  $W_8$ -pseudoparallel submanifold, then  $\tilde{M}$  is either a total geodesic or  $k_1 = -1$ .

**Proof.**

Assume that  $\tilde{M}$  is a  $W_8$ -pseudoparallel submanifold. Thus, for all  $a_1, a_2, a_4, a_5 \in \Gamma(T\tilde{M})$ ,

$$(W_8(a_1, a_2) \cdot \sigma)(a_4, a_5) = k_1 Q(g, \sigma)(a_4, a_5; a_1, a_2) \tag{3.3}$$

From (3.3), it is clear that

$$R^\perp(a_1, a_2)\sigma(a_4, a_5) - \sigma(W_8(a_1, a_2)a_4, a_5) - \sigma(a_4, W_8(a_1, a_2)a_5) = -k_1 \{ \sigma((a_1 \wedge_g a_2)a_4, a_5) + \sigma(a_4, (a_1 \wedge_g a_2)a_5) \}$$

That is, we can write

$$\begin{aligned} R^\perp(a_1, a_2)\sigma(a_4, a_5) - \sigma(W_8(a_1, a_2)a_4, a_5) - \sigma(a_4, W_8(a_1, a_2)a_5) = \\ -k_1 \{ g(a_2, a_4)\sigma(a_1, a_5) - g(a_1, a_4)\sigma(a_2, a_5) + g(a_2, a_5)\sigma(a_4, a_1) - g(a_1, a_5)\sigma(a_4, a_2) \} \end{aligned} \tag{3.4}$$

If we choose  $a_5 = \xi$  in (3.4) and make use of (2.15) and (3.2), then

$$\eta(a_1)\sigma(a_4, a_2) = k_1 [\eta(a_2)\sigma(a_4, a_1) - \eta(a_1)\sigma(a_4, a_2)] \tag{3.5}$$

If we choose  $a_1 = \xi$  in (3.5), we obtain

$$(k_1 + 1)\sigma(a_4, a_2) = 0$$

□

**Corollary 3.4.** Let  $\tilde{M}$  be an pseudoparallel invariant submanifold of a  $(2n + 1)$ -dimensional Kenmotsu manifold  $M(\phi, \xi, \eta, g)$ . Then,  $\tilde{M}$  is  $W_8$ -semi-parallel if and only if  $\tilde{M}$  is totally geodesic.

**Definition 3.5.** Let  $\tilde{M}$  be the invariant submanifold of a  $(2n + 1)$ -dimensional Kenmotsu manifold  $M(\phi, \xi, \eta, g)$ . If  $W_8 \cdot \nabla\sigma$  and  $Q(g, \nabla\sigma)$  are linearly dependent, then  $\tilde{M}$  is called  $W_8$ -2 pseudoparallel submanifold.

In this case, there is a function  $k_2$  on the set  $M_2 = \{x \in \tilde{M} \mid \nabla\sigma(x) \neq g(x)\}$  such that

$$W_8 \cdot \nabla\sigma = k_2 Q(g, \nabla\sigma)$$

If  $k_2 = 0$  specifically,  $\tilde{M}$  is called a  $W_8$ -2 semiparallel submanifold.

**Theorem 3.6.** Let  $\tilde{M}$  be an invariant submanifold of a  $(2n + 1)$ -dimensional Kenmotsu manifold  $M(\phi, \xi, \eta, g)$ . If  $\tilde{M}$  is  $W_8$ -2 pseudoparallel submanifold, then  $\tilde{M}$  is either a total geodesic submanifold or  $k_2 = -1$ .

**Proof.**

Assume that  $\tilde{M}$  is a  $W_8$ -2 pseudoparallel submanifold. Therefore,

$$(W_8(a_1, a_2) \cdot \nabla\sigma)(a_4, a_5, a_3) = k_2 Q(g, \nabla\sigma)(a_4, a_5, a_3; a_1, a_2) \tag{3.6}$$

for all  $a_1, a_2, a_4, a_5, a_3 \in \Gamma(T\tilde{M})$ . If we choose  $a_1 = a_3 = \xi$  in (3.6), then

$$R^\perp(\xi, a_2)(\nabla_{a_4}\sigma)(a_5, \xi) - (\nabla_{W_8(\xi, a_2)a_4}\sigma)(a_5, \xi) - (\nabla_{a_4}\sigma)(W_8(\xi, a_2)a_5, \xi) - (\nabla_{a_4}\sigma)(a_5, W_8(\xi, a_2)\xi) = -k_2 \left\{ (\nabla_{(\xi \wedge_g a_2)a_4}\sigma)(a_5, \xi) + (\nabla_{a_4}\sigma)((\xi \wedge_g a_2)a_5, \xi) + (\nabla_{a_4}\sigma)(a_5, (\xi \wedge_g a_2)\xi) \right\} \tag{3.7}$$

Calculate all the expressions in (3.7). Thus, by using (2.18) and taking into account Lemma 3.1, we can write

$$\begin{aligned} R^\perp(\xi, a_2)(\nabla_{a_4}\sigma)(a_5, \xi) &= R^\perp(\xi, a_2) \left\{ \tilde{\nabla}_{a_4}^\perp \sigma(a_5, \xi) - \sigma(\tilde{\nabla}_{a_4} a_5, \xi) - \sigma(a_5, \tilde{\nabla}_{a_4} \xi) \right\} \\ &= -R^\perp(\xi, a_2)\sigma(a_5, -a_4 + \eta(a_4)\xi) \\ &= R^\perp(\xi, a_2)\sigma(a_5, a_4) \end{aligned} \tag{3.8}$$

secondly,

$$\begin{aligned} (\nabla_{W_8(\xi, a_2)a_4}\sigma)(a_5, \xi) &= \tilde{\nabla}_{W_8(\xi, a_2)a_4}^\perp \sigma(a_5, \xi) - \sigma(\tilde{\nabla}_{W_8(\xi, a_2)a_4} a_5, \xi) - \sigma(a_5, \tilde{\nabla}_{W_8(\xi, a_2)a_4} \xi) \\ &= -\sigma(a_5, -W_8(\xi, a_2)a_4 + \eta(W_8(\xi, a_2)a_4)\xi) \\ &= \eta(a_4)\sigma(a_5, a_2) - \eta(a_2)\sigma(a_5, a_4) \end{aligned} \tag{3.9}$$

Moreover,

$$\begin{aligned} (\nabla_{a_4}\sigma)(W_8(\xi, a_2)a_5, \xi) &= \tilde{\nabla}_{a_4}^\perp \sigma(W_8(\xi, a_2)a_5, \xi) - \sigma(\tilde{\nabla}_{a_4} W_8(\xi, a_2)a_5, \xi) - \sigma(W_8(\xi, a_2)a_5, \tilde{\nabla}_{a_4} \xi) \\ &= -\sigma\left(-g(a_2, a_5)\xi + \eta(a_5)a_2 - \eta(a_2)a_5 - \frac{1}{2n}S(a_2, a_5)\xi, -a_4 + \eta(a_4)\xi\right) \\ &= \eta(a_5)\sigma(a_2, a_4) - \eta(a_2)\sigma(a_5, a_4) \end{aligned} \tag{3.10}$$

$$\begin{aligned} (\nabla_{a_4}\sigma)(a_5, W_8(\xi, a_2)\xi) &= (\nabla_{a_4}\sigma)(a_5, a_2 - \eta(a_2)\xi) \\ &= (\nabla_{a_4}\sigma)(a_5, a_2) - (\nabla_{a_4}\sigma)(a_5, \eta(a_2)\xi) \\ &= (\nabla_{a_4}\sigma)(a_5, a_2) - \tilde{\nabla}_{a_4}^\perp \sigma(a_5, \eta(a_2)\xi) + \sigma(\tilde{\nabla}_{a_4} a_5, \eta(a_2)\xi) + \sigma(a_5, \tilde{\nabla}_{a_4} \eta(a_2)\xi) \\ &= (\nabla_{a_4}\sigma)(a_5, a_2) - \eta(a_2)\sigma(a_5, a_4) \end{aligned} \tag{3.11}$$

$$\begin{aligned} (\nabla_{(\xi \wedge_g a_2)a_4}\sigma)(a_5, \xi) &= \tilde{\nabla}_{(\xi \wedge_g a_2)a_4}^\perp \sigma(a_5, \xi) - \sigma(\tilde{\nabla}_{(\xi \wedge_g a_2)a_4} a_5, \xi) - \sigma(a_5, \tilde{\nabla}_{(\xi \wedge_g a_2)a_4} \xi) \\ &= -\eta(a_4)\sigma(a_5, a_2) \end{aligned} \tag{3.12}$$

$$\begin{aligned} (\nabla_{a_4}\sigma)((\xi \wedge_g a_2)a_5, \xi) &= \tilde{\nabla}_{a_4}^\perp \sigma((\xi \wedge_g a_2)a_5, \xi) - \sigma(\tilde{\nabla}_{a_4} (\xi \wedge_g a_2)a_5, \xi) - \sigma((\xi \wedge_g a_2)a_5, \tilde{\nabla}_{a_4} \xi) \\ &= -\sigma(g(a_2, a_5)\xi - g(\xi, a_5)a_2, -a_4 + \eta(a_4)\xi) \\ &= -\eta(a_5)\sigma(a_2, a_4) \end{aligned} \tag{3.13}$$

and

$$\begin{aligned} (\nabla_{a_4}\sigma)(a_5, (\xi \wedge_g a_2)\xi) &= (\nabla_{a_4}\sigma)(a_5, \eta(a_2)\xi - a_2) \\ &= (\nabla_{a_4}\sigma)(a_5, \eta(a_2)\xi) - (\nabla_{a_4}\sigma)(a_5, a_2) \\ &= \eta(a_2)\sigma(a_5, a_4) - (\nabla_{a_4}\sigma)(a_5, a_2) \end{aligned} \tag{3.14}$$

If we substitute (3.8)-(3.14) in (3.7), we have

$$R^\perp(\xi, a_2)\sigma(a_5, a_4) - \eta(a_4)\sigma(a_5, a_2) - \eta(a_5)\sigma(a_2, a_4) + 3\eta(a_2)\sigma(a_5, a_4) - (\nabla_{a_4}\sigma)(a_5, a_2) = -k_2\{-\eta(a_5)\sigma(a_4, a_2) - \eta(a_4)\sigma(a_2, a_5) + \eta(a_2)\sigma(a_5, a_4) - (\nabla_{a_4}\sigma)(a_5, a_2)\} \tag{3.15}$$

If we choose  $a_5 = \xi$  in (3.5) and use,

$$(\nabla_{a_4}\sigma)(\xi, a_2) = \sigma(a_4, a_2)$$

we get

$$[k_2 + 1]\sigma(a_2, a_4) = 0$$

which proves the assertions. □

**Corollary 3.7.** Let  $\tilde{M}$  be an invariant pseudoparallel submanifold of a  $(2n + 1)$ -dimensional Kenmotsu manifold  $M(\phi, \xi, \eta, g)$ . Then,  $\tilde{M}$  is  $W_8$ -2 semi-parallel if and only if  $\tilde{M}$  is totally geodesic.

**Definition 3.8.** Let  $\tilde{M}$  be the invariant submanifold of a  $(2n + 1)$ -dimensional Kenmotsu manifold  $M(\phi, \xi, \eta, g)$ . If  $W_8 \cdot \sigma$  and  $Q(S, \sigma)$  are linearly dependent,  $\tilde{M}$  is called  $W_8$ -Ricci generalized pseudoparallel submanifold.

In this case, there is a function  $k_3$  on the set  $M_3 = \{x \in \tilde{M} \mid \sigma(x) \neq S(x)\}$  such that

$$W_8 \cdot \sigma = k_3 Q(S, \sigma)$$

If  $k_3 = 0$  specifically,  $\tilde{M}$  is called a  $W_8$ -Ricci generalized semiparallel submanifold.

**Theorem 3.9.** Let  $\tilde{M}$  be the invariant submanifold of a  $(2n + 1)$ -dimensional Kenmotsu manifold  $M(\phi, \xi, \eta, g)$ . If  $\tilde{M}$  is  $W_8$ -Ricci generalized pseudoparallel submanifold, then  $\tilde{M}$  is either a total geodesic or  $k_3 = \frac{1}{2n}$ .

**Proof.**

Assume that  $\tilde{M}$  is a  $W_8$ -Ricci generalized pseudoparallel submanifold. Therefore, we have

$$(W_8(a_1, a_2) \cdot \sigma)(a_4, a_5) = k_3 Q(S, \sigma)(a_4, a_5; a_1, a_2)$$

that is

$$R^\perp(a_1, a_2)\sigma(a_4, a_5) - \sigma(W_8(a_1, a_2)a_4, a_5) - \sigma(a_4, W_8(a_1, a_2)a_5) = -k_3\{\sigma((a_1 \wedge_S a_2)a_4, a_5) + \sigma(a_4, (a_1 \wedge_S a_2)a_5)\} \tag{3.16}$$

for all  $a_1, a_2, a_4, a_5 \in \Gamma(T\tilde{M})$ . If we choose  $a_1 = a_5 = \xi$  in (3.6), we get

$$-\sigma(a_4, W_8(\xi, a_2)\xi) = k_3 S(\xi, \xi)\sigma(a_4, a_2) \tag{3.17}$$

If we use (2.10) and (2.15) in (3.7), we have

$$(1 - 2nk_3)\sigma(a_4, a_2) = 0$$

□

**Corollary 3.10.** Let  $\tilde{M}$  be an invariant pseudoparallel submanifold of a  $(2n + 1)$ -dimensional Kenmotsu manifold  $M(\phi, \xi, \eta, g)$ . Then,  $\tilde{M}$  is  $W_8$ -Ricci generalized semi-parallel if and only if  $\tilde{M}$  is totally geodesic.

**Definition 3.11.** Let  $\tilde{M}$  be an invariant pseudoparallel submanifold of a  $(2n + 1)$ -dimensional Kenmotsu manifold  $M(\phi, \xi, \eta, g)$ . If  $W_8 \cdot \tilde{\nabla} \sigma$  and  $Q(S, \tilde{\nabla} \sigma)$  are linearly dependent,  $\tilde{M}$  is called  $W_8$ -2 Ricci generalized pseudoparallel submanifold.

Then, there is a function  $k_4$  on the set  $M_4 = \{x \in \tilde{M} \mid \nabla \sigma(x) \neq S(x)\}$  such that

$$W_8 \cdot \nabla \sigma = k_4 Q(S, \nabla \sigma)$$

If specifically,  $k_4 = 0$ ,  $M$  is called a  $W_8$ -2 Ricci generalized semiparallel submanifold.

**Theorem 3.12.** Let  $\tilde{M}$  be an invariant pseudoparallel submanifold of a  $(2n + 1)$ -dimensional Kenmotsu manifold  $M(\phi, \xi, \eta, g)$ . If  $\tilde{M}$  is  $W_8$ -2 Ricci generalized pseudoparallel submanifold, then  $\tilde{M}$  is either a total geodesic or  $k_4 = \frac{1}{2n}$ .

**Proof.**

Assume that  $\tilde{M}$  is a  $W_8$ -2 Ricci generalized pseudoparallel submanifold. Thus, we can write

$$(W_8(a_1, a_2) \cdot \nabla \sigma)(a_4, a_5, a_3) = k_4 Q(S, \nabla \sigma)(a_4, a_5, a_3; a_1, a_2) \tag{3.18}$$

for all  $a_1, a_2, a_4, a_5, a_3 \in \Gamma(T\tilde{M})$ . If we choose  $a_1 = a_5 = \xi$  in (3.18), we can write

$$\begin{aligned} R^\perp(\xi, a_2)(\nabla_{a_4} \sigma)(\xi, a_3) - (\nabla_{W_8(\xi, a_2)a_4} \sigma)(\xi, a_3) - (\nabla_{a_4} \sigma)(W_8(\xi, a_2)\xi, a_3) - (\nabla_{a_4} h)(\xi, W_8(\xi, a_2)a_3) \\ = -k_4 \{ (\nabla_{(\xi \wedge_S a_2)a_4} \sigma)(\xi, a_3) + (\nabla_{a_4} \sigma)((\xi \wedge_S a_2)\xi, a_3) + (\tilde{\nabla}_{a_4} \sigma)(\xi, (\xi \wedge_S a_2)a_3) \} \end{aligned} \tag{3.19}$$

Calculate all the expressions in (3.9). Firstly, making use of (2.18), (3.1), and Lemma 3.1, we can write

$$\begin{aligned} R^\perp(\xi, a_2)(\nabla_{a_4} \sigma)(\xi, a_3) &= R^\perp(\xi, a_2) \{ \tilde{\nabla}_{a_4}^\perp \sigma(\xi, a_3) - \sigma(\tilde{\nabla}_{a_4} a_3, \xi) - \sigma(a_3, \tilde{\nabla}_{a_4} \xi) \} \\ &= R^\perp(\xi, a_2) \sigma(a_3, a_4) \end{aligned} \tag{3.20}$$

For the same reason, we can write

$$\begin{aligned} (\nabla_{W_8(\xi, a_2)a_4} \sigma)(\xi, a_3) &= \tilde{\nabla}_{W_8(\xi, a_2)a_4}^\perp \sigma(\xi, a_3) - \sigma(\tilde{\nabla}_{W_8(\xi, a_2)a_4} \xi, a_3) - \sigma(\xi, \tilde{\nabla}_{W_8(\xi, a_2)a_4} a_3) \\ &= \eta(a_4) \sigma(a_2, a_3) - \eta(a_2) \sigma(a_3, a_4) \end{aligned} \tag{3.21}$$

$$\begin{aligned} (\nabla_{a_4} \sigma)(W_8(\xi, a_2)\xi, a_3) &= (\nabla_{a_4} \sigma)(a_2 + \eta(a_2)\xi, a_3) \\ &= (\nabla_{a_4} \sigma)(a_2, a_3) - \eta(a_2) \sigma(a_4, a_3) \end{aligned} \tag{3.22}$$

$$\begin{aligned} (\nabla_{a_4} \sigma)(\xi, W_8(\xi, a_2)a_3) &= \tilde{\nabla}_{a_4}^\perp \sigma(\xi, W_8(\xi, a_2)a_3) - \sigma(\tilde{\nabla}_{a_4} \xi, W_8(\xi, a_2)a_3) - \sigma(\xi, \tilde{\nabla}_{a_4} W_8(\xi, a_2)a_3) \\ &= \eta(a_3) \sigma(a_4, a_2) - \eta(a_2) \sigma(a_3, a_4) \end{aligned} \tag{3.23}$$

$$\begin{aligned} (\nabla_{(\xi \wedge_S a_2)a_4} \sigma)(\xi, a_3) &= \tilde{\nabla}_{(\xi \wedge_S a_2)a_4}^\perp \sigma(\xi, a_3) - \sigma(\tilde{\nabla}_{(\xi \wedge_S a_2)a_4} \xi, a_3) - \sigma(\xi, \tilde{\nabla}_{(\xi \wedge_S a_2)a_4} a_3) \\ &= 2n\eta(a_4) \sigma(a_2, a_3) \end{aligned} \tag{3.24}$$

$$\begin{aligned} (\nabla_{a_4} \sigma)((\xi \wedge_S a_2)\xi, a_3) &= (\nabla_{a_4} h)(S(a_2, \xi)\xi - S(\xi, \xi)a_2, a_3) \\ &= (\nabla_{a_4} h)(-2n\eta(a_2)\xi + 2na_2, a_3) \\ &= -2n\{\tilde{\nabla}_{a_4}^\perp \sigma(\eta(a_2)\xi, a_3) - \sigma(\tilde{\nabla}_{a_4} \eta(a_2)\xi, a_3) - \sigma(\eta(a_2)\xi, \tilde{\nabla}_{a_4} a_3) + 2n(\nabla_{a_4} \sigma)(a_2, a_3)\} \\ &= 2n(\nabla_{a_4} \sigma)(a_2, a_3) - 2n\eta(a_2) \sigma(a_4, a_3) \end{aligned} \tag{3.25}$$

In the same way, we have

$$\begin{aligned} (\nabla_{a_4} \sigma)(\xi, (\xi \wedge_S a_2)a_3) &= (\nabla_{a_4} \sigma)(\xi, S(a_2, a_3)\xi - S(\xi, a_3)a_2) \\ &= (\nabla_{a_4} \sigma)(\xi, S(a_2, a_3)\xi) + (\tilde{\nabla}_{a_4} \sigma)(\xi, 2n\eta(a_3)a_2) \\ &= 2n\eta(a_3)\sigma(a_4, a_2) \end{aligned} \quad (3.26)$$

Consequently, we substitute (3.20)-(3.26) in (3.19), we obtain

$$\begin{aligned} R^\perp(\xi, a_2)\sigma(a_3, a_4) - \eta(a_4)\sigma(a_2, a_3) + 3\eta(a_2)\sigma(a_4, a_3) - \eta(a_3)\sigma(a_4, a_2) - (\nabla_{a_4} \sigma)(a_2, a_3) = \\ -k_4\{2n\eta(a_4)\sigma(a_2, a_3) - 2n\eta(a_2)\sigma(a_4, a_3) + 2n\eta(a_3)\sigma(a_4, a_2) + 2n(\nabla_{a_4} \sigma)(a_2, a_3)\} \end{aligned} \quad (3.27)$$

If we choose  $a_3 = \xi$  in (3.27) and use

$$(\nabla_{a_4} \sigma)(a_2, \xi) = \sigma(a_4, a_2)$$

we get

$$[2nk_4 - 1]\sigma(a_4, a_2) = 0$$

□

**Corollary 3.13.** Let  $\tilde{M}$  be a pseudoparallel invariant submanifold of a  $(2n + 1)$ -dimensional Kenmotsu manifold  $M(\phi, \xi, \eta, g)$ . Then,  $\tilde{M}$  is  $W_8$ -2 Ricci generalized semi-parallel if and only if  $\tilde{M}$  is totally geodesic.

## 4. Conclusion

This paper considered pseudoparallel invariant submanifolds of Kenmotsu manifolds on  $W_8$  curvature tensor and researched some basic characterizations, such as  $W_8$  pseudoparallel,  $W_8$ -2 pseudoparallel,  $W_8$ -Ricci generalized pseudoparallel, and  $W_8$ -2 Ricci generalized pseudoparallel. In addition, the paper provided some relations between these pseudoparallel invariant submanifolds and semi-parallel invariant submanifolds. In future studies, pseudoparallel invariant submanifolds of Kenmotsu manifolds can also be characterized using other curvature tensors. Besides, this topic is worth studying on the other manifolds.

## Author Contributions

All the authors equally contributed to this work. This paper is derived from the first author's master's thesis supervised by the second author. They all read and approved the final version of the paper.

## Conflict of Interest

All the authors declare no conflict of interest.

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## Effect of fractional time derivatives to pressure-driven flow through the horizontal microchannel

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**Abstract** — This research applies fractional time derivatives to fluid flow through a horizontal microchannel. It uses fractional time derivatives with the Laplace transform technique and method of undetermined coefficient to analyze and obtain solutions of the governing equations in the Laplace domain. To this end, the solutions are reversed in the time domain using Riemann-sum approximation methods. In order to obtain the solutions for the pressure-driven flow, the time fractional derivative in the Caputo sense is employed. Here, the influence of each governing parameter is explained with a line graph. Results show that with the decreases in fractional order ( $\alpha$ ), the velocity decreases within the interval  $0 < \alpha < 1$ . The fluid velocity increases and decreases as the Knudsen number ( $kn$ ) changes. Besides, transient wall-skin frictions for different times ( $t$ ) and Knudsen number ( $kn$ ) with a fixed value of fractional order ( $\alpha$ ) are observed.

**Keywords:** Fractional time derivative, pressure-driven flow, Knudsen number, Laplace transform, Couette flow

**Subject Classification (2020):** 76D55, 34A08

### 1. Introduction

Fractional calculus is a generalization of ordinary differential and integral of non-integer order  $\alpha$ . It was first introduced by L'Hospital and Leibnitz in 1695 after they proposed what would happen if the ordinary derivative of integer order was changed to fractional order by L'Hospital. Then, Leibnitz first used the notation  $d^{(1/2)}y$  in 1697. Many mathematicians have suggested their interest in its application, as Lacroix 1819 mentioned fractional derivatives in his text on differential and integral calculus. Euler and Fourier mentioned fractional derivatives but did not give any application or example. The first and popular definition, the Riemann-Liouville definition, was proposed by Riemann and Liouville, after which Caputo proposed a second popular definition called the Caputo Fractional Derivative. There are many definitions of Fractional calculus, such as Jumarie, Wely, Eudelyikober, Hadamard, and the Riesz fractional derivative (see, for example, Srivastava and Saxena [1] and Kaur [2]).

In recent decades, many researchers have been devoted to its applications in science and engineering. Fractional calculus has been recognized as a practical modeling approach in fields such as electrical networks, electrochemistry, and viscoelastic deformation, solving linear, nonlinear partial fractional differential equations (see Farid et al. [3]). According to Ali et al. [4], Newtonian and non-Newtonian fluids depend on their deformation. Newtonian fluids are fluids that obey Newton's law of viscosities. In contrast,

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non-Newtonian fluids do not follow Newton's law of viscosities, having many applications in fields such as industries, medical treatment, and engineering worldwide.

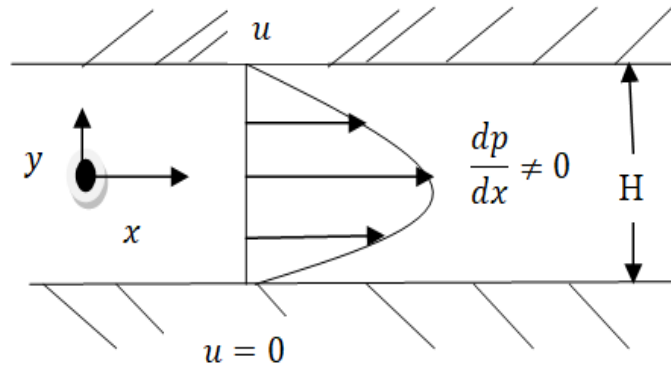
A micro-channel is defined in Djordjevic [5] as a flow channel with a hydraulic diameter of less than 1 mm and characterized by the rarefaction effect, which includes the Knudsen number  $kn = \lambda/l$ , where  $\lambda$  is the mean free path of the molecules and  $l$  is the characteristic length scale (height  $h$  of the channel or the radius  $a$  of the tube), then the Knudsen number is the quantity that helps to know which fluid dynamic formula to use to model a situation in both statistical mechanics or continuum mechanics for the continuum hypothesis to be valid, the Knudsen number must be less than 0.1 for pressure driven. Saqib et al. [6] explain that the temperature and velocity fields can be reduced for any value of  $\alpha$  between the interval  $0 < \alpha < 1$  with memory and heredity profile, which are more generally flexible and reliable, in the presence of variation in the thermal boundary layer when increasing volume fraction of carbon nanotubes (CNTs) the temperature profile increases and decreases with increases of fractional order  $\alpha$  in both cases.

Ellahia et al. [7] change more than one parameter in the channel and find that the fluid velocity decreases as  $\beta$  increases the fixed value of the channel length  $L$ . In the same paper, they also found that for a fixed value of  $\beta$  and growing  $L$ , the velocity also increases. Farooq et al. [8] studied the generalized Couette flow by varying the various parameters of temperature distribution and velocity, where it was observed that as the fluid moved from a fixed plate to a movable plate, the velocity and temperature increased. Arif et al. [9] open channel for Couple Stress Fluid (CSF) using integral transform (Laplace and Fourier) for the comparative analysis of Caputo (C), Caputo-Fabrizio (CF), Atangana Baleanu (AB), and classical CSF where it is observed the velocity of the CSF of C, CF has less influence of fluid dynamics than the velocity of the CSF concerning AB, which clearly shows that AB fractional derivatives has a better memory effect than C, CF and increasing the constant pressure gradient of CSF improves the velocity. Maitia et al. [10] discovered the impact of the Caputo-Fabrizio derivative of the fractional order model on blood flow, where they found that increasing the value of the fractional parameter value decreased velocity and temperature when memory counters average speed of blood flow medium effect to drive faster. The velocity profile improves as the stress jump coefficient increases. When the stress jump coefficient  $\beta$  is close to zero, non-Newtonian characteristics become more effective, and  $\beta$  approaches infinity, the model becomes a Newtonian when viscosity increases. Blood flow decreases with a decrease in  $\beta$ . In the same paper, they also find that the shear stress increases in the wall due to chemical reactions.

The governing equation for this present study is in fractional order, focusing on pressure-driven flow through a horizontal channel with many applications in applied science and engineering, such as biological research, geophysical engineering, DNA sequencing for drug delivery, and micro-electro-mechanical systems (MECSs). In the presence of pressure gradient and upper plate motion of the boundary layer (generalized Couette flow), the steady and unsteady flow has been studied related to skin friction on the pressure gradient and dependence on the interface velocity (see Kaurangini and Jha [11]).

## 2. Analytical Solution

The governing equations [12] are derived from the classical equations and modified by replacing the ordinary time derivatives with the fractional calculus operators. This generalization allows us to define non-integer order integrals or derivatives precisely. Figure 1 manifests the fluid flow in the microchannel is induced by pressure-driven flow.



**Figure 1.** Schematic diagram of pressure-driven flow

The governing equation [12] for the flow is as follows:

$$D_t^\alpha u(y, t) = \gamma \frac{\partial^2 u(y, t)}{\partial y^2} + p \tag{2.1}$$

with initial and boundary conditions and  $D_t^\alpha u(y, t)$  is the Caputo fractional derivative,

$$t \leq 0: u = 0, \text{ for all } y \tag{2.2}$$

and

$$t > 0: u(y, t) = \begin{cases} +\beta_v k_n \frac{du}{dy}, & y = 0 \\ -\beta_v k_n \frac{du}{dy}, & y = H \end{cases} \tag{2.3}$$

with the analysis technique mentioned above, we have the following solution approach:

Taking the Laplace transform of both sides of (2.1) together with (2.2), we have

$$\frac{d^2 \bar{U}(y, s)}{dy^2} - \frac{s^\alpha \bar{U}(y, s)}{\gamma} = -\frac{p}{\gamma s} \tag{2.4}$$

Solving (2.4) by the method of undetermined coefficient to obtain the general solution,

$$\bar{U}(y, s) = c_1 \cosh k_1 y + c_2 \sinh k_1 y + k_2 \tag{2.5}$$

Similarly, we apply the Laplace transform to (2.3), the boundary conditions become

$$\frac{1}{s^2} > 0: \bar{U}(y, s) = \begin{cases} +\beta_v k_n \frac{d}{dy} \bar{U}(y, s), & y = 0 \\ -\beta_v k_n \frac{d}{dy} \bar{U}(y, s), & y = H \end{cases} \tag{2.6}$$

Using (2.5) on (2.6), we obtained the following solutions:

$$\bar{U}(y, s) = k_7 \cosh k_1 y + k_6 \sinh k_1 y + k_2 \tag{2.7}$$

where

$$\left\{ \begin{array}{l} k_1 = \left( \frac{s^\alpha}{\gamma} \right)^{\frac{1}{2}} \\ k_2 = \frac{P}{s^{\alpha+1}} \\ k_3 = \cosh k_1 H + \beta_v k_n k_1 \sinh k_1 H \\ k_4 = \sinh k_1 H + \beta_v k_n k_1 \cosh k_1 H \\ k_5 = \beta_v k_n k_1 k_3 + k_4 \\ k_6 = \frac{k_2(k_3 - 1)}{k_5} \\ k_7 = \beta_v k_n k_1 k_6 - k_2 \end{array} \right. \quad (2.8)$$

### 3. Skin Friction for Pressure Driven Flow

From (2.7), the skin frictions at the wall of the channel are obtained

$$\hat{\tau}_0 = \left. \frac{d\bar{U}(y, s)}{dy} \right|_{y=0} = (k_1 k_7 \sinh k_1 y + k_1 k_6 \cosh k_1 y)|_{y=0} = K_1 K_6 \quad (3.1)$$

$$\hat{\tau}_1 = \left. \frac{d\bar{U}(y, s)}{dy} \right|_{y=1} = (k_1 k_7 \sinh k_1 y + k_1 k_6 \cosh k_1 y)|_{y=1} = k_1 k_7 \sinh k_1 + k_1 k_6 \cosh k_1 \quad (3.2)$$

## 4. Results and Discussions

### 4.1. Numerical Results

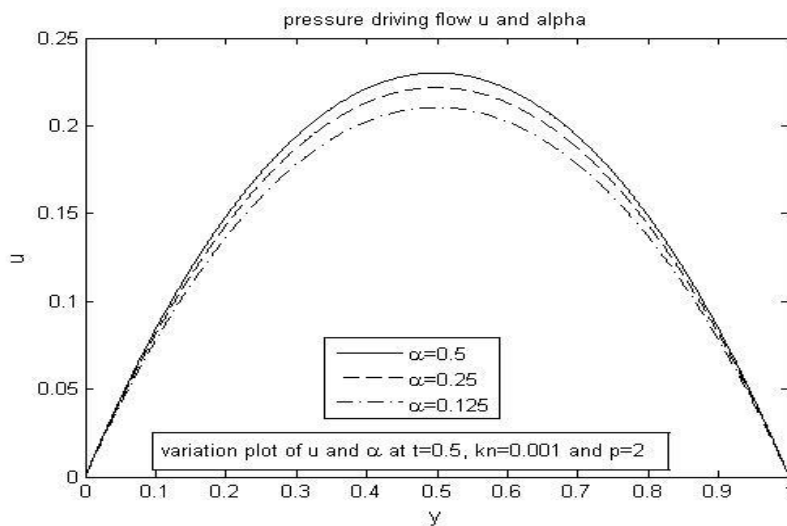
This was done to simulate numerical solutions for transient skin friction at different walls using the computational software MATLAB R2014a. We obtained the following results.

**Table 1.** Transient skin frictions at the walls for different time  $t$  and Knudsen number  $kn$  of Pressure driven flow

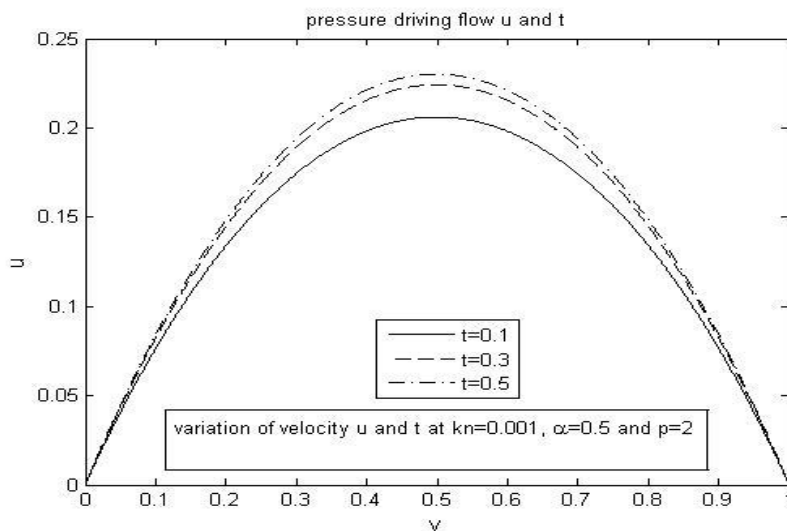
	$\beta v = 0.5, a = 0.5$ $p = 2, \gamma = 1, kn = 0.0$		$\beta v = 0.5, a = 0.5$ $Y = 1, kn = 0.04$		$\beta v = 0.5, a = 0.5, p = 2$ $Y = 1, kn = 0.08$	
$t$	$\tau_0$	$\tau_1$	$\tau_0$	$\tau_1$	$\tau_0$	$\tau_1$
0.1	0.0140	-0.0140	0.0134	-0.0134	0.0129	-0.0129
0.2	0.0310	-0.0310	0.0299	-0.0299	0.0289	-0.0289
0.3	0.0487	-0.0487	0.0473	-0.0473	0.0460	-0.0460
0.4	0.0670	-0.0670	0.0652	-0.0652	0.0636	-0.0636
0.5	0.0856	-0.0856	0.0835	-0.0835	0.0815	-0.0815
0.6	0.1044	-0.1044	0.1020	-0.1020	0.0998	-0.0998
0.7	0.1234	-0.1234	0.1208	-0.1208	0.1183	-0.1183
0.8	0.1425	-0.1425	0.1397	-0.1397	0.1370	-0.1370
0.9	0.1618	-0.1618	0.1587	-0.1587	0.1558	-0.1558
1.0	0.1812	-0.1812	0.1779	-0.1779	0.1747	-0.1747

### 4.2. 2D-Plots Presentation

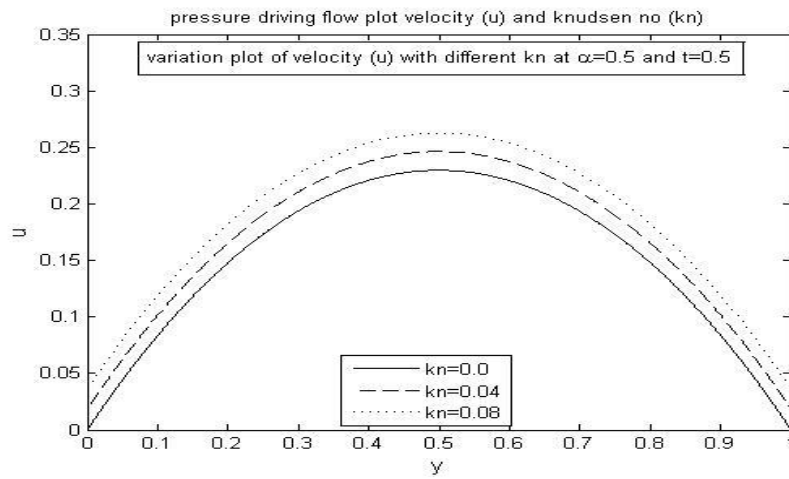
Figures 2-5 describe the velocity profiles for various parameters, such as fractional  $\alpha$ , pressure  $p$ , Knudsen number  $kn$ , and time  $t$ , caused by the pressure gradient. Figure 2 shows that the reduction of fractional order reduces the velocity of the fluid, which implies that the velocity can be slowed down by decreasing the fractional order. In addition, it shows the advantages of fractional derivatives over integer derivatives. Figure 3 shows that the transient velocity increases with time, which implies that with a constant driving force, the velocity can increase as time goes on. Figure 4 shows that as the Knudsen number increased, the fluid velocity increased, indicating that enlarging the length scale allowed the mean free path to enlarge and the velocity to increase. Similarly, Figure 5 shows the velocity profiles for different Knudsen numbers  $kn$ . Figure 6 depicts the variation of fractional order  $\alpha$  with velocity  $U$ , which that the velocity of the fluid decreases when the fractional order decreases with the interval of 0.3, and between 0.6 and 0.3, the velocity reduces unlike from 0.9 to 0.6, which clearly shows the effect of the fractional order. Figure 7 shows the variation of velocity  $U$  with time  $t$ , which shows that increasing time makes velocity also increase and converge at both walls, which leads the velocity to decrease between 0.5 to 0.8, and as time goes on, the velocity will be steady. It should be noted that the fluid velocity slows down as the Knudsen number decreases. Table 1 shows that skin friction increases evenly on both walls but in opposite directions with increasing time and Knudsen number.



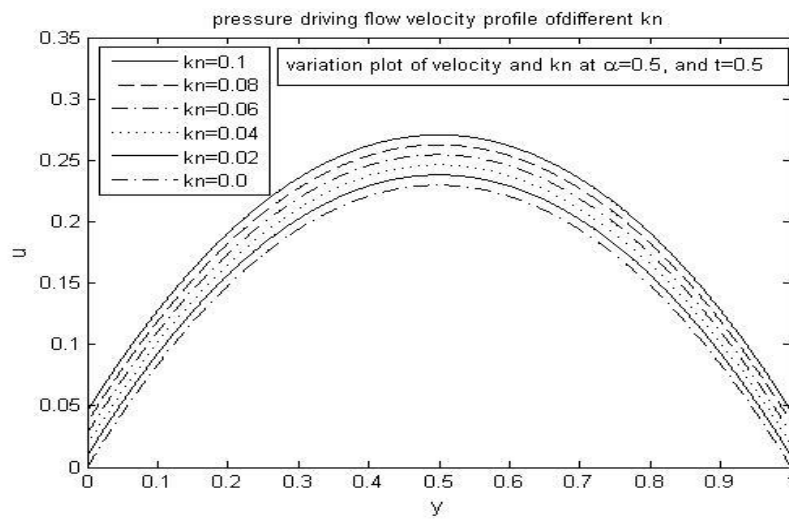
**Figure 2.** Variation of fractional order  $\alpha$  against velocity  $U$  when the fluid flow as a result of pressure gradient



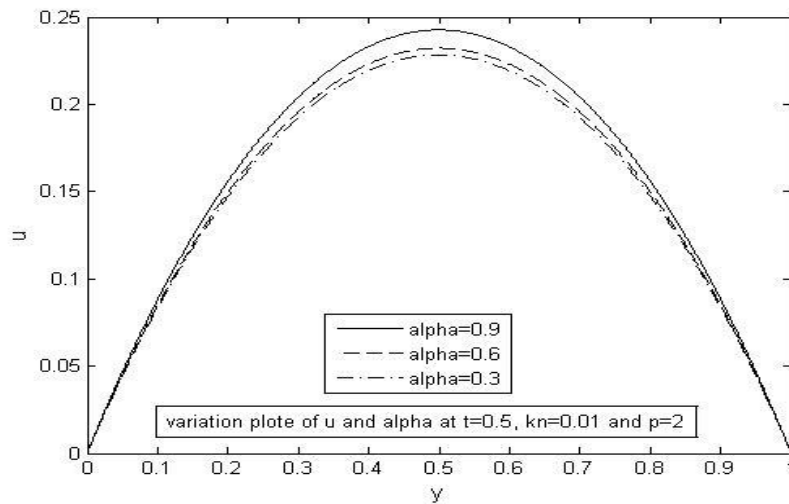
**Figure 3.** Variation of time  $t$  against velocity  $U$  when the fluid flows as a result of pressure gradient



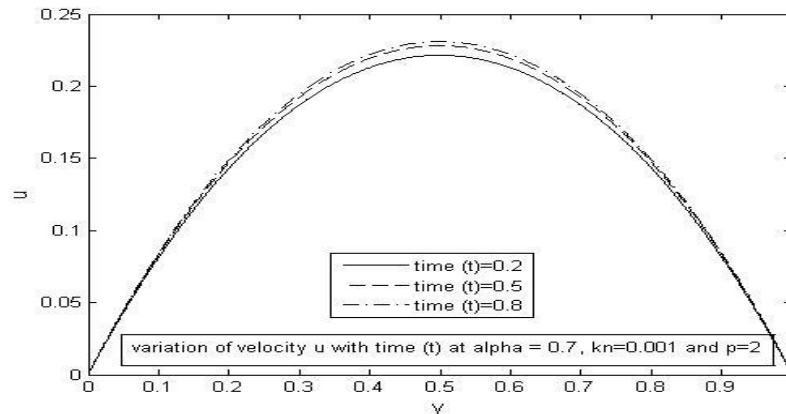
**Figure 4.** Variation of Knudsen number  $kn$  against velocity  $U$  as a result of pressure gradient



**Figure 5.** Variation of Knudsen number  $kn$  against velocity  $U$  as a result of pressure gradient



**Figure 6.** Variation of fractional order  $\alpha$  against velocity  $U$  when the fluid flows as a result of pressure gradient



**Figure 7.** Variation of time  $t$  against velocity  $U$  when the fluid flows as a result of pressure gradient

## 5. Conclusion

In this paper, the effect of varying the governing parameters was considered to study the velocity profile induced by pressure-driven flow in the microchannel. The transient skin friction uniformly increases at both walls but in opposite directions. It has been discovered that the velocity of a fluid flow can be controlled by adjusting the fractional order ( $\alpha$ ). The advantages of fractional derivatives over integer derivatives have been studied. It has been observed that the velocity can increase with a constant driven force as time goes on. Enlarging the length scale enlarged the mean free path and increased velocity. It can be seen that with a continuous decrease of the Knudsen number  $kn$ , at  $\beta\nu = -0.5$ , the velocity increases but remains constant at  $\beta\nu = 0.0$  while at  $\beta\nu = 0.5$ , the velocity decreases. The results obtained from this study are significant for industries, as they contribute to a better comprehension of various applications such as oil reservoirs, nuclear reactors, groundwater flow, filtration, and geothermal systems. Furthermore, these findings present opportunities for further investigation through the inclusion of porous mediums, suction, and injection velocities.

## Abbreviations

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$D$	fractional derivative
$\alpha$	fractional order
$t$	time
$u$	velocity of fluid flow
$y$	dimensionless y coordinate
$p$	dimensionless pressure gradient
$kn$	Knudsen number
$\beta$	stress jump coefficient
$\rho$	fluid density
$\lambda$	molecular mean free path
$\nu_f$	kinematics viscosity of the fluid
$y'$	dimensional y-coordinate
$u_f$	dimensionless velocity in the clear fluid region
$u'_f$	dimensional velocity in the clear fluid region
$u_t$	transient velocity
$\frac{\delta p'}{\delta z'}$	dimensional pressure gradient
$\beta_v$	dimensionless variable

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## Author Contributions

All the authors equally contributed to this work. They all read and approved the final version of the paper.

## Conflict of Interest

All the authors declare no conflict of interest.

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## Some identities of bivariate Pell and bivariate Pell-Lucas polynomials

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**Abstract** — In this paper, we obtain some identities for the bivariate Pell polynomials and bivariate Pell-Lucas polynomials. We establish some sums and connection formulas involving them. Moreover, we present its two cross two matrices representation and find some of its properties, such as the  $b^{\text{th}}$  power of the matrix. We finally derive the identities by using Binet's formula, generating function, and induction method.

**Keywords:** *Bivariate Pell polynomials, bivariate Pell-Lucas polynomials, Binet's formula, generating function*

**Subject Classification (2020):** 11B37, 11B39

### 1. Introduction

Sequences and polynomials have a wide range of applications in applied mathematics and physics. Bivariate polynomials are widely used in theoretical physics for modeling physical processes. Catalani [1-3] defined generalized bivariate polynomials from which, by specifying initial conditions, the bivariate Fibonacci and Lucas polynomials are obtained, and many interesting identities are derived. Belbachir and Bencherif [4] generalized to bivariate Fibonacci and Lucas polynomials properties obtained for Chebyshev polynomials. They proved that the coordinates of the bivariate polynomials over an appropriate basis are families of integers satisfying remarkable recurrence relations. Tuğlu et al. [5] presented generalized bivariate Fibonacci and Lucas  $p$ -polynomials, which are general forms of the Fibonacci, Lucas, Pell, Jacobsthal, Pell-Lucas, Jacobsthal-Lucas sequences, as well as Fibonacci, Lucas, Pell, Jacobsthal, Pell-Lucas, Jacobsthal-Lucas, bivariate Fibonacci and Lucas, first and second type of Chebyshev polynomials, and many others. Halıcı and Akyüz [6] derived some identities and some sum formulas for the bivariate Pell polynomials using different matrices. Saba and Boussayoud [7] introduced a symmetric function to derive a new generating function of bivariate Pell Lucas polynomials, also derived new symmetric functions, and gave some interesting properties. This study defines the identities of bivariate Pell and bivariate Pell-Lucas polynomials.

### 2. Preliminaries

For  $n \geq 2$ , the bivariate Pell polynomials sequence [6] is defined by

$$P_n(x, y) = 2xyP_{n-1}(x, y) + yP_{n-2}(x, y) \quad (2.1)$$

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Therefore, the first few bivariate Pell polynomials are

$$\{P_n(x, y)\} = \{0, 1, 2xy, 4x^2y^2 + y, 8x^3y^3 + 4xy^2, 16x^4y^4 + 12x^2y^3 + y^2, \dots\}$$

Binet's formula,

$$P_n(x, y) = \frac{\ell_1^n - \ell_2^n}{\ell_1 - \ell_2}$$

Generating function,

$$P_n(x, y) = \frac{t}{(1 - 2xyt - yt^2)}$$

For  $n \geq 2$ , the bivariate Pell-Lucas polynomials sequence [6] is defined by

$$Q_n(x, y) = 2xyQ_{n-1}(x, y) + yQ_{n-2}(x, y) \quad (2.2)$$

Therefore, the first few bivariate Pell-Lucas polynomials are

$$\{Q_n(x, y)\} = \{2, 2xy, 4x^2y^2 + 2y, 8x^3y^3 + 6xy^2, 16x^4y^4 + 16x^2y^3 + 2y^2, \dots\}$$

Binet's formula,

$$Q_n(x, y) = \ell_1^n + \ell_2^n$$

Generating function,

$$Q_n(x, y) = \frac{2 + 2xyt(x - 1)}{(1 - 2xyt - yt^2)}$$

The characteristic equation of recurrence relations (2.1) and (2.2) is

$$t^2 - 2xyt - y = 0$$

where  $x \neq 0$ ,  $y \neq 0$ , and  $x^2y^2 + y \neq 0$ . This equation has two real roots:  $\ell_1 = xy + \sqrt{x^2y^2 + y}$  and  $\ell_2 = xy - \sqrt{x^2y^2 + y}$ . Note that  $\ell_1 + \ell_2 = 2xy$ ,  $\ell_1\ell_2 = -y$ , and  $\ell_1 - \ell_2 = \sqrt{x^2y^2 + y}$ . Moreover,  $P_{-n}(x, y) = \frac{-1}{(-y)^n} P_n(x, y)$  and  $Q_{-n}(x, y) = \frac{1}{(-y)^n} Q_n(x, y)$ . The main objective of this study is to describe sums and connection formulas. Moreover, we introduce the special sums and prove them using Binet's formula.

### 3. Results and Discussions

We first establish sums and relations for bivariate Pell and bivariate Pell-Lucas polynomials. The motivation of this work comes from the study of [8-11].

**Proposition 3.1.** For  $\vartheta, \omega \in \mathbb{Z}$ , we get

$$\sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (2xy)^b y^{\vartheta+\omega-b} P_b(x, y) = P_{2\vartheta+2\omega}(x, y)$$

**Proof.**

By Binet's formula,

$$\begin{aligned} \sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (2xy)^b y^{\vartheta+\omega-b} P_b(x, y) &= \sum_{b=0}^{c+d} \binom{\vartheta+\omega}{b} (2xy)^b y^{\vartheta+\omega-b} \left( \frac{\ell_1^b - \ell_2^b}{\ell_1 - \ell_2} \right) \\ &= \frac{1}{\ell_1 - \ell_2} \sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (2xy)^b y^{\vartheta+\omega-b} (\ell_1^b - \ell_2^b) \\ &= \frac{1}{\ell_1 - \ell_2} \sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} \{(2xy\ell_1)^b - (2xy\ell_2)^b\} y^{\vartheta+\omega-b} \\ &= \frac{1}{\ell_1 - \ell_2} \{(2xy\ell_1 + y)^{\vartheta+\omega} - (2xy\ell_2 + y)^{\vartheta+\omega}\} \end{aligned}$$

Since  $\ell_1$  and  $\ell_2$  are the roots of  $t^2 - 2xyt - y = 0$ ,

$$\sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (2xy)^b y^{\vartheta+\omega-b} P_b(x, y) = \frac{(\ell_1^2)^{\vartheta+\omega} - (\ell_2^2)^{\vartheta+\omega}}{\ell_1 - \ell_2} = P_{2\vartheta+2\omega}(x, y)$$

□

**Proposition 3.2.** For  $\vartheta, \omega \in \mathbb{Z}$ , we get

$$\sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (2xy)^b (-y)^{\vartheta+\omega-b} P_b(x, y) = \sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (-2y)^b P_{2\vartheta+2\omega-2b}(x, y)$$

**Proof.**

By Binet’s formula,

$$\begin{aligned} \sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (2xy)^b (-y)^{\vartheta+\omega-b} P_b(x, y) &= \sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (2xy)^b (-y)^{\vartheta+\omega-b} \left( \frac{\ell_1^b - \ell_2^b}{\ell_1 - \ell_2} \right) \\ &= \frac{1}{\ell_1 - \ell_2} \sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (2xy)^b (-y)^{\vartheta+\omega-b} (\ell_1^b - \ell_2^b) \\ &= \frac{1}{\ell_1 - \ell_2} \sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} \{(2xy\ell_1)^b - (2xy\ell_2)^b\} (-y)^{\vartheta+\omega-b} \\ &= \frac{1}{\ell_1 - \ell_2} \{(2xy\ell_1 - y)^{\vartheta+\omega} - (2xy\ell_2 - y)^{\vartheta+\omega}\} \end{aligned}$$

Since  $\ell_1$  and  $\ell_2$  are the roots of  $t^2 - 2xyt - y = 0$ ,

$$2xy\ell_1 - y = \ell_1^2 - 2y$$

and

$$2xy\ell_2 - y = \ell_2^2 - 2y$$

Thus,

$$\begin{aligned} \sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (2xy)^b (-y)^{\vartheta+\omega-b} P_b(x, y) &= \frac{(\ell_1^2 - 2y)^{\vartheta+\omega} - (\ell_2^2 - 2y)^{\vartheta+\omega}}{\ell_1 - \ell_2} \\ &= \sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (-2y)^b P_{2\vartheta+2\omega-2b}(x, y) \end{aligned}$$

□

**Proposition 3.3.** For  $\vartheta, \omega \in \mathbb{Z}$ , we get

$$\sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (2xy)^{\vartheta+\omega-b} (-1)^b Q_b(x, y) = Q_{\vartheta+\omega}(x, y)$$

**Proof.**

By Binet’s formula,

$$\begin{aligned} \sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (2xy)^{\vartheta+\omega-b} (-1)^b Q_b(x, y) &= \sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (2xy)^{\vartheta+\omega-b} (-1)^b (\ell_1^b + \ell_2^b) \\ &= \sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (2xy)^{\vartheta+\omega-b} (-1)^b (-\ell_1^b) + \sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (2xy)^{\vartheta+\omega-b} (-1)^b (-\ell_2^b) \\ &= (2xy - \ell_1)^{\vartheta+\omega} + (2xy - \ell_2)^{\vartheta+\omega} \\ &= \left(\frac{-y}{\ell_1}\right)^{\vartheta+\omega} + \left(\frac{-y}{\ell_2}\right)^{\vartheta+\omega} \\ &= (-y)^{\vartheta+\omega} \frac{\ell_1^{\vartheta+\omega} + \ell_2^{\vartheta+\omega}}{(\ell_1 \ell_2)^{\vartheta+\omega}} \\ &= Q_{\vartheta+\omega}(x, y) \end{aligned}$$

□

**Proposition 3.4.** For  $\vartheta, \omega \in \mathbb{Z}$ , we get

$$\sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (2xy)^b y^{\vartheta+\omega-b} Q_b(x, y) = Q_{2\vartheta+2\omega}(x, y)$$

**Proof.**

By Binet’s formula,

$$\begin{aligned} \sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (2xy)^b y^{\vartheta+\omega-b} Q_b(x, y) &= \sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (2xy)^b y^{\vartheta+\omega-b} Q_b(x, y) (\ell_1^b + \ell_2^b) \\ &= \sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (2xy\ell_1)^b y^{\vartheta+\omega-b} + \sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (2xy\ell_2)^b y^{\vartheta+\omega-b} \\ &= (2xy\ell_1 + y)^{\vartheta+\omega} + (2xy\ell_2 + y)^{\vartheta+\omega} \end{aligned}$$

Since  $\ell_1$  and  $\ell_2$  are the roots of  $t^2 - 2xyt - y = 0$ ,

$$\begin{aligned} \sum_{b=0}^{\vartheta+\omega} \binom{\vartheta+\omega}{b} (2xy)^b y^{\vartheta+\omega-b} Q_b(x, y) &= (\ell_1^2)^{\vartheta+\omega} + (\ell_2^2)^{\vartheta+\omega} \\ &= Q_{2\vartheta+2\omega}(x, y) \end{aligned}$$

□

**Proposition 3.5.** If  $P_b(x, y)$  and  $Q_b(x, y)$  are Bivariate Pell and Bivariate Pell-Lucas polynomials, then for  $b \geq \vartheta + \omega$ ,

$$P_{b+\vartheta+\omega}(x, y) - (-y)^{\vartheta+\omega} P_{b-\vartheta-\omega}(x, y) = P_{\vartheta+\omega}(x, y) Q_b(x, y)$$

**Proof.**

By Binet’s formula,

$$\begin{aligned} P_{b+\vartheta+\omega}(x, y) - (-y)^{\vartheta+\omega} P_{b-\vartheta-\omega}(x, y) &= \frac{\rho_1^{b+\vartheta+\omega} - \rho_2^{b+\vartheta+\omega}}{\ell_1 - \ell_2} - (-y)^{\vartheta+\omega} \left( \frac{\rho_1^{b-\vartheta-\omega} - \rho_2^{b-\vartheta-\omega}}{\ell_1 - \ell_2} \right) \\ &= \frac{(\rho_1^{b+\vartheta+\omega} - \rho_2^{b+\vartheta+\omega}) - (-y)^{\vartheta+\omega} (\rho_1^{b-\vartheta-\omega} - \rho_2^{b-\vartheta-\omega})}{\ell_1 - \ell_2} \\ &= \frac{(\rho_1^{b+\vartheta+\omega} - \rho_2^{b+\vartheta+\omega}) - (\ell_1 \ell_2)^{\vartheta+\omega} (\rho_1^{b-\vartheta-\omega} - \rho_2^{b-\vartheta-\omega})}{\ell_1 - \ell_2} \\ &= \frac{(\rho_1^{b+\vartheta+\omega} - \rho_2^{b+\vartheta+\omega}) - (\rho_1^b \rho_2^{\vartheta+\omega} - \rho_1^{\vartheta+\omega} \rho_2^b)}{\ell_1 - \ell_2} \\ &= \left( \frac{\rho_1^{\vartheta+\omega} - \rho_2^{\vartheta+\omega}}{\ell_1 - \ell_2} \right) (\rho_1^b + \rho_2^b) \\ &= P_{\vartheta+\omega}(x, y) Q_b(x, y) \end{aligned}$$

□

Secondly, we investigate sums for Bivariate Pell and Pell-Lucas polynomials with negative indices.

**Theorem 3.6.** For  $\vartheta \geq 1$  and  $\omega$  any integer, we get

$$\sum_{i=0}^b (-y)^i P_{-i\vartheta-\omega}(x, y) = \begin{cases} \frac{P_{\vartheta b+\vartheta+\omega}(x, y) - (-y)^\vartheta P_{\vartheta b+\omega}(x, y) - (-y)^\omega P_{\vartheta-\omega}(x, y) + P_\omega(x, y)}{(-1)^\vartheta - Q_\vartheta(x, y) + 1}, & \omega < \vartheta \\ \frac{P_{\vartheta b+\vartheta+\omega}(x, y) - (-y)^\vartheta P_{\vartheta b+\omega}(x, y) + (-y)^\omega P_{\vartheta-\omega}(x, y) + P_\omega(x, y)}{(-1)^\vartheta - Q_\vartheta(x, y) + 1}, & \text{otherwise} \end{cases}$$

**Proof.**

Since

$$\sum_{i=0}^b (-y)^i P_{-i\vartheta-\omega}(x, y) = - \sum_{i=0}^b P_{i\vartheta+\omega}(x, y)$$

By Binet’s formula,

$$\begin{aligned} \sum_{i=0}^b (-y)^i P_{-i\vartheta-\omega}(x, y) &= - \sum_{i=0}^b \frac{\ell_1^{i\vartheta+\omega} - \ell_2^{i\vartheta+\omega}}{\ell_1 - \ell_2} \\ &= \frac{-1}{\ell_1 - \ell_2} \left( \ell_1^\omega \sum_{i=0}^b \ell_1^{\vartheta i} - \ell_2^\omega \sum_{i=0}^b \ell_2^{\vartheta i} \right) \\ &= \frac{-1}{\ell_1 - \ell_2} \left[ \frac{\ell_1^{\vartheta b+\vartheta+\omega} - \ell_1^\omega}{\ell_1^\vartheta - 1} - \frac{\ell_2^{\vartheta b+\vartheta+\omega} - \ell_2^\omega}{\ell_2^\vartheta - 1} \right] \\ &= \frac{(\ell_1^{\vartheta b+\vartheta+\omega} - \ell_2^{\vartheta b+\vartheta+\omega}) - (\ell_1 \ell_2)^\vartheta (\ell_1^{\vartheta b+\omega} - \ell_2^{\vartheta b+\omega}) - (\ell_1^\vartheta \ell_2^\omega - \ell_1^\omega \ell_2^\vartheta) + (\ell_1^\omega - \ell_2^\omega)}{(\ell_1 - \ell_2) \{ (\ell_1 \ell_2)^\vartheta - (\ell_1^\vartheta + \ell_2^\vartheta) + 1 \}} \\ &= \begin{cases} \frac{P_{\vartheta b+\vartheta+\omega}(x, y) - (-y)^\vartheta P_{\vartheta b+\omega}(x, y) - (-y)^\omega P_{\vartheta-\omega}(x, y) + P_\omega(x, y)}{(-1)^\vartheta - Q_\vartheta(x, y) + 1}, & \omega < \vartheta \\ \frac{P_{\vartheta b+\vartheta+\omega}(x, y) - (-y)^\vartheta P_{\vartheta b+\omega}(x, y) + (-y)^\omega P_{\vartheta-\omega}(x, y) + P_\omega(x, y)}{(-1)^\vartheta - Q_\vartheta(x, y) + 1}, & \text{otherwise} \end{cases} \end{aligned}$$

□

**Theorem 3.7.** For  $\vartheta \geq 1$  and  $\omega$  any integer, we get

$$\sum_{i=0}^b (-y)^i Q_{-i\vartheta-\omega}(x, y) = \begin{cases} \frac{(-y)^\vartheta Q_{\vartheta b+\omega}(x, y) - Q_{\vartheta b+\vartheta+\omega}(x, y) - (-y)^\omega Q_{\vartheta-\omega}(x, y) + Q_\omega(x, y)}{(-1)^\vartheta - Q_\vartheta(x, y) + 1}, & \omega < \vartheta \\ \frac{(-y)^\vartheta Q_{\vartheta b+\omega}(x, y) - Q_{\vartheta b+\vartheta+\omega}(x, y) + (-y)^\omega Q_{\vartheta-\omega}(x, y) + Q_\omega(x, y)}{(-1)^\vartheta - Q_\vartheta(x, y) + 1}, & \text{otherwise} \end{cases}$$

**Proof.**

Since

$$\sum_{i=0}^b (-y)^i Q_{-i\vartheta-\omega}(x, y) = \sum_{i=0}^b Q_{i\vartheta+\omega}(x, y)$$

By Binet’s formula,

$$\begin{aligned} \sum_{i=0}^b (-y)^i Q_{-i\vartheta-\omega}(x, y) &= \sum_{i=0}^b (\ell_1^{i\vartheta+\omega} + \ell_2^{i\vartheta+\omega}) \\ &= \ell_1^\omega \sum_{i=0}^b \ell_1^{\vartheta i} + \ell_2^\omega \sum_{i=0}^b \ell_2^{\vartheta i} \\ &= \frac{\ell_1^{\vartheta b+\vartheta+\omega} - \ell_1^\omega}{\ell_1^\vartheta - 1} + \frac{\ell_2^{\vartheta b+\vartheta+\omega} - \ell_2^\omega}{\ell_2^\vartheta - 1} \\ &= \frac{(\ell_1 \ell_2)^\vartheta (\ell_1^{\vartheta b+\omega} + \ell_2^{\vartheta b+\omega}) - (\ell_1^{\vartheta b+\vartheta+\omega} + \ell_2^{\vartheta b+\vartheta+\omega}) - (\ell_1^\vartheta \ell_2^\omega + \ell_1^\omega \ell_2^\vartheta) + (\ell_1^\omega + \ell_2^\omega)}{(\ell_1 - \ell_2) \{ (\ell_1 \ell_2)^\vartheta - (\ell_1^\vartheta + \ell_2^\vartheta) + 1 \}} \end{aligned}$$

$$= \begin{cases} \frac{(-y)^\vartheta Q_{\vartheta b+\omega}(x, y) - Q_{\vartheta b+\vartheta+\omega}(x, y) - (-y)^\omega Q_{\vartheta-\omega}(x, y) + Q_\omega(x, y)}{(-1)^\vartheta - Q_\vartheta(x, y) + 1}, & \omega < \vartheta \\ \frac{(-y)^\vartheta Q_{\vartheta b+\omega}(x, y) - Q_{\vartheta b+\vartheta+\omega}(x, y) + (-y)^\omega Q_{\vartheta-\omega}(x, y) + Q_\omega(x, y)}{(-1)^\vartheta - Q_\vartheta(x, y) + 1}, & \text{otherwise} \end{cases}$$

□

Thirdly, we establish some identities for bivariate Pell and bivariate Pell-Lucas polynomials.

**Theorem 3.8.** For  $\vartheta, \omega \in \mathbb{Z}$ , we get

$$\sum_{b=0}^{\vartheta+\omega} P_b(x, y)t^{-b} = \frac{1}{t^{\vartheta+\omega}(t^2 - 2xyt - y)} \{t^{\vartheta+\omega+1} - tP_{\vartheta+\omega+1}(x, y) - yP_{\vartheta+\omega}(x, y)\}$$

**Proof.**

By Binet’s formula,

$$\begin{aligned} \sum_{b=0}^{\vartheta+\omega} P_b(x, y)t^{-b} &= \sum_{b=0}^{\vartheta+\omega} \left(\frac{\ell_1^b - \ell_2^b}{\ell_1 - \ell_2}\right)t^{-b} \\ &= \frac{1}{\ell_1 - \ell_2} \sum_{b=0}^{\vartheta+\omega} \left\{ \left(\frac{\ell_1}{t}\right)^b - \left(\frac{\ell_2}{t}\right)^b \right\} \\ &= \frac{1}{\ell_1 - \ell_2} \left\{ \frac{1 - \left(\frac{\ell_1}{t}\right)^{\vartheta+\omega+1}}{1 - \frac{\ell_1}{t}} - \frac{1 - \left(\frac{\ell_2}{t}\right)^{\vartheta+\omega+1}}{1 - \frac{\ell_2}{t}} \right\} \\ &= \frac{1}{(\ell_1 - \ell_2)t^{\vartheta+\omega}} \left( \frac{t^{\vartheta+\omega+1} - \ell_1^{\vartheta+\omega+1}}{t - \ell_1} - \frac{t^{\vartheta+\omega+1} - \ell_2^{\vartheta+\omega+1}}{t - \ell_2} \right) \\ &= \frac{1}{(\ell_1 - \ell_2)t^{\vartheta+\omega}} \left\{ \frac{t^{\vartheta+\omega+1}(\ell_1 - \ell_2) - t(\ell_1^{\vartheta+\omega+1} - \ell_2^{\vartheta+\omega+1}) - y(\ell_1^{\vartheta+\omega} - \ell_2^{\vartheta+\omega})}{(t - \ell_1)(t - \ell_2)} \right\} \\ &= \frac{1}{t^{\vartheta+\omega}(t^2 - 2xyt - y)} \{t^{\vartheta+\omega+1} - tP_{\vartheta+\omega+1}(x, y) - yP_{\vartheta+\omega}(x, y)\} \end{aligned}$$

□

**Theorem 3.9.** For  $\vartheta, \omega \in \mathbb{Z}$ , we get

$$\sum_{b=0}^{\vartheta+\omega} Q_b(x, y)t^{-b} = \frac{2t^2 - xt}{(t^2 - 2xyt - y)} - \frac{1}{t^{\vartheta+\omega}(t^2 - 2xyt - y)} \{tQ_{\vartheta+\omega+1}(x, y) + yQ_{\vartheta+\omega}(x, y)\}$$

**Proof.**

By Binet’s formula,

$$\sum_{b=0}^{\vartheta+\omega} Q_b(x, y)t^{-b} = \sum_{b=0}^{\vartheta+\omega} (\ell_1^b + \ell_2^b)t^{-b}$$

$$\begin{aligned}
 &= \sum_{b=0}^{\vartheta+\omega} \left\{ \left(\frac{\ell_1}{t}\right)^b + \left(\frac{\ell_2}{t}\right)^b \right\} \\
 &= \frac{1 - \left(\frac{\ell_1}{t}\right)^{\vartheta+\omega+1}}{1 - \frac{\ell_1}{t}} + \frac{1 - \left(\frac{\ell_2}{t}\right)^{\vartheta+\omega+1}}{1 - \frac{\ell_2}{t}} \\
 &= \frac{1}{t^{\vartheta+\omega}} \left( \frac{t^{\vartheta+\omega+1} - \ell_1^{\vartheta+\omega+1}}{t - \ell_1} + \frac{t^{\vartheta+\omega+1} - \ell_2^{\vartheta+\omega+1}}{t - \ell_2} \right) \\
 &= \frac{2t^{\vartheta+\omega+2} - t(\ell_1^{\vartheta+\omega+1} + \ell_2^{\vartheta+\omega+1}) - t^{\vartheta+\omega+1}(\ell_1 + \ell_2) + \ell_1\ell_2(\ell_1^{\vartheta+\omega} + \ell_2^{\vartheta+\omega})}{t^{\vartheta+\omega}(t - \ell_1)(t - \ell_2)} \\
 &= \frac{2t^2 - xt}{(t^2 - 2xyt - y)} - \frac{1}{t^{\vartheta+\omega}(t^2 - 2xyt - y)} \{tQ_{\vartheta+\omega+1}(x, y) + yQ_{\vartheta+\omega}(x, y)\}
 \end{aligned}$$

□

Fourthly, we define identities involving common factors of bivariate Pell and Pell-Lucas polynomials.

**Theorem 3.10.** If  $P_b(x, y)$  and  $Q_b(x, y)$  are Bivariate Pell and Pell-Lucas polynomials, then holds for every  $b$  and  $s$ ,

- i.  $P_{2b+s}(x, y)Q_{2b+1}(x, y) = P_{4b+s+1}(x, y) + (-y)^{2b+1}P_{s-1}(x, y)$
- ii.  $P_{2b+s}(x, y)Q_{2b+2}(x, y) = P_{4b+s+2}(x, y) + y^{2b+2}P_{s-2}(x, y)$
- iii.  $P_{2b+s}(x, y)Q_{2b}(x, y) = P_{4b+s}(x, y) + y^{2b}P_s(x, y)$
- iv.  $P_{2b-s}(x, y)Q_{2b+1}(x, y) = P_{4b-s+1}(x, y) + (-y)^{2b+1}P_{s-1}(x, y)$
- v.  $P_{2b-s}(x, y)Q_{2b-1}(x, y) = P_{4b-s-1}(x, y) + (-y)^{2b-1}P_{1-s}(x, y)$
- vi.  $P_{2b-s}(x, y)Q_{2b}(x, y) = P_{4b-s}(x, y) + (-y)^{2b}P_s(x, y)$
- vii.  $P_{2b}(x, y)Q_{2b+s}(x, y) = P_{4b-s}(x, y) - (-y)^{2b}P_s(x, y)$
- viii.  $(x^2y^2 + y)P_{2b}(x, y)Q_{2b+s}(x, y) = Q_{4b+s}(x, y) - (-y)^{2b}Q_s(x, y)$
- ix.  $Q_{2b}(x, y)Q_{2b+s}(x, y) = Q_{4b+s}(x, y) + (-y)^{2b}Q_s(x, y)$

**Proof.**

Using Binet’s formula of Bivariate Pell and Pell-Lucas polynomials and Principle of Mathematical Induction (PMI) on  $b$  and  $s$ , the proof is clear. □

Finally, we present two cross two matrix for bivariate Pell and Pell-Lucas polynomials by  $B = \begin{bmatrix} 2xy & 1 \\ y & 0 \end{bmatrix}$ .

Then, we can write,  $B^n = \begin{bmatrix} P_{n+1}(x, y) & P_n(x, y) \\ yP_n(x, y) & yP_{n-1}(x, y) \end{bmatrix}$  and we get  $\det(B^n) = (-1)^n(y^n)$  (Cassini’s identity).

Many authors introduce and present matrices properties and identities of bivariate polynomials [1,2,4].

**Theorem 3.11.** Let  $b \in \mathbb{N}$ . Then,

$$\begin{bmatrix} P_{b+1}(x, y) \\ yP_b(x, y) \end{bmatrix} = B \begin{bmatrix} P_b(x, y) \\ yP_{b-1}(x, y) \end{bmatrix}$$



**Proof.**

Let  $b \in \mathbb{N}$ . For  $b = 1$ ,

$$\begin{bmatrix} P_2(x, y) \\ yP_1(x, y) \end{bmatrix} = B \begin{bmatrix} P_1(x, y) \\ yP_0(x, y) \end{bmatrix} = B \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

The identity is valid for  $b = 1$ .

For the mathematical induction on  $b$ , suppose that the identity is true for  $b$ . Thus,

$$\begin{aligned} \begin{bmatrix} P_{b+2}(x, y) \\ yP_{b+1}(x, y) \end{bmatrix} &= \begin{bmatrix} 2xyP_{b+1}(x, y) + yP_b(x, y) \\ yP_{b+1}(x, y) \end{bmatrix} \\ &= \begin{bmatrix} 2xy & 1 \\ y & 0 \end{bmatrix} \begin{bmatrix} P_{b+1}(x, y) \\ yP_b(x, y) \end{bmatrix} \\ &= \begin{bmatrix} 2xy & 1 \\ y & 0 \end{bmatrix} \begin{bmatrix} 2xy & 1 \\ y & 0 \end{bmatrix} \begin{bmatrix} P_b(x, y) \\ yP_{b-1}(x, y) \end{bmatrix} \\ &= \begin{bmatrix} 2xy & 1 \\ y & 0 \end{bmatrix} \begin{bmatrix} 2xyP_b(x, y) + yP_{b-1}(x, y) \\ yP_b(x, y) \end{bmatrix} \\ &= \begin{bmatrix} 2xy & 1 \\ y & 0 \end{bmatrix} \begin{bmatrix} P_{n+1}(x, y) \\ yP_n(x, y) \end{bmatrix} \\ &= B \begin{bmatrix} P_{b+1}(x, y) \\ yP_b(x, y) \end{bmatrix} \end{aligned}$$

□

**Theorem 3.12.** Let  $b \in \mathbb{N}$ . Then,

$$\begin{bmatrix} Q_{b+1}(x, y) \\ yQ_b(x, y) \end{bmatrix} = B \begin{bmatrix} Q_b(x, y) \\ yQ_{b-1}(x, y) \end{bmatrix}$$

**Theorem 3.13.** Let  $b \in \mathbb{N}$ . Then,

$$\begin{bmatrix} P_{b+1}(x, y) \\ yP_b(x, y) \end{bmatrix} = B^b \begin{bmatrix} P_1(x, y) \\ yP_0(x, y) \end{bmatrix}$$

**Theorem 3.14.** Let  $b \in \mathbb{N}$ . Then,

$$\begin{bmatrix} Q_{b+1}(x, y) \\ yQ_b(x, y) \end{bmatrix} = B^b \begin{bmatrix} Q_1(x, y) \\ yQ_0(x, y) \end{bmatrix}$$

**4. Conclusion**

In this paper, we present sums of bivariate Pell and Pell-Lucas polynomials. Moreover, we describe sums with negative indices, some connection formulas, and two cross two matrix representation and give several interesting identities involving them.

**Author Contributions**

The author read and approved the final version of the paper.

## Conflict of Interest

The author declares no conflict of interest.

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## Statistical Riesz and Nörlund convergence for sequences of fuzzy numbers

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**Abstract** — Nuray and Savaş proposed statistical convergence of fuzzy number sequences. Afterward, Tripathy and Baruah presented Riesz and Nörlund convergence for sequences of fuzzy numbers. This paper defines statistical Riesz and Nörlund convergence of fuzzy number sequences. It then shows that if a sequence of fuzzy numbers is convergent, then it is statistical Riesz/Nörlund convergent, but the converse is not always true. Finally, this paper discusses the need for further research.

**Keywords:** *Statistical convergence, statistical Riesz convergence, statistical Nörlund convergence, sequences of fuzzy numbers*

**Subject Classification (2020):** 40A35, 46S40

### 1. Introduction

Thus far, many studies, such as de la Vallée-Poussin, Cesàro, Riesz, and Nörlund convergence [1-3], have been conducted on sequences of fuzzy numbers [4,5]. New convergence types for nonconvergent sequences of fuzzy numbers via Cesàro, Riesz, and Nörlund means have been proposed in these studies. Another useful type of convergence introduced for fuzzy number sequences is statistical convergence [6]. Afterward, statistical convergence and statistical Cesàro and  $p$ -Cesàro convergence [7-9] have been investigated. This study defines statistical Riesz and Nörlund convergence for fuzzy number sequences.

Section 2 of the present study provides some basic definitions to be required in the next section. Section 3 defines statistical Riesz and Nörlund convergence of fuzzy number sequences. Moreover, it shows that convergent sequences are statistical Riesz/Nörlund convergent, but the converse is not always correct. Finally, we discuss the need for further research.

### 2. Preliminaries

This section presents some basic notions to be needed for the following section.

**Definition 2.1.** A fuzzy set  $\mu$  over  $\mathbb{R}$  is called a fuzzy number if

- i. there exists an  $x \in \mathbb{R}$  such that  $\mu(x) = 1$
- ii.  $\mu(\lambda x + (1 - \lambda)y) \geq \min\{\mu(x), \mu(y)\}$ , for all  $x, y \in \mathbb{R}$  and for all  $\lambda \in [0,1]$
- iii. for all  $\varepsilon > 0$ , there exists a  $\delta(\varepsilon) > 0$  such that  $|x - a| < \delta \Rightarrow \mu(x) - \mu(a) < \varepsilon$
- iv. the closure of  $\{x \in \mathbb{R} : \mu(x) > 0\}$ , denoted by  $\overline{\text{supp}(\mu)}$ , in the usual topology of  $\mathbb{R}$  is compact

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Throughout this paper, the set of all the fuzzy numbers over  $\mathbb{R}$  is denoted by  $FN(\mathbb{R})$ .

**Definition 2.2.** The  $\alpha$ -level set  $[\mu]_\alpha$  of  $\mu \in FN(\mathbb{R})$  is defined by

$$[\mu]_\alpha := \begin{cases} \{x \in \mathbb{R} : \mu(x) \geq \alpha\}, & 0 < \alpha \leq 1 \\ \text{supp}(\mu), & \alpha = 0 \end{cases}$$

**Proposition 2.3.** Let  $\mu \in FN(\mathbb{R})$ . Then, the set  $[\mu]_\alpha$ , denoted by  $[\mu^-(\alpha), \mu^+(\alpha)]$ , is a closed, bounded, and non-empty interval for all  $\alpha \in [0, 1]$ .

**Proposition 2.4.** The function  $D$  defined by, for all  $\mu, \nu \in FN(\mathbb{R})$ ,

$$D(\mu, \nu) := \sup_{\alpha \in [0, 1]} \max\{|\mu^-(\alpha) - \nu^-(\alpha)|, |\mu^+(\alpha) - \nu^+(\alpha)|\}$$

is a metric on  $FN(\mathbb{R})$ , and  $(FN(\mathbb{R}), D)$  is a complete metric space.

**Proposition 2.5.** Let  $\mu, \nu, \eta, \omega \in FN(\mathbb{R})$  and  $\lambda \in \mathbb{R}$ . Then,

- i.  $D(\lambda\mu, \lambda\nu) = |\lambda|D(\mu, \nu)$
- ii.  $D(\mu + \nu, \eta + \nu) = D(\mu, \eta)$
- iii.  $D(\mu + \nu, \eta + \omega) \leq D(\mu, \eta) + D(\nu, \omega)$

**Definition 2.6.** A sequence  $(u_k)$  of fuzzy numbers is a function  $u$  from  $\mathbb{N}$  to  $FN(\mathbb{R})$ . The fuzzy number  $u_k$  denotes the value of the function at  $k \in \mathbb{N}$  and is called the  $k^{th}$  term of the sequence.

Across this study, the set of all the sequences of fuzzy numbers is denoted by  $w(F)$ .

**Definition 2.7.** A sequence  $(u_k) \in w(F)$  is called convergent to  $u \in FN(\mathbb{R})$  if, for all  $\varepsilon > 0$ , there exists an  $n_0 = n_0(\varepsilon) \in \mathbb{N}$  such that  $D(u_k, u) < \varepsilon$ , for all  $k \geq n_0$ .

Hereinafter, the set of all the convergent sequences of fuzzy numbers is denoted by  $c(F)$ .

**Definition 2.8.** [3] Let  $(u_k) \in w(F)$ ,  $(q_k)$  be a sequence of non-negative real numbers, not all zero and  $q_1 > 0$ , and  $Q_n := q_1 + q_2 + \dots + q_n$ , for all  $n \in \mathbb{N}$ . If  $\lim_n R_n(q, u) = u_0 \in FN(\mathbb{R})$ , then  $(u_k)$  is called Riesz-convergent to fuzzy number  $u_0$  and denoted by  $R\text{-}\lim_k u_k = u_0$  or  $u_k \xrightarrow{R} u_0$  where

$$R_n(q, u) = \frac{1}{Q_n} \sum_{k=1}^n q_k u_k, \quad n \in \mathbb{N}$$

**Definition 2.9.** [3] Let  $(u_k) \in w(F)$ ,  $(q_k)$  be a sequence of non-negative real numbers, not all zero and  $q_1 > 0$ , and  $Q_n := q_1 + q_2 + \dots + q_n$ , for all  $n \in \mathbb{N}$ . If  $\lim_n N_n(q, u) = u_0 \in FN(\mathbb{R})$ , then  $(u_k)$  is called Nörlund-convergent to fuzzy number  $u_0$  and denoted by  $N\text{-}\lim_k u_k = u_0$  or  $u_k \xrightarrow{N} u_0$  where

$$N_n(q, u) = \frac{1}{Q_n} \sum_{k=1}^n q_{n-k+1} u_k, \quad n \in \mathbb{N}$$

From now on, the set of all the Riesz and Nörlund convergent sequences of fuzzy numbers are denoted by  $Rc(F)$  and  $Nc(F)$ , respectively.

**Definition 2.10.** The natural density of a set  $K \subseteq \mathbb{N}$  is defined by  $\delta(K) := \lim_n \frac{1}{n} |\{k \leq n : k \in K\}|$  where  $|\cdot|$  denotes the cardinality of a set.

**Definition 2.11.** [6] A sequence  $(u_k) \in w(F)$  is called statistical convergent (or briefly *st*-convergent) to  $u_0 \in FN(\mathbb{R})$  and denoted by  $st\text{-}\lim_k u_k = u_0$  or  $u_k \xrightarrow{st} u_0$  if

for all  $\varepsilon > 0$  and for all  $k$  except for a set of natural density zero,  $D(u_k, u_0) < \varepsilon$

or

$$\text{for all } \varepsilon > 0, \delta(\{k \leq n : D(u_k, u_0) \geq \varepsilon\}) = 0$$

or

there exists a subsequence  $(u_{n_k})$  such that  $\lim_k \frac{k}{n_k} = 1$  and  $u_{n_k} \rightarrow u_0$

**Proposition 2.12.** Let  $(u_k) \in c(F)$ . Then,  $(u_k) \in sc(F)$ ,  $(u_k) \in Rc(F)$ , and  $(u_k) \in Nc(F)$ .

### 3. Statistical Riesz and Nörlund Convergence for Fuzzy Number Sequences

This section proposes statistical Riesz and Nörlund convergence of sequences of fuzzy numbers and investigates their properties.

**Definition 3.1.** Let  $(u_k) \in w(F)$  and  $(u_{n_k})$  be a Riesz convergent subsequence of  $(u_k)$  to  $u_0 \in FN(\mathbb{R})$  such that  $\lim_k \frac{k}{n_k} = 1$ . Then,  $(u_k)$  is called statistical Riesz convergent (or briefly *stR*-convergent) to  $u_0$  and denoted by  $stR\text{-}\lim_k u_k = u_0$  or  $u_k \xrightarrow{stR} u_0$ . In other words,

$$stR\text{-}\lim_k u_k = u_0 \Leftrightarrow \exists (u_{n_k}) \ni R\text{-}\lim_{n_k} u_{n_k} = u_0 \wedge \lim_k \frac{k}{n_k} = 1$$

Throughout this study, the set of all the *stR*-convergent sequences of fuzzy numbers is denoted by  $stRc(F)$ .

**Definition 3.2.** Let  $(u_k) \in w(F)$  and  $(u_{n_k})$  be a Nörlund convergent subsequence of  $(u_k)$  to  $u_0 \in FN(\mathbb{R})$  such that  $\lim_k \frac{k}{n_k} = 1$ . Then,  $(u_k)$  is called statistical Nörlund convergent (or briefly *stN*-convergent) to  $u_0$  and denoted by  $stN\text{-}\lim_k u_k = u_0$  or  $u_k \xrightarrow{stN} u_0$ . In other words,

$$stN\text{-}\lim_k u_k = u_0 \Leftrightarrow \exists (u_{n_k}) \ni N\text{-}\lim_{n_k} u_{n_k} = u_0 \wedge \lim_k \frac{k}{n_k} = 1$$

Across this study, the set of all the *stN*-convergent sequences of fuzzy numbers is denoted by  $stNc(F)$ .

**Theorem 3.3.** Let  $(u_k) \in stc(F)$ . Then,  $(u_k) \in stRc(F)$ .

**Proof.**

Let  $u_k \xrightarrow{st} u_0$ . Then, there exists a  $(u_{n_k})$  such that  $\lim_k \frac{k}{n_k} = 1$  and  $u_{n_k} \rightarrow u_0$ . From Proposition 2.12,  $u_{n_k} \xrightarrow{R} u_0$ .

□

The converse of Theorem 3.3 is not always correct.

**Example 3.4.** Let  $(w_k) \in w(\mathbb{R})$  defined by

$$w_k(x) = \begin{cases} v_k, & \exists n \in \mathbb{N} \ni k = n^2 \\ u_k, & \forall n \in \mathbb{N}, k \neq n^2 \end{cases}$$

such that

$$u_k(x) = \begin{cases} \frac{k-2+x}{k}, & x \in [2-k, 2] \\ \frac{k+2-x}{k}, & x \in (2, 2+k] \\ 0, & \text{otherwise} \end{cases}$$

and

$$v_k(x) = \begin{cases} x - k, & x \in [k, k + 1] \\ k + 2 - x, & x \in (k + 1, k + 2] \\ 0, & \text{otherwise} \end{cases}$$

Then, the  $\alpha$ -level sets of  $u_k$  and  $v_k$ , for all  $k \in \mathbb{N}$  and for all  $\alpha \in [0,1]$ , are as follows:

$$[u_k]_\alpha = [k\alpha - (k - 2), (k + 2) - k\alpha]$$

and

$$[v_k]_\alpha = [\alpha + k, k + 2 - \alpha]$$

Therefore,  $(w_k)$  is not convergent and also not statistical convergent because

$$\lim_k [u_k]_\alpha = \lim_k [2 - k(1 - \alpha), 2 + k(1 - \alpha)] = \infty$$

Consider a sequence of real numbers  $(q_k) = \left(\frac{k}{2^k}\right)$ . Thus,

$$stR\text{-}\lim_k w_k = R\text{-}\lim_k u_k = \lim_k R_k(q, u)$$

where

$$R_k(q, u) = \begin{cases} \frac{2(2^k - 1)(x + 1) - k(k + x + 2)}{6(2^k - 1) - k(k + 4)}, & x \in \left[ \frac{k(k + 1)}{2^{k+1} - (k + 2)} - 1, 2 \right] \\ \frac{k(-k + x - 6) - 2(2^k - 1)(x - 5)}{6(2^k - 1) - k(k + 4)}, & x \in \left( 2, \frac{k(k + 1)}{(k + 2) - 2^{k+1}} + 5 \right] \\ 0, & \text{otherwise} \end{cases}$$

and its  $\alpha$ -level sets, for all  $\alpha \in [0,1]$ ,

$$[R_k(q, u)]_\alpha = \left[ 3\alpha - 1 - \frac{(\alpha - 1)k(k + 1)}{2^{k+1} - (k + 2)}, 5 - 3\alpha + \frac{(\alpha - 1)k(k + 1)}{2^{k+1} - (k + 2)} \right]$$

because

$$[u_1]_\alpha = [\alpha + 1, 3 - \alpha]$$

$$[u_2]_\alpha = [2\alpha, 4 - 2\alpha]$$

$$[u_3]_\alpha = [3\alpha - 1, 5 - 3\alpha]$$

$$[u_4]_\alpha = [4\alpha - 2, 6 - 4\alpha]$$

$$[u_5]_\alpha = [5\alpha - 3, 7 - 5\alpha]$$

$$[u_6]_\alpha = [6\alpha - 4, 8 - 6\alpha]$$

⋮

$$[u_k]_\alpha = [k\alpha - (k - 2), (k + 2) - k\alpha]$$

and

$$[R_1(q, u)]_\alpha = \frac{q_1 u_1}{q_1} = u_1 = [\alpha + 1, 3 - \alpha]$$

$$[R_2(q, u)]_\alpha = \frac{q_1 u_1 + q_2 u_2}{q_1 + q_2} = \left[ \frac{6\alpha + 2}{4}, \frac{14 - 6\alpha}{4} \right]$$

$$[R_3(q, u)]_\alpha = \frac{q_1 u_1 + q_2 u_2 + q_3 u_3}{q_1 + q_2 + q_3} = \left[ \frac{21\alpha + 1}{11}, \frac{43 - 21\alpha}{11} \right]$$

$$\begin{aligned}
 [R_4(q, u)]_\alpha &= \frac{q_1u_1 + q_2u_2 + q_3u_3 + q_4u_4}{q_1 + q_2 + q_3 + q_4} = \left[ \frac{58\alpha - 6}{26}, \frac{110 - 58\alpha}{26} \right] \\
 [R_5(q, u)]_\alpha &= \frac{q_1u_1 + q_2u_2 + q_3u_3 + q_4u_4 + q_5u_5}{q_1 + q_2 + q_3 + q_4 + q_5} = \left[ \frac{141\alpha - 27}{57}, \frac{255 - 141\alpha}{57} \right] \\
 [R_6(q, u)]_\alpha &= \frac{q_1u_1 + q_2u_2 + q_3u_3 + q_4u_4 + q_5u_5 + q_6u_6}{q_1 + q_2 + q_3 + q_4 + q_5 + q_6} = \left[ \frac{318\alpha - 78}{120}, \frac{558 - 318\alpha}{120} \right] \\
 &\vdots \\
 [R_k(q, u)]_\alpha &= \left[ \frac{(3 \cdot 2^{k+1} - k^2 - 4k - 6)\alpha - (2^{k+1} - k^2 - 2k - 2)}{2^{k+1} - (k + 2)}, \frac{5 \cdot 2^{k+1} - k^2 - 6k - 10 - (3 \cdot 2^{k+1} - k^2 - 4k - 6)\alpha}{2^{k+1} - (k + 2)} \right] \\
 &= \left[ 3\alpha - 1 - \frac{(\alpha - 1)k(k + 1)}{2^{k+1} - (k + 2)}, 5 - 3\alpha + \frac{(\alpha - 1)k(k + 1)}{2^{k+1} - (k + 2)} \right]
 \end{aligned}$$

Thus,

$$\begin{aligned}
 \lim_k [R_k(q, u)]_\alpha &= \lim_k \left[ 3\alpha - 1 - \frac{(\alpha - 1)k(k + 1)}{2^{k+1} - (k + 2)}, 5 - 3\alpha + \frac{(\alpha - 1)k(k + 1)}{2^{k+1} - (k + 2)} \right] \\
 &= [3\alpha - 1, 5 - 3\alpha]
 \end{aligned}$$

Hence,

$$\lim_k R_k(q, u) = \begin{cases} \frac{x + 1}{3}, & x \in [-1, 2] \\ \frac{5 - x}{3}, & x \in (2, 5] \\ 0, & \text{otherwise} \end{cases}$$

Therefore,

$$Rst\text{-}\lim_k w_k = \begin{cases} \frac{x+1}{3}, & x \in [-1, 2] \\ \frac{5-x}{3}, & x \in (2, 5] \\ 0, & \text{otherwise} \end{cases}$$

Consequently, although  $(w_k)$  is not convergent and not statistical convergent,  $(w_k)$  is statistical Riesz convergent.

**Corollary 3.5.** Let  $(u_k) \in c(F)$ . Then,  $(u_k) \in stRc(F)$ .

**Theorem 3.6.** Let  $(u_k) \in sc(F)$ . Then,  $(u_k) \in stNc(F)$ .

The proof is similar to the proof of Theorem 3.3. The converse of Theorem 3.6 is not always correct.

**Example 3.7.** Consider  $(w_k)$  provided in Example 3.4 and  $(q_k) = (2^k)$ . Thus,

$$stN\text{-}\lim_k w_k = N\text{-}\lim_k u_k = \lim_k N_k(q, u)$$

where

$$N_k(q, u) = \begin{cases} \frac{(2^k - 1)x - k}{2^{k+1} - (k + 2)}, & x \in \left[\frac{k}{2^k - 1}, 2\right] \\ -\frac{(2^k - 1)x + k}{2^{k+1} - 2 - k} + 2, & x \in \left(2, 4 - \frac{k}{2^k - 1}\right) \\ 0 & \text{otherwise} \end{cases}$$

and its  $\alpha$ -level sets, for all  $\alpha \in [0, 1]$ ,

$$[N_k(q, u)]_\alpha = \left[2\alpha + \frac{k(1 - \alpha)}{2^k - 1}, 4 - 2\alpha + \frac{k(\alpha - 1)}{2^k - 1}\right]$$

because

$$\begin{aligned} [u_1]_\alpha &= [\alpha + 1, 3 - \alpha] \\ [u_2]_\alpha &= [2\alpha, 4 - 2\alpha] \\ [u_3]_\alpha &= [3\alpha - 1, 5 - 3\alpha] \\ [u_4]_\alpha &= [4\alpha - 2, 6 - 4\alpha] \\ [u_5]_\alpha &= [5\alpha - 3, 7 - 5\alpha] \\ [u_6]_\alpha &= [6\alpha - 4, 8 - 6\alpha] \\ &\vdots \\ [u_k]_\alpha &= [k\alpha - (k - 2), (k + 2) - k\alpha] \end{aligned}$$

and

$$\begin{aligned} [N_1(q, u)]_\alpha &= \frac{q_1 u_1}{q_1} = u_1 = [\alpha + 1, 3 - \alpha] \\ [N_2(q, u)]_\alpha &= \frac{q_2 u_1 + q_1 u_2}{q_1 + q_2} = \left[\frac{4\alpha + 2}{3}, \frac{10 - 4\alpha}{3}\right] \\ [N_3(q, u)]_\alpha &= \frac{q_3 u_1 + q_2 u_2 + q_1 u_3}{q_1 + q_2 + q_3} = \left[\frac{11\alpha + 3}{7}, \frac{25 - 11\alpha}{7}\right] \\ [N_4(q, u)]_\alpha &= \frac{q_4 u_1 + q_3 u_2 + q_2 u_3 + q_1 u_4}{q_1 + q_2 + q_3 + q_4} = \left[\frac{26\alpha + 4}{15}, \frac{56 - 26\alpha}{15}\right] \\ [N_5(q, u)]_\alpha &= \frac{q_5 u_1 + q_4 u_2 + q_3 u_3 + q_2 u_4 + q_1 u_5}{q_1 + q_2 + q_3 + q_4 + q_5} = \left[\frac{57\alpha + 5}{31}, \frac{119 - 57\alpha}{31}\right] \\ [N_6(q, u)]_\alpha &= \frac{q_6 u_1 + q_5 u_2 + q_4 u_3 + q_3 u_4 + q_2 u_5 + q_1 u_6}{q_1 + q_2 + q_3 + q_4 + q_5 + q_6} = \left[\frac{120\alpha + 6}{63}, \frac{246 - 120\alpha}{63}\right] \\ &\vdots \\ [N_k(q, u)]_\alpha &= \left[\frac{(2^{k+1} - 2 - k)\alpha + k}{2^k - 1}, \frac{2^{k+2} - 4 - k - (2^{k+1} - 2 - k)\alpha}{2^k - 1}\right] \\ &= \left[2\alpha + \frac{k(1 - \alpha)}{2^k - 1}, 4 - 2\alpha + \frac{k(\alpha - 1)}{2^k - 1}\right] \end{aligned}$$

Thus,

$$\lim_k [N_k(q, u)]_\alpha = [2\alpha, 4 - 2\alpha]$$



Hence,

$$\lim_k N_k(q, u) = \begin{cases} \frac{x}{2}, & x \in [0, 2] \\ \frac{4-x}{2}, & x \in (2, 4] \\ 0, & \text{otherwise} \end{cases}$$

Therefore,

$$stN\text{-}\lim_k w_k = \begin{cases} \frac{x}{2}, & x \in [0, 2] \\ \frac{4-x}{2}, & x \in (2, 4] \\ 0, & \text{otherwise} \end{cases}$$

Consequently, although  $(w_k)$  is not convergent and not statistical convergent,  $(w_k)$  is statistical Nörlund convergent.

**Corollary 3.8.** Let  $(u_k) \in c(F)$ . Then,  $(u_k) \in stNc(F)$ .

#### 4. Conclusion

This paper proposed statistical Riesz and Nörlund convergence of sequences of fuzzy numbers. It then showed that if a sequence of fuzzy numbers is convergent, then it is statistical Riesz/Nörlund convergent, and the converse is not always correct by two examples. In the future, the Tauberian conditions for a statistical Riesz/Nörlund convergent sequence to be convergent/statistical convergent and Korovkin-type theorems can be studied.

#### Author Contributions

All the authors equally contributed to this work. They all read and approved the final version of the paper.

#### Conflict of Interest

All the authors declare no conflict of interest.

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## Investigation of the potential use of halloysite nanotube doped chitosan films for food packaging

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**Abstract** — Polymer-based food packaging is widely used and causes serious environmental problems due to the chemical ingredients. Therefore, these packages should be replaced by biodegradable alternatives in order to prevent environmental pollution. Many biodegradable polymers are used in food packaging. Among them, chitosan is gaining attention since it is bio-sourced and biodegradable. In this study, the usability of chitosan films as physical and chemical tests investigated food packaging. In order to improve the packaging properties of the films, halloysite nanotube was used as filler with a concentration range of 1-4 wt.%. It was observed that the halloysite significantly increased the opacity, mechanical strength, water resistance, and antioxidant properties of the films.

**Keywords:** *Chitosan films, composite films, food packaging, halloysite nanotube*

**Subject Classification (2020):**

### 1. Introduction

The plastic-based environmental problems are increasing day by day in accordance with plastic consumption depending on the human population. Petrochemical-derived packaging materials, especially those that cannot be recycled after use, are known to remain in the soil and seas for a long time. It is also known that these are broken down into phthalates with sunlight and are harmful to the entire ecosystem. In addition, it has also been proven that chemicals in contact with food undergo plastic transfer to food under light and heat. Therefore, the use of bioplastics for food packaging will have a positive impact on both health and the environment [1-3]. However, it is known that the mechanical strength and water resistance of biopolymers are relatively low compared to the petrochemical-based packaging. For this reason, these deficiencies are tried to be overcome with strong fillers.

Chitin is one of the most abundant biopolymers in the world. It is found in the exoskeletons of insects, arthropods such as crabs, shrimp, and the cell walls of fungi [4]. Chitosan is also biocompatible, completely degradable, soluble in water, and forms a colloidal solution. It can be used in hydrogel or film form [5]. It is seen as a suitable polymer for many fields of study due to its antimicrobial properties, metal binding ability, high mechanical strength, non-toxicity, and biodegradability.

Halloysite nanotube (HNT) is a tubular natural clay with a large surface area. It is used as a nanofiller material in film formation and improves the mechanical properties of the film. Depending on the negatively charged surface of HNT, it enables the slow release of antimicrobial substances in its structure, allowing their effects

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to last for a long time [6] It has been revealed that it has a potential to replace traditional films in recent years due to its long-term durability and food spoilage retarding properties. In the literature, limited studies have performed on use of HNT in chitosan [7]. In studies where it was used other than chitosan, it was observed that it increased many properties of films simultaneously.

Salmos et al. [8] aimed to extend the shelf life of kiwi fruit by obtaining a biodegradable film by dispersing thymol-enriched halloysite nanotube structure in chitosan/polyvinyl alcohol gel. Mechanical properties, transparency, antimicrobial and antioxidant properties were investigated. It was reported that the HNT simultaneously increased both parameters. Risyon et al. [9] aimed to strengthen the low thermal resistance of biopolymers with nanostructure additives by producing polylactic acid/halloysite nanotube (HNT) films. When the mechanical, thermal, and barrier properties were examined, it was concluded that the optimum HNT doping was obtained as 3% by weight. The critical point in composite polymeric films is the homogeneous distribution of the filler through the films. Homogeneous distribution of filler improves the properties throughout the film. For this, it is necessary to determine the appropriate ratio.

In this study, HNT doped chitosan films were prepared, and their usability in food packaging was investigated. The HNT ratio was kept between 1-5% by weight. The effect of HNT doping on film opacity, moisture content, swelling, mechanical strength, and antioxidant properties was investigated.

## 2. Materials and Methods

Medium molecular weight Chitosan powder was purchased from Aldrich Chemicals. The HNT nanoparticles were kindly supplied from Esan Eczacıbaşı, Türkiye. Acetic acid (analytic grade) was purchased from Merck Chemical.

### 2.1. Film Preparation

Films were prepared by solution casting method. The aqueous solution containing 1 wt.% chitosan was stirred at room temperature for 24 hours. The solution contains 2% acetic acid. After the homogeneous mixture was obtained. HNT particles were added with the weight concentration of 1-5% and stirred for three hours. The solution was degassed under vacuum and casted on a polymethyl methacrylate plate. After casting, the films were allowed to dry at room temperature for 2 days and peeled off gently. The films were named according to the concentration of HNT (CS for the pristine chitosan, CS-HNT1, CS-HNT2, CS-HNT3, CS-HNT4 for the filled chitosan films)

### 2.2. Characterization

FTIR analysis of the membranes was performed with The Agilent Cary 630 FTIR spectrometer. This test was performed to determine the structural moisture retention properties of membranes and to examine their chemical bond structures. The test was performed in the wavelength ranges of 650-4000  $\text{cm}^{-1}$ .

The light transmittance of the prepared films is determined by opacity tests. For this test, the opacity of the films cut in certain sizes was examined by measuring the absorbance at 600 nm in UV/Vis spectrophotometer (Shimadzu-1280). The opacity was calculated as shown in (2.1)

$$Opacity = \frac{Absorbance}{Thickness\ of\ films} \quad (2.1)$$

The percentage of moisture trapping of the films in standard media was determined by moisture content tests. The films were dried at 105°C for 24 hours until to constant weight and measured gravimetrically ( $M_i$ ). The

films were kept on a water bath without contact at room temperature and the percentage of weight gain ( $W_g$ ) was calculated as moisture content as shown in (2.2).

$$\text{Moisture content} = \frac{W_g}{W_i} * 100 \quad (2.2)$$

The swelling test is used to determine the water resistance of films. To test the swelling properties of the films, each sample was dried in an oven at 65 °C for 12 hours before the test. The films were soaked in 25 mL deionized water for 12 hours and the values before ( $W_i$ ) and after ( $W_f$ ) water retention were recorded as shown in (2.3).

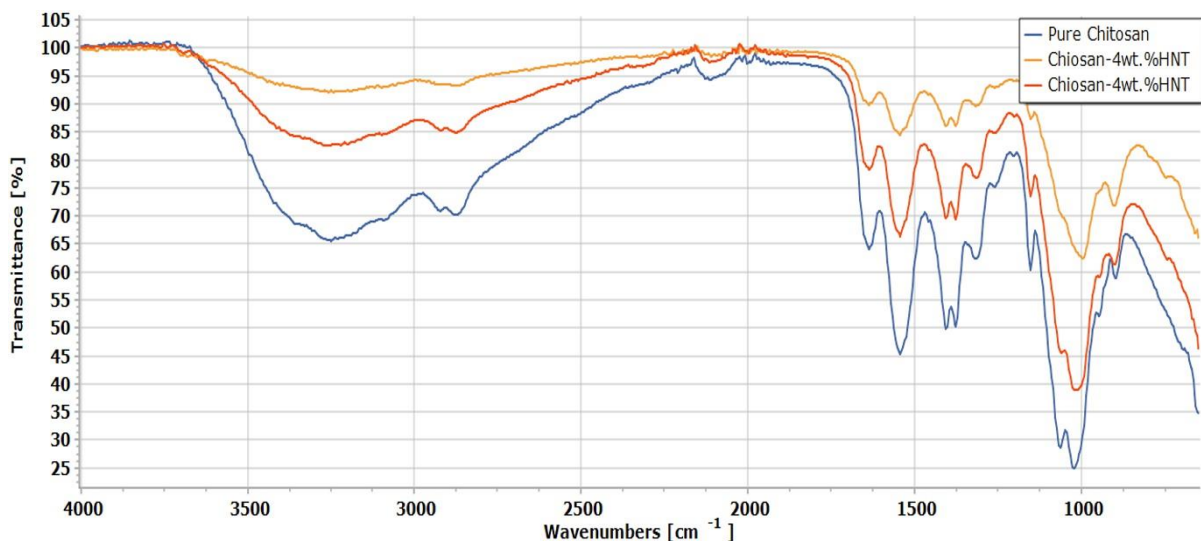
$$\text{Swelling Degree} = \frac{W_f - W_i}{W_i} * 100 \quad (2.3)$$

The antioxidant properties of the added additives were determined by antioxidant activity test. According to this test, films weighing 0.1 gram were placed in 70% methanol and 2,2-diphenyl-1-picrylhydrazyl (DPPH) stable radical (10 ml 70% methanol, 0.2 mg DPPH) and kept in the dark for 90 minutes. When this radical reacts with the antioxidant, a change from violet to yellow is observed and the antioxidant activity is calculated by measuring the absorbance at 520 nm with UV-Vis Spectrophotometer [10].

The mechanical analysis of the films was analyzed in Ankarin brand mechanical analyzer according to ASTM D882 standard. The mechanical strengths were performed by measuring the mechanical strength (stress) and elongation (strain) from the force and elongation at break of the strips cut in 4\*1 cm size. Experiments were performed at a tensile speed of 3 mm/min.

### 3. Results and Discussion

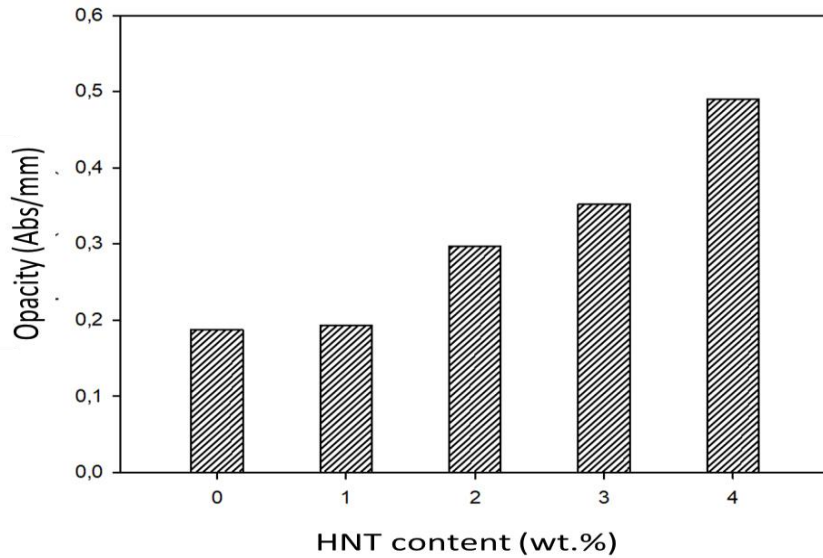
The FTIR spectrum of the films are shown in Figure 1. A prominent band within the range of 3000–3620  $\text{cm}^{-1}$  is indicative of N–H and O–H stretching. It is clear that the intensity of the peak decreasing by increasing HNT depending on the reducing moisture content.



**Figure 1.** FTIR spectra of the pure and HNT loaded films

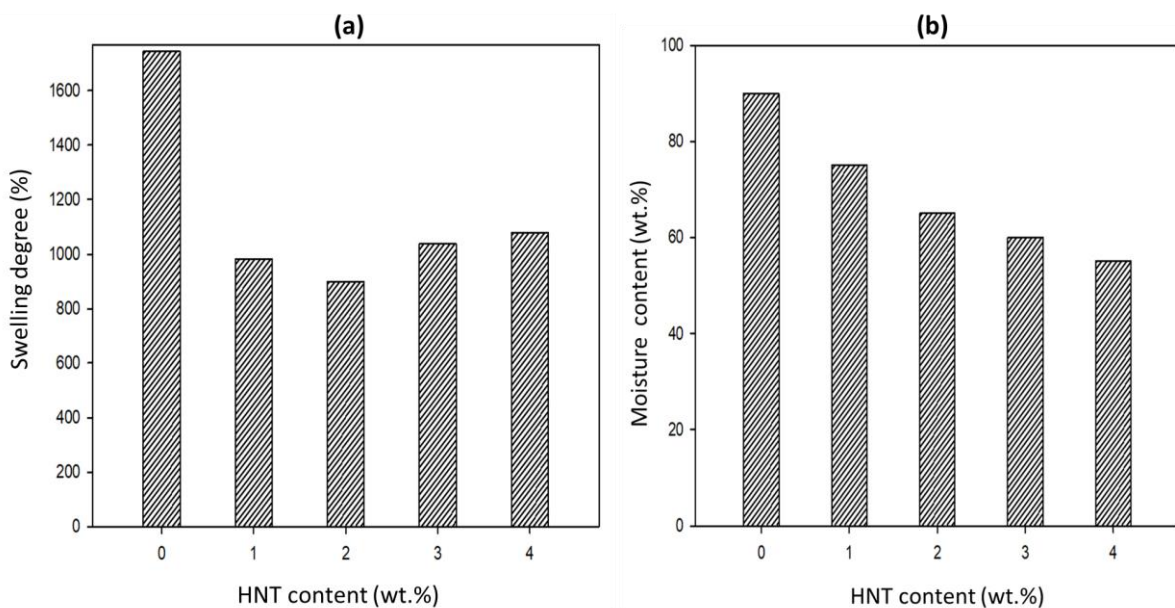
C-H symmetric and asymmetric stretching are responsible for the absorption bands at approximately 2920 and 2876  $\text{cm}^{-1}$ , respectively. These bands are typical polysaccharide properties and are present in the spectra of various polysaccharides. The bands at about 1638  $\text{cm}^{-1}$  (C=O stretching) and 1318  $\text{cm}^{-1}$  (C-N stretching) respectively confirmed the presence of residual N-acetyl groups [11].

The light transmittance of the packaging films produced is a very important parameter [12]. While light can be degrading for some foods, an optimal degree of opacity is desired as a high degree of opacity reduces the visibility of the food [13,14]. Especially considering the freshness of the food, it is desired that it refracts and does not transmit too much light. Figure 2 shows the opacity of the films. Accordingly, all additive ratios increased the opacity values compared to pure chitosan film.



**Figure 2.** Opacity results of films with and without HNT loading

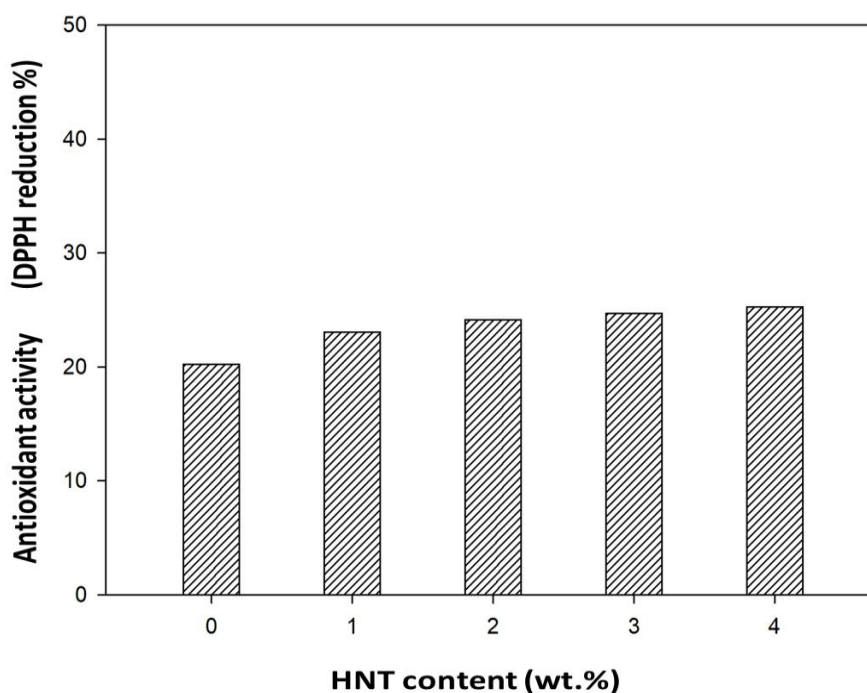
Figure 3a shows the results of the swelling tests of the additives in pure water for 30 minutes. Swelling tests are normally performed for very long hours, but in this study chitosan was not crosslinked. This is because the cross-linking process prevents understanding the antimicrobial activity or determining the actual character of the films. Therefore, the swelling tests were short because pure chitosan dissolves in water and disintegrates after 20-30 minutes. As can be seen in the figure, when the HNT content in the membrane increased from zero to 2 percentage, its resistance to water was significantly increased. However, there is a small increase of 3 percent and 4 percent. This shows that when the films are loaded with excess HNT, the HNT structure also interacts with water and fills its pores.



**Figure 3.** Swelling degree (a) and Moisture content (b) results of films with and without HNT loading

Similar to the swelling test, the moisture retention (content) test is a measure of the resistance of films to water vapor. Unlike swelling, in this test the films interact only with the vapor at room temperature. Moisture retention value is actually expected similar results to swelling. However, since there is no direct contact with water, the structure of the HNT particles is not expected to be filled with water. Therefore, as seen in Figure 3b, the vapor contents gradually decreased with the addition of HNT. While the pure film retains a lot of vapor, this value decreased significantly in HNT doped films. This shows that the resistance of the films to moisture retention increases under room conditions, and therefore the degree of degradation decreases.

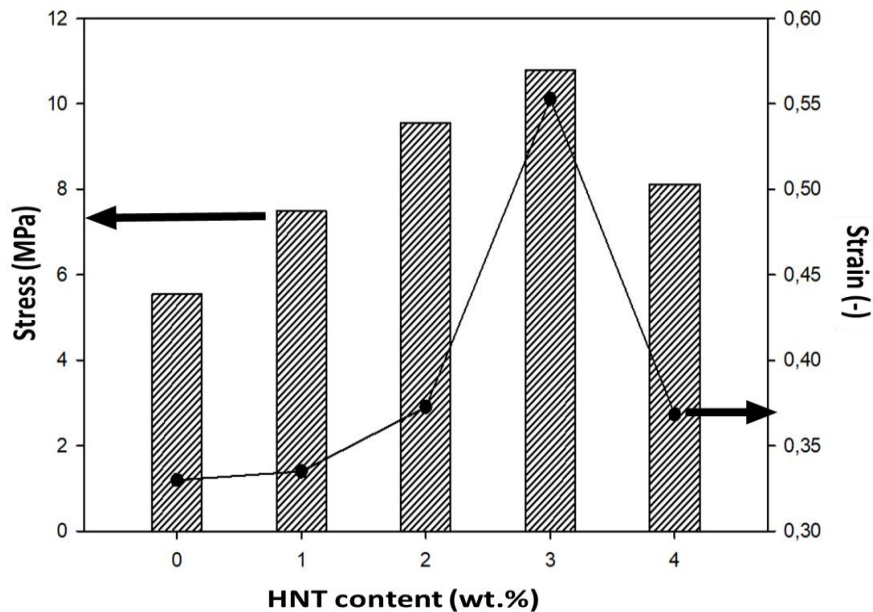
Oxidative reactions change the basic properties of foods and cause them to deteriorate. Antioxidants are microcomponents that can scavenge free radicals by terminating oxidative chain reactions. Therefore, antioxidant activity is an important feature for food packaging [15-17]. In this study, DPPH free radical scavenging method is used to evaluate the antioxidant capacity of the chitosan films. Figure 4 shows the antioxidant values of the films depending on the DPPH reagent. This value is also an indicator of the resistance of the films against oxidation and is expected to be as high as possible. As seen in the figure, while the antioxidant value of the film was 20% in the pure film, this value increased to over 24% in the 4% added film. that is, more than 20% antioxidant properties were improved with 4% additive.



**Figure 4.** Antioxidant results of films with and without HNT loading

Figure 5 shows the mechanical analysis results of the additive ratios. Mechanical analysis is evaluated in two ways. The first is the stress, which is an indicator of the force applied at break, and the other is the strain value calculated based on the amount of elongation at break. The strength of the films is described by the stress value. Strain gives more information about elasticity. As seen in the figure, the stress value of pure chitosan is around 5.7 MPa. As seen in Figure 5, this value increased to 10.8 MPa with the addition of HNT. However, it decreased after this value. The reason for this is that the additive material added to the polymeric matrix increases the mechanical strength, contributes to load

transfer in homogeneous distribution, but due to agglomeration caused by overloading, the load cannot be distributed properly and weak points are formed and cause rupture [18,19].



**Figure 5.** Stress-strain results of films with and without HNT loading

#### 4. Conclusion

The environmental impact of reducing the use of plastic and replacing it with biodegradable packaging is increasing day by day. In this way, carcinogenic compounds resulting from plastic degradation are not formed, and naturally occurring films reduce the carbon footprint in nature. In this study, chitosan-based films were prepared for use in food packaging. In order to improve the mechanical properties, swelling and moisture retention properties, opacity, antioxidant and antimicrobial properties of the films, HNT additives were added between 1-4%. As a result of the study,

- i.* The HNT additives increased the opacity values depending on the increasing ratios and since this is an indicator that reduces the light transmittance of the films, it has an inhibitory effect on food degradation.
- ii.* The increasing ratio of HNT decreased the swelling and solubility of the films in water.
- iii.* Increasing ratios of HNT in films significantly decreased moisture retention. This is a factor preventing the degradation of the films and thus the food when exposed to moisture and steam.
- iv.* Increasing HNT content in films increased the mechanical strength and generally above 3% the mechanical strength decreased due to agglomeration.
- v.* Increasing HNT content improved the antioxidant properties.

In the next stage of the study, the degradation processes of the produced films in soil and atmospheric environments will be examined, and accordingly, their sustainability will be examined according to biodegradability criteria.

#### Author Contributions

All the authors equally contributed to this work. They all read and approved the final version of the paper.



## Conflict of Interest

All the authors declare no conflict of interest.

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